EUROPEAN JOURNAL OF PURE AND APPLIED MATHEMATICS
Vol. 14, No. 1, 2021, 278-300
ISSN 1307-5543 - ejpam.com
Published by New York Business Global


# Properties of nilpotent evolution algebras with no maximal nilindex 

Ahmad Alarafeen ${ }^{1}$, Izzat Qaralleh ${ }^{2, *}$, Azhana Ahmad ${ }^{1}$<br>${ }^{1}$ School of Mathematical Sciences, Universiti Sains Malaysia 11800 USM, Penang, Malaysia<br>${ }^{2}$ Department of Mathematics, Faculty of Science, Tafila Technical University, Tafila, Jordan


#### Abstract

As a system of abstract algebra, evolution algebras are commutative and non-associative algebras. There is no deep structure theorem for general non-associative algebras. However, there are deep structure theorem and classification theorem for evolution algebras because it has been introduced concepts of dynamical systems to evolution algebras. Recently, in [25], it has been studied some properties of nilpotent evolution algebra with maximal index $\left(\operatorname{dim} \mathbf{E}^{2}=\operatorname{dim} \mathbf{E}-1\right)$. This paper is devoted to studying nilpotent finite-dimensional evolution algebras $\mathbf{E}$ with $\operatorname{dim} \mathbf{E}^{2}=$ $\operatorname{dim} \mathbf{E}-2$. We describe Lie algebras related to the evolution of algebras. Moreover, this result allowed us to characterize all local and 2 -local derivations of the considered evolution algebras. All automorphisms and local automorphisms of the nilpotent evolution algebras are found.


2020 Mathematics Subject Classifications: 6S10, 82B26, 12J12, 39A70, 47H10, 60K35
Key Words and Phrases: Evolution algebra, derivation, local derivation, automorphism, local automorphism

## 1. Introduction

The departure point of a new type of evolution algebra has been introduced by [34]. This algebra is motivated by some evolution laws of genetics. The study of evolution algebras serves as a foundation of a new research area in algebra and the theory of dynamic systems. Many related open problems have to be addressed to develop research in this area (for further details, we refer to [33]).

We note that evolution algebras are not defined by identities, and therefore they do not form a type of non-associative algebras, such as Lie, Jordan, or alternative algebras. Thus, to investigate such algebras, a different approach has to be used (see [7, 9, 12]).

In [12], the relationships among nil, right nilpotent evolution algebras, which are defined by an upper triangular matrix of structural constants, have been found. A further

[^0](C) 2021 EJPAM All rights reserved.
problem which has been addressed in $[10,15,18,19,27]$ is the classification of lowdimensional evolution algebras. Nevertheless, a full classification of nilpotent evolution algebras is a tricky task. [20] have investigated certain properties of nilpotent evolution algebras with maximal nilindex. In the current study, we analyze some propensities of nilpotent evolution algebras whose index of nilpotency is $2^{n-2}+1$.

The derivation of non-associative algebra forms the Lie algebra, which is considered as one of the important tools for studying its structure. Extensive work has been conducted on the subject of derivations of genetic algebras ( [13], [17], [20], [28],,[16],[1]). since the multiplication is trivial then set of all until is invertible In fact, [7, 14] have investigated several properties of derivations of $n$-dimensional complex evolution algebras,depending on the rank of the appropriate matrices. Recently, many paper have been devoted to study the derivation of evolution algebras see for instance [2, 26, 30, 31]. Other properties of evolution algebra have been investigated in $[5,6,8,9,11,23,29]$. In [25], it has been study the properties of the nilpotent finite-dimensional evolution algebras with maximal nil index such as derivation, local derivation, automorphism, and local automorphism.

In the present study, we explicitly describe the space of derivations of evolution algebras with nilindex $2^{(n-2)}+1$, which allows us to study further properties of the evolution algebras.Moreover, we describe all local and 2-local derivations of the considered algebra.We stress that the notions of local automorphism and local derivation were introduced and investigated independently by Kadison [22] and Larson and Sourour [24]. Subsequently, P. Šemrl [32] introduced the concepts of 2-local automorphisms and 2-local derivations. The preceding studies have led to a series of works devoted to description of mappings which are close to automorphisms and derivations of $C^{*}$-algebras and operator algebras. For details and the survey, we refer to the work of $[3,4]$.

The paper is organized as follows. Section 2 provides preliminary information about evolution algebras. Derivations of non-associative algebras form the Lie algebra; thus, so, in section 3 we describe the Lie algebra associated with evolution algebras whose nilindex is $2^{(n-2)}+1$. Furthermore, based on results in section 3, section 4 describes local and 2 -local derivations of the considered evolution algebras. In section 5, we find all automorphisms and local automorphisms of the nilpotent evolution algebras with nilindex $2^{(n-2)}+1$.

## 2. Evolution algebras

Recall the definition of evolution algebras. Let $\mathbf{E}$ be a vector space over a field $\mathbb{K}$. In the follows, we always assume that $\mathbb{K}$ has characteristic zero. The vector space $\mathbf{E}$ is called evolution algebra w.r.t. natural basis $\left\{\mathbf{e}_{1}, \mathbf{e}_{2}, \ldots\right\}$ if a multiplication rule $\cdot$ on $\mathbf{E}$ satisfies

$$
\begin{gathered}
\mathbf{e}_{i} \cdot \mathbf{e}_{j}=\mathbf{0}, i \neq j, \\
\mathbf{e}_{i} \cdot \mathbf{e}_{i}=\sum_{k} a_{i k} \mathbf{e}_{k}, i \geq 1 .
\end{gathered}
$$

From the preceding definition, it follows that evolution algebras are commutative (therefore, flexible).

We denote by $A=\left(a_{i j}\right)_{i, j=1}^{n}$ the matrix of the structural constants of the finitedimensional evolution algebra E. Obviously, $\operatorname{rank} A=\operatorname{dim}(\mathbf{E} \cdot \mathbf{E})$. Thus, for finitedimensional evolution algebra, the rank of the matrix does not depend on choice of natural basis. In the following, for convenience, we write $\mathbf{u v}$ instead $\mathbf{u} \cdot \mathbf{v}$ for any $\mathbf{u}, \mathbf{v} \in \mathbf{E}$ and we write $\mathbf{E}^{2}$ instead of $\mathbf{E} \cdot \mathbf{E}$.

A linear map $\psi: \mathbf{E}_{1} \rightarrow \mathbf{E}_{2}$ is called a homomorphism of evolution algebras if $\psi(\mathbf{u v})=$ $\psi(\mathbf{u}) \psi(\mathbf{v})$ for any $\mathbf{u}, \mathbf{v} \in \mathbf{E}_{1}$. Moreover, if $\psi$ is bijective, then it is called an isomorphism. In this case, the last relation is denoted by $\mathbf{E}_{1} \cong \mathbf{E}_{2}$.

For an evolution algebra $\mathbf{E}$, we introduce the following sequence, $k \geq 1$

$$
\begin{equation*}
\mathbf{E}^{k}=\sum_{i=1}^{k-1} \mathbf{E}^{i} \mathbf{E}^{k-i} \tag{1}
\end{equation*}
$$

As $\mathbf{E}$ is commutative algebra, we obtain

$$
\mathbf{E}^{k}=\sum_{i=1}^{\lfloor k / 2\rfloor} \mathbf{E}^{i} \mathbf{E}^{k-i}
$$

where $\lfloor x\rfloor$ denotes the integer part of $x$.
Definition 1. An evolution algebra $\mathbf{E}$ is called nilpotent if some $m \in \mathbb{N}$ such that $\mathbf{E}^{m}=\mathbf{0}$. The smallest $m$ such that $\mathbf{E}^{m}=\mathbf{0}$ is called the index of nilpotency.

Theorem 1. [12] An n-dimensional evolution algebra $\mathbf{E}$ is nilpotent iff it admits a natural basis such that the matrix of the structural constants corresponding to $\mathbf{E}$ on this basis is represented in the form

$$
\tilde{A}=\left(\begin{array}{lllll}
0 & \tilde{a}_{12} & \tilde{a}_{13} & \vdots & \tilde{a}_{1 n} \\
0 & 0 & \tilde{a}_{23} & \vdots & \tilde{a}_{2 n} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
0 & 0 & 0 & \vdots & \tilde{a}_{n-1, n} \\
0 & 0 & 0 & \vdots & 0
\end{array}\right)
$$

Due to Theorem 1, any nilpotent evolution algebra $\mathbf{E}$ with $\operatorname{dim}\left(\mathbf{E}^{2}\right)=n-2$ has the following form:

$$
\mathbf{e}_{i}^{2}= \begin{cases}\sum_{j=i+1}^{n} a_{i j} \mathbf{e}_{j}, & i \leq n-2  \tag{2}\\ \mathbf{0}, & i \in\{n-1, n\}\end{cases}
$$

where $a_{i j} \in \mathbb{K}$ and $a_{i, i+1} \neq 0$ for any $i<n-1$.
Theorem 2. [11] Let $\mathbf{E}$ be a nilpotent evolution algebra. Then, $\mathbf{E}$ has maximal index of nilpotency $2^{(n-2)}+1$ if and only if the multiplication table of $\mathbf{E}$ is given by (2).

In the following, we will work with nilpotent evolution algebras with $2^{(n-2)}+1$ index of nilpotency. Due to the last theorem, we only consider evolution algebras with the multiplication table given by (2).

Lemma 1. Let $\mathbf{E}_{1}, \mathbf{E}_{2}$ be two isomorphic evolution algebras. Then, $\operatorname{Der}\left(\mathbf{E}_{1}\right) \cong \operatorname{Der}\left(\mathbf{E}_{2}\right)$.
Lemma 2. Let $\mathbf{E}$ and $\mathbf{E}^{\prime}$ be evolution algebras with basis $\left\{\mathbf{e}_{i}\right\}_{i=1}^{n}$ and $\left\{\mathbf{f}_{i}\right\}_{i=1}^{n}$ respectively, defined by
$\mathbf{e}_{i}^{2}=\left\{\begin{array}{ll}a_{i, i+1} \mathbf{e}_{i+1}+a_{i n-1} \mathbf{e}_{n-1}+a_{i n} \mathbf{e}_{n}, & i<n-1 ; \\ \mathbf{0}, & i \in\{n-1, n\} .\end{array} \quad \mathbf{f}_{i}^{2}= \begin{cases}\mathbf{f}_{i+1}, & i<n-1 ; \\ \mathbf{0}, & i \in\{n-1, n\} .\end{cases}\right.$
If $a_{i, i+1} \neq 0$ for every $i<n-1$, then $\mathbf{E} \cong \mathbf{E}^{\prime}$.
Proof. Let $a_{i, i+1} \neq 0$ for every $i<n-1$. If $n=3$ after changing the basis $\mathbf{e}_{1}, \mathbf{e}_{2}, \mathbf{e}_{3}$ to $\mathbf{f}_{1}=\mathbf{e}_{1}, \mathbf{f}_{2}=\mathbf{e}_{1}^{2}$, and $\mathbf{f}_{3}=\mathbf{e}_{3}$, we immediately get $\mathbf{E}^{\prime}$.

So. let us suppose $n \geq 4$. Then, the linear mapping $\varphi: \mathbf{E} \rightarrow \mathbf{E}^{\prime}$ defined by

$$
\varphi:\left\{\begin{array}{l}
\mathbf{f}_{1}=\mathbf{e}_{1}  \tag{3}\\
\mathbf{f}_{2}=\mathbf{e}_{1}^{2} \\
\mathbf{f}_{i+1}=\prod_{k=1}^{i-1} a_{k, k+1}^{2 i-k} \mathbf{e}_{i}^{2}, \quad 2 \leq i<n-1 \\
\mathbf{f}_{n}=\mathbf{e}_{n}
\end{array}\right.
$$

is an isomorphism from $\mathbf{E}$ to $\mathbf{E}^{\prime}$.

## 3. Derivations

In this section, we consider derivations of nilpotent evolution algebras with $2^{n-2}+1$ index of nilpotency.

Recall that derivation of an evolution algebra $\mathbf{E}$ is a linear mapping $d: \mathbf{E} \rightarrow \mathbf{E}$ such that $d(\mathbf{u v})=d(\mathbf{u}) \mathbf{v}+\mathbf{u} d(\mathbf{v})$ for all $\mathbf{u}, \mathbf{v} \in \mathbf{E}$.

We note that for any algebra, the space $\operatorname{Der}(\mathbf{E})$ of all derivations is a Lie algebra w.r.t. the commutator multiplication:

$$
\left[d_{1}, d_{2}\right]=d_{1} d_{2}-d_{2} d_{1}, \quad \forall d_{1}, d_{2} \in \operatorname{Der}(\mathbf{E}) .
$$

For a given structural matrix $A=\left(a_{i j}\right)_{i, j \geq 1}^{n}$ of nilpotent evolution algebra $\mathbf{E}$ with $\operatorname{dim}\left(\mathbf{E}^{2}\right)=$ $n-2$, we denote

$$
\begin{equation*}
I_{A}=\left\{(i, j): i+1<j<n-1, a_{i j} \neq 0\right\} . \tag{4}
\end{equation*}
$$

Theorem 3. Let $\mathbf{E}$ be an evolution algebra with structural matrix $A=\left(a_{i j}\right)_{i, j \geq 1}^{n}$ in a natural basis $\left\{\mathbf{e}_{i}\right\}_{i=1}^{n}$. If $\mathbf{E}$ is a nilpotent with rank $A=n-2$, then the following statements hold
(i) if $I_{A} \neq \emptyset$, then

$$
\operatorname{Der}(\mathbf{E})=\left\{\left(\begin{array}{ccccc}
0 & 0 & \ldots & d_{1 n-1} & d_{1 n} \\
0 & 0 & \ldots & d_{2 n-1} & d_{2 n} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & d_{n-1 n-1} & d_{n-1 n} \\
0 & 0 & \ldots & d_{n n-1} & d_{n n}
\end{array}\right)\right\}
$$

where

$$
\begin{aligned}
d_{n-1, n-1} & =-a_{n-2, n} d_{n, n-1} ; \\
d_{n-1, n} & =-a_{n-2, n} d_{n n} ; \\
d_{i m} & =-\sum_{k=1}^{n-i} a_{i-1, k+i} d_{k+i, m}, m \in\{n-1, n\}
\end{aligned}
$$

(ii) if $I_{A}=\emptyset$, then

$$
\operatorname{Der}(\mathbf{E})=\left\{\left(\begin{array}{lllll}
\alpha & 0 & \ldots & \beta & \gamma \\
0 & 2 \alpha & \ldots & d_{2, n-1} & d_{2 n} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & d_{n-2, n-1} & d_{n-2, n} \\
0 & 0 & \ldots & d_{n-1, n-1} & d_{n-1, n} \\
0 & 0 & \ldots & s & t
\end{array}\right): \alpha, \beta, \gamma, s, t \in \mathbb{K}\right\}
$$

where

$$
\begin{aligned}
d_{n-1, n-1} & =2^{n-2} \alpha-a_{n-2, n} s \\
d_{n-1, n} & =\left(2^{n-2}-t\right) a_{n-2, n} \\
d_{i, n-1} & =\left(2^{i-1}-2^{n-2}\right) \alpha a_{i-1, n-1}+\left(a_{i-1, n-1} a_{n-2, n}-a_{i-1, n}\right) s \\
d_{i, n} & =a_{i-1, n-1} d_{n-1, n}+a_{n-2, n}\left(2^{i-1} \alpha-t\right), \quad 2 \leq i<n-1 .
\end{aligned}
$$

Proof. The $(i)$ and (ii) are easy to check for $n=3,4$. Thus, we consider only the case $n>4$. Let $d$ be a derivation. We represent $d$ in a matrix form based on $\left\{\mathbf{e}_{i}\right\}_{i=1}^{n}$ as follows: $d\left(\mathbf{e}_{i}\right)=\sum_{j=1}^{n} d_{i j} \mathbf{e}_{j}$. Then, we have $d_{j i} \mathbf{e}_{i}^{2}+d_{i j} \mathbf{e}_{j}^{2}=\mathbf{0}$ for all $1 \leq i<j \leq n$. As $\mathbf{e}_{i}^{2}$ and $\mathbf{e}_{j}^{2}$ are linearly independent, then $d_{i j}=d_{j i}=0$ for any $1 \leq i<j<n-1$. If we take $m \in\{n-1, n\}$, then considering that $\mathbf{e}_{n-1}^{2}=\mathbf{e}_{n}^{2}=\mathbf{0}$ from $d_{m i} \mathbf{e}_{i}^{2}+d_{i m} \mathbf{e}_{m}^{2}=\mathbf{0}$ one has $d_{m i}=0$ for any $i<m$.

Thus, we have shown the following:

$$
\begin{equation*}
d_{i j}=0, \quad \text { if } i \neq j, i \leq n, j<n-1 \tag{5}
\end{equation*}
$$

On the other hand, we have $d\left(\mathbf{e}_{i}^{2}\right)=2 d_{i i} \mathbf{e}_{i}^{2}$ for any $i \leq n$. Then, for $i=n-2$ using (2), we obtain $d\left(\mathbf{e}_{n-1}+a_{n-2, n} \mathbf{e}_{n}\right)=2 d_{n-2, n-2} \mathbf{e}_{n-2}^{2}$. Then, we have the following system:

$$
\begin{array}{r}
d_{n-1, n-1}+a_{n-2, n} d_{n, n-1}=2 d_{n-2, n-2} \\
d_{n-1, n}+a_{n-2, n} d_{n, n}=2 a_{n-2, n} d_{n-2, n-2} . \tag{6}
\end{array}
$$

Furthermore, we assume that $i<n-2$. Then, one finds

$$
\begin{align*}
d\left(\mathbf{e}_{i}^{2}\right) & =d\left(\sum_{j=i+1}^{n} a_{i j} \mathbf{e}_{j}\right)=\sum_{j=i+1}^{n} a_{i j} d\left(\mathbf{e}_{j}\right) \\
& =\sum_{j=i+1}^{n-2} a_{i j} d_{j j} \mathbf{e}_{j}+\sum_{j=i+1}^{n} a_{i j} d_{j, n-1} \mathbf{e}_{n-1}+\sum_{j=i+1}^{n} a_{i j} d_{j n} \mathbf{e}_{n} . \tag{7}
\end{align*}
$$

On the other hand, from

$$
d\left(\mathbf{e}_{i}^{2}\right)=2 d_{i i} \mathbf{e}_{i}^{2}=2 d_{i i} \sum_{j=i+1}^{n} a_{i j} \mathbf{e}_{j}
$$

with (7), one finds

$$
\begin{align*}
& 2 d_{i i}=d_{i+1, i+1}, \quad 1 \leq i<n-2  \tag{8}\\
& a_{i j} d_{j j}=2 a_{i j} d_{i i}, \quad i+2 \leq j \leq n-2  \tag{9}\\
& \sum_{j=i+1}^{n} a_{i j} d_{j, n-1}=2 d_{i i} a_{i, n-1}, \quad 1 \leq i<n-2  \tag{10}\\
& \sum_{j=i+1}^{n} a_{i j} d_{j n}=2 d_{i i} a_{i n}, \quad 1 \leq i<n-2 . \tag{11}
\end{align*}
$$

From (8), (9), we can easily derive

$$
\begin{align*}
& d_{j j}=2^{j-1} d_{11}, \quad 2 \leq j \leq n-2  \tag{12}\\
& \quad a_{i j} d_{11}=0, \quad i+2 \leq j \leq n-1 \tag{13}
\end{align*}
$$

Now, we consider (10), (11).

$$
\begin{align*}
d_{i+1, n-1} & =2 a_{i, n-1} d_{i i}-\sum_{k=1}^{n-i} a_{i-1, k+i} d_{k+i, n-1} \\
d_{i+1, n} & =2 a_{i, n} d_{i i}-\sum_{k=1}^{n-i} a_{i-1, k+i} d_{k+i, n} . \tag{14}
\end{align*}
$$

Thus, from (5),(6),(12),(13) and (14), we conclude that $d$ is a derivation of evolution algebra given by (2) if and only if

$$
\begin{align*}
& d_{i j}=d_{n-1, i}=d_{n i}=0, \quad 1 \leq i \neq j \leq n-2  \tag{15}\\
& d_{j j}=2^{j-1} d_{11}, \quad 2 \leq j \leq n-2  \tag{16}\\
& a_{i j} d_{11}=0, \quad i+2 \leq j \leq n-2  \tag{17}\\
& d_{i+1, n-1}=2 a_{i, n-1} d_{i i}-\sum_{k=1}^{n-i} a_{i-1, k+i} d_{k+i, n-1}  \tag{18}\\
& d_{i+1, n}=2 a_{i, n} d_{i i}-\sum_{k=1}^{n-i} a_{i-1, k+i} d_{k+i, n} \tag{19}
\end{align*}
$$

Case $I_{A} \neq \emptyset$. In this case, we have $a_{i_{0} j_{0}} \neq 0$ for a pair $\left(i_{0}, j_{0}\right)$ that satisfies $i_{0}+2 \leq$ $j_{0}<n-1$. Then, from (17), one finds $d_{11}=0$. Plugging this fact into (16),(18), and (19), we obtain

$$
\operatorname{Der}(\mathbf{E})=\left\{\left(\begin{array}{lllll}
0 & 0 & \ldots & d_{1 n-1} & d_{1 n} \\
0 & 0 & \ldots & d_{2 n-1} & d_{2 n} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & d_{n-1 n-1} & d_{n-1 n} \\
0 & 0 & \ldots & d_{n n-1} & d_{n n}
\end{array}\right)\right\}
$$

where

$$
\begin{aligned}
d_{n-1, n-1} & =-a_{n-2, n} d_{n, n-1} \\
d_{n-1, n} & =-a_{n-2, n} d_{n n} \\
d_{i m} & =-\sum_{k=1}^{n-i} a_{i-1, k+i} d_{k+i, m}, m \in\{n-1, n\}
\end{aligned}
$$

Case $I_{A}=\emptyset$. In this case, (17) is true for any $d_{11} \in \mathbb{K}$. Thus, from (15),(16), (18), and (19), we conclude that

$$
\operatorname{Der}(\mathbf{E})=\left\{\left(\begin{array}{lllll}
\alpha & 0 & \ldots & \beta & \gamma \\
0 & 2 \alpha & \ldots & d_{2, n-1} & d_{2 n} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & d_{n-2, n-1} & d_{n-2, n} \\
0 & 0 & \ldots & d_{n-1, n-1} & d_{n-1, n} \\
0 & 0 & \ldots & s & t
\end{array}\right): \alpha, \beta, s, t \in \mathbb{K}\right\}
$$

where

$$
d_{n-1, n-1}=2^{n-2} \alpha-a_{n-2, n} s
$$

$$
\begin{aligned}
d_{n-1, n} & =\left(2^{n-2}-t\right) a_{n-2, n} \\
d_{i, n-1} & =\left(2^{i-1}-2^{n-2}\right) \alpha a_{i-1, n-1}+\left(a_{i-1, n-1} a_{n-2, n}-a_{i-1, n}\right) s \\
d_{i, n} & =a_{i-1, n-1} d_{n-1, n}+a_{n-2, n}\left(2^{i-1} \alpha-t\right), \quad 2 \leq i<n-1 .
\end{aligned}
$$

The proof is complete.
Remark 1. i. In [25], It has been considered the nilpotent evolution algebras with maximal nil index and they found $1 \leq \operatorname{dim} \operatorname{Der}(\mathbf{E}) \leq 2$.
ii. From the proved theorem, we infer that $1 \leq \operatorname{dim} \operatorname{Der}(\mathbf{E}) \leq 5$. This type of result can be proved using the work of Jacobson [21]. However, the advantage of Theorem 3 is that it fully describes the structure of the derivations on a natural basis.
Corollary 1. Lie algebras

$$
\mathbf{E}=\left\{\left(\begin{array}{lllll}
\alpha & 0 & \vdots & \beta & \gamma \\
0 & 2 \alpha & \vdots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \vdots & 2^{n-2} \alpha & 0 \\
0 & 0 & \vdots & s & t
\end{array}\right): \alpha, \beta, \gamma, s, t \in \mathbb{K}\right\}
$$

and

$$
\mathbf{E}^{\prime}=\left\{\left(\begin{array}{lllll}
\alpha & 0 & \vdots & \beta & \gamma \\
0 & 2 \alpha & \vdots & d_{2, n-1} & d_{2 n} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \vdots & d_{n-1, n-1} & d_{n-1, n} \\
0 & 0 & \vdots & s & t
\end{array}\right): \alpha, \beta, \gamma, s, t \in \mathbb{K}\right\}
$$

are isomorphic for any $d_{i, n-1}, d_{i, n} \in \mathbb{K}, i=\overline{2, n-1}$.
Remark 2. We stress that isomorphisms of Lie algebras do not imply isomorphism of the corresponding evolution algebras (see lemma 1).

## 4. Local and 2-local derivations for evolution algebras

The results of section 3 allow us to describe local and 2-local derivations of nilpotent evolution algebra. In this section, we want to fully describe local and 2-local derivations of nilpotent evolution algebras with $2^{n-2}+1$ index of nilpotency.

Recall that a linear mapping $\Delta$ on $\mathbf{E}$ is called local derivation if for every $\mathbf{u} \in \mathbf{E}$, a derivation $d_{\mathbf{u}}$ exists such that $\Delta(\mathbf{u})=d_{\mathbf{u}}(\mathbf{u})$. A mapping (not necessary linear) $D: \mathbf{E} \rightarrow \mathbf{E}$ is called 2-local derivation of algebra $\mathbf{E}$ if for every $\mathbf{u}, \mathbf{v} \in \mathbf{E}$ there exists a derivation $d_{\mathbf{u}, \mathbf{v}}$ of $\mathbf{E}$ such that $D(\mathbf{u})=d_{\mathbf{u}, \mathbf{v}}(\mathbf{u})$ and $D(\mathbf{v})=d_{\mathbf{u}, \mathbf{v}}(\mathbf{v})$. Therefore, it is natural to find all local derivations of $\mathbf{E}$.

Theorem 4. Let $\mathbf{E}$ be an n-dimensional nilpotent evolution algebra with $2^{(n-2)}+1$ index of nilpotency. Then, the following statements hold:
(i) If $n=3$, then the space of all local derivations has the following form:

$$
\left\{\left(\begin{array}{lll}
\alpha & \beta & \gamma  \tag{20}\\
0 & \delta & 0 \\
0 & s & t
\end{array}\right): \alpha, \beta, \gamma, \delta, s, t \in \mathbb{K}\right\} .
$$

(ii) If $n>3$, then every local derivation of $\mathbf{E}$ is a derivation.

Proof. (i) Let $n=3$. Due to Lemma 2, we may assume that an evolution algebra $\mathbf{E}$ is given by $\mathbf{e}_{1}^{2}=\mathbf{e}_{2}$ and $\mathbf{e}_{2}^{2}=\mathbf{e}_{3}^{2}=\mathbf{0}$. Take an arbitrary linear map $\Delta$ on $\mathbf{E}$, i.e.,

$$
\begin{gathered}
\Delta(\mathbf{u})=\left(\Delta_{11} u_{1}+\Delta_{21} u_{2}+\Delta_{31} u_{3}\right) \mathbf{e}_{1}+\left(\Delta_{12} u_{1}+\Delta_{22} u_{2}+\Delta_{32} u_{3}\right) \mathbf{e}_{2}+\left(\Delta_{13} u_{1}+\Delta_{23} u_{2}+\Delta_{33} u_{3}\right) \mathbf{e}_{3}, \\
\forall \mathbf{u}=u_{1} \mathbf{e}_{1}+u_{2} \mathbf{e}_{2}+u_{3} \mathbf{e}_{3} .
\end{gathered}
$$

If $\Delta$ is a local derivation, then for any $\mathbf{u}$, there exist $\alpha_{\mathbf{u}}, \beta_{\mathbf{u}}, s_{\mathbf{u}}$, and $t_{\mathbf{u}}$ such that

$$
\begin{aligned}
& \Delta_{11} u_{1}+\Delta_{21} u_{2}+\Delta_{31} u_{3}=\alpha_{\mathbf{u}} u_{1} \\
& \Delta_{12} u_{1}+\Delta_{22} u_{2}+\Delta_{12} u_{3}=\beta_{\mathbf{u}} u_{1}+2 \alpha_{\mathbf{u}} u_{2}+s_{\mathbf{u}} u_{3} \\
& \Delta_{13} u_{1}+\Delta_{23} u_{2}+\Delta_{33} u_{3}=\gamma_{\mathbf{u}} u_{1}+t_{\mathbf{u}} u_{3} ;
\end{aligned}
$$

From the first equation, we get $\Delta_{21}=\Delta_{31}=0$. If we take $\mathbf{u}$ such that $u_{1}=u_{3}=0$, then from the second equation, we immediately find $\Delta_{22} \in\left\{0,2 \Delta_{11}\right\}$. we find that $\Delta$ is a derivation of $\mathbf{E}$ if $\Delta_{22}=2 \Delta_{11}$.

Suppose $\Delta_{22}=0$ and $\Delta_{11} \neq 0$. Then, for every $\mathbf{u}$, we can find that derivation $d_{\mathbf{u}}$ satisfies $\Delta(\mathbf{u})=d_{\mathbf{u}}(\mathbf{u})$ as follows:

$$
d_{\mathbf{u}}= \begin{cases}\left(\begin{array}{lll}
\Delta_{11} & \Delta_{12}-\frac{2 \Delta_{11} u_{2}}{u_{1}} & \Delta_{13} \\
0 & 2 \Delta_{11} & 0 \\
0 & \Delta_{32} & \Delta_{33}
\end{array}\right), & \text { if } u_{1}, u_{3} \neq 0 \\
\left(\begin{array}{lll}
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{array}\right), & \end{cases}
$$

This result means that a linear mapping defined by

$$
\Delta=\left(\begin{array}{ccc}
\alpha & \beta & \gamma  \tag{21}\\
0 & 0 & 0 \\
0 & s & t
\end{array}\right): \alpha, \beta, \gamma, s, t \in \mathbb{K}
$$

is a local derivation of $\mathbf{E}$. Finally, as every derivation of algebra $\mathbf{E}$ is local derivation and due to (21), one obtains (20).
(ii) Let $\Delta$ be a non-zero local derivation given by matrix $\left(\Delta_{i j}\right)_{i, j \geq 1}^{n}$. Assume that $I_{A} \neq \emptyset$. Then, due to $\Delta\left(\mathbf{e}_{i}\right)=d_{\mathbf{e}_{i}}\left(\mathbf{e}_{i}\right)$, for any $i \leq n$, we immediately obtain

$$
\begin{align*}
& \Delta_{1, n-1}=d_{1, n-1}^{\left(\mathbf{e}_{1}\right)}, \quad \Delta_{1 n}=d_{1, n}^{\left(\mathbf{e}_{1}\right)} ;  \tag{22}\\
& \Delta_{i m}=d_{i m}^{\left(\mathbf{e}_{\mathbf{i}}\right)}, \quad m \in\{n-1, n\}, 2 \leq i<n-1 ;  \tag{23}\\
& \Delta_{n-1, n-1}=d_{n-1, n-1}^{\left(\mathbf{e}_{\mathbf{n}}-1\right)}, \quad \Delta_{n-1, n}=d_{n-1, n}^{\left(\mathbf{e}_{\mathbf{n}-1}\right)} ;  \tag{24}\\
& \Delta_{n, n-1}=d_{n, n-1}^{\left(\mathbf{e n}_{\mathbf{n}}\right)}, \quad \Delta_{n, n}=d_{n n}^{\left(\mathbf{e n}_{\mathbf{n}}\right)} ;  \tag{25}\\
& \Delta_{i j}=0, \text { otherwise. } \tag{26}
\end{align*}
$$

Taking $\mathbf{u}=\sum_{k=2}^{n-2} \mathbf{e}_{k}$. we obtain $\Delta_{i m}=-\sum_{k=1}^{n-i} a_{i-1, k+i} \Delta_{k+i, m}$. We consider that, $\mathbf{v}=$ $\mathbf{e}_{\mathbf{n}-\mathbf{1}}+a_{n-2, n} \mathbf{e}_{\mathbf{n}}$, and then a derivation $d_{\mathbf{v}}$ exists such that $\Delta(\mathbf{v})=\mathbf{d}_{\mathbf{v}}(\mathbf{v})$. Thus,

$$
\begin{aligned}
& \left(-a_{n-2, n} d_{n, n-1}^{\left(\mathbf{e}_{\mathbf{n}-1}\right)}+a_{n-2, n} d_{n, n-1}^{\left(\mathbf{e}_{\mathbf{n}}\right)}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}+\left(-a_{n-2, n} d_{n, n}^{\left(\mathbf{e}_{\mathbf{n}-1}\right)}+a_{n-2, n} d_{n n}^{\left(\mathbf{e}_{\mathbf{n}}\right)}\right) \mathbf{e}_{\mathbf{n}} \\
& =\left(-a_{n-2, n} d_{n, n-1}^{(\mathbf{u})}+a_{n-2, n} d_{n, n-1}^{(\mathbf{u})}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}+\left(-a_{n-2, n} d_{n, n}^{(\mathbf{u})}+a_{n-2, n} d_{n n}^{(\mathbf{u})}\right) \mathbf{e}_{\mathbf{n}} .
\end{aligned}
$$

This result implies $d_{n, n-1}^{\left(\mathbf{e}_{\mathbf{n}-1}\right)}=d_{n, n-1}^{\left(\mathbf{e}_{\mathbf{n}}\right)}, \quad d_{n, n}^{\left(\mathbf{e}_{n-1}\right)}=d_{n n}^{\left(\mathbf{e}_{\mathbf{n}}\right)}$. Therefore, one has $\Delta_{n-1, n-1}=$ $-a_{n-1, n} \Delta_{n, n-1}$. Suppose that $I_{A}=\emptyset$. We establish that $\Delta \in \operatorname{Der}(\mathbf{E})$ for any local derivation $\Delta$. Due to Lemmas 2 and 1 , to show every local derivation can be a derivation we need to check only for evolution algebra $\mathbf{E}^{\prime}$ (see Lemma 2).

As $\Delta\left(\mathbf{e}_{i}\right)=d_{\mathbf{e}_{i}}\left(\mathbf{e}_{i}\right)$, for any $i \leq n$, we can easily find

$$
\begin{array}{ll}
\Delta_{i i}=d_{i i}^{\left(\mathbf{e}_{i}\right)}, & i \leq n-1 \\
\Delta_{1, n-1}=d_{1, n-1}^{\left(\mathbf{e}_{1}\right)} & \\
\Delta_{1 n}=d_{1 n}^{\left(\mathbf{e}_{1}\right)} &  \tag{27}\\
\Delta_{n, n-1}=d_{n, n-1}^{\left(\mathbf{e}_{n}\right)} & \\
\Delta_{n, n}=d_{n, n}^{\left(\mathbf{e}_{n}\right)} & \\
\Delta_{i j}=0, & \text { otherwise. }
\end{array}
$$

Taking $\mathbf{u}=\sum_{k=1}^{n-2} \mathbf{e}_{k}$, we obtain

$$
\begin{equation*}
\Delta_{i i}=2^{i-1} \Delta_{11}, \quad i<n-1 . \tag{28}
\end{equation*}
$$

Consider $\mathbf{v}=\mathbf{e}_{2}+\mathbf{e}_{n-1}$. Then, a derivation $d_{\mathbf{v}}$ exists such that $\Delta(\mathbf{v})=d_{\mathbf{v}}(\mathbf{v})$. Due to the assumption (ii) of Theorem 3, we have

$$
\Delta_{22} \mathbf{e}_{2}+\Delta_{n-1, n-1} \mathbf{e}_{n}=2 d_{11}^{(\mathbf{v})} \mathbf{e}_{2}+2^{n-2} d_{11}^{(\mathbf{v})} \mathbf{e}_{n} .
$$

This result implies

$$
\begin{aligned}
& 2 d_{11}^{(\mathbf{v})}=\Delta_{22} \\
& 2^{n-2} d_{11}^{(\mathbf{v})}=\Delta_{n-1, n-1} .
\end{aligned}
$$

Adding the preceding equations into (28), we obtain $\Delta_{i i}=2^{i-1} \Delta_{11}$. Then, using (27), one finds

$$
\begin{array}{ll}
\Delta_{i i}=d_{i i}^{\left(\mathbf{e}_{1}\right)}, & i \leq n-1 \\
\Delta_{1, n-1}=d_{1, n-1}^{\left(\mathbf{e}_{1}\right)} & \\
\Delta_{1 n}=d_{1 n}^{\left(\mathbf{e}_{1}\right)} & \\
\Delta_{n, n-1}=d_{n, n-1}^{\left(\mathbf{e}_{n}\right)} & \\
\Delta_{n, n}=d_{n, n}^{\left(\mathbf{e}_{n}\right)} & \\
\Delta_{i j}=0, & \text { otherwise. }
\end{array}
$$

Thus, due to Theorem 3, we conclude that $\Delta$ is a derivation. The proof is complete.
Remark 3. In [25], it was proven that if $n>2$ then all local derivation is derivation, in the above theorem we find the if $n>3$ then all local derivation is derivation.

Theorem 5. Every 2-local derivation of nilpotent evolution algebras with $2^{n-2}+1$ index of nilpotency is a derivation.

Proof. Let $D$ be a non-zero 2-local derivation of $\mathbf{E}$. Denote $\Gamma_{1}=\left\{\mathbf{u} \in \mathbf{E}: u_{1} \neq\right.$ $0\}, \Gamma_{2}=\left\{\mathbf{u} \in \mathbf{E}: u_{n} \neq 0\right\}$.

Case $I_{A}=\emptyset$. By definition, functionals $\alpha_{\mathbf{u}, \mathbf{v}}, \beta_{\mathbf{u}, \mathbf{v}}, \gamma_{\mathbf{u}, \mathbf{v}}, s_{\mathbf{u}, \mathbf{v}}$ and $t_{\mathbf{u}, \mathbf{v}}$ exist such that

$$
\begin{align*}
& D(\mathbf{u})=\sum_{k=1}^{n-2} 2^{k-1} \alpha_{\mathbf{u}, \mathbf{v}} u_{k} \mathbf{e}_{k}+ \\
& \left(\beta_{\mathbf{u}, \mathbf{v}} u_{1}+\left(K_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-M_{n-1} s_{\mathbf{u}, \mathbf{v}}\right) u_{n-1}+s_{\mathbf{u}, \mathbf{v}} u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}, \mathbf{v}}+M_{i} s_{\mathbf{u}, \mathbf{v}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}} \\
& +\left(\gamma_{\mathbf{u}, \mathbf{v}} u_{1}+\left(L_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-N_{n-1} t_{\mathbf{u}, \mathbf{v}}\right) u_{n-1}+t_{\mathbf{u}, \mathbf{v}} u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}, \mathbf{v}}+N_{i} t_{\mathbf{u}, \mathbf{v}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}} \\
& D(\mathbf{v})=\sum_{k=1}^{n-2} 2^{k-1} \alpha_{\mathbf{u}, \mathbf{v}} v_{k} \mathbf{e}_{k}+ \\
& \left(\beta_{\mathbf{u}, \mathbf{v}} v_{1}+\left(K_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-M_{n-1} s_{\mathbf{u}, \mathbf{v}}\right) v_{n-1}+s_{\mathbf{u}, \mathbf{v}} v_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}, \mathbf{v}}+M_{i} s_{\mathbf{u}, \mathbf{v}}\right) v_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}} \\
& +\left(\gamma_{\mathbf{u}, \mathbf{v}} v_{1}+\left(L_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-N_{n-1} t_{\mathbf{u}, \mathbf{v}}\right) v_{n-1}+t_{\mathbf{u}, \mathbf{v}} v_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}, \mathbf{v}}+N_{i} t_{\mathbf{u}, \mathbf{v}}\right) v_{i}\right) \mathbf{e}_{\mathbf{n}} \tag{29}
\end{align*}
$$

where $\mathbf{u}=\sum_{k=1}^{n} u_{k} \mathbf{e}_{k}$ and $\mathbf{v}=\sum_{k=1}^{n} v_{k} \mathbf{e}_{k}$. Take an arbitrary non-zero $\mathbf{u} \in \mathbf{E}$. Then, for any $\mathbf{v}, \mathbf{v}^{\prime} \in \mathbf{E}$ from the preceding equations, we find

$$
\begin{align*}
& \sum_{k=1}^{n-2} 2^{k-1} \alpha_{\mathbf{u}, \mathbf{v}} u_{k} \mathbf{e}_{k}+ \\
& \left(\beta_{\mathbf{u}, \mathbf{v}} u_{1}+\left(K_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-M_{n-1} s_{\mathbf{u}, \mathbf{v}}\right) u_{n-1}+s_{\mathbf{u}, \mathbf{v}} u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}, \mathbf{v}}+M_{i} s_{\mathbf{u}, \mathbf{v}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}} \\
& +\left(\gamma_{\mathbf{u}, \mathbf{v}} u_{1}+\left(L_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-N_{n-1} t_{\mathbf{u}, \mathbf{v}}\right) u_{n-1}+t_{\mathbf{u}, \mathbf{v}} u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}, \mathbf{v}}+N_{i} t_{\mathbf{u}, \mathbf{v}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}} \\
& =\sum_{k=1}^{n-2} 2^{k-1} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}} u_{k} \mathbf{e}_{k}+ \\
& \left(\beta_{\mathbf{u}, \mathbf{v}^{\prime}} u_{1}+\left(K_{n-1} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}-M_{n-1} s_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{n-1}+s_{\mathbf{u}, \mathbf{v}^{\prime}} u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}+M_{i} s_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}} \\
& +\left(\gamma_{\mathbf{u}, \mathbf{v}^{\prime}} u_{1}+\left(L_{n-1} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}-N_{n-1} t_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{n-1}+t_{\mathbf{u}, \mathbf{v}^{\prime}} u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}+N_{i} t_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}}, \tag{30}
\end{align*}
$$

which is equivalent to

$$
\begin{aligned}
& \alpha_{\mathbf{u}, \mathbf{v}} u_{k}=\alpha_{\mathbf{u}, \mathbf{v}^{\prime}} u_{k}, \quad k=\overline{1, n-2} \\
& \left(\beta_{\mathbf{u}, \mathbf{v}} u_{1}+\left(K_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-M_{n-1} s_{\mathbf{u}, \mathbf{v}}\right) u_{n-1}+s_{\mathbf{u}, \mathbf{v}} u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}, \mathbf{v}}+M_{i} s_{\mathbf{u}, \mathbf{v}}\right) u_{i}\right)= \\
& \left(\beta_{\mathbf{u}, \mathbf{v}^{\prime}} u_{1}+\left(K_{n-1} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}-M_{n-1} s_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{n-1}+s_{\mathbf{u}, \mathbf{v}^{\prime}} u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}+M_{i} s_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{i}\right) \\
& \left(\gamma_{\mathbf{u}, \mathbf{v}} u_{1}+\left(L_{n-1} \alpha_{\mathbf{u}, \mathbf{v}}-N_{n-1} t_{\mathbf{u}, \mathbf{v}}\right) u_{n-1}+t_{\mathbf{u}, \mathbf{v}} u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}, \mathbf{v}}+N_{i} t_{\mathbf{u}, \mathbf{v}}\right) u_{i}\right)= \\
& \left(\gamma_{\mathbf{u}, \mathbf{v}^{\prime}} u_{1}+\left(L_{n-1} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}-N_{n-1} t_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{n-1}+t_{\mathbf{u}, \mathbf{v}^{\prime}} u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}, \mathbf{v}^{\prime}}+N_{i} t_{\mathbf{u}, \mathbf{v}^{\prime}}\right) u_{i}\right) .
\end{aligned}
$$

As, $\mathbf{u} \neq \mathbf{0}$, we obtain $\alpha_{\mathbf{u}, \mathbf{v}}=\alpha_{\mathbf{u}, \mathbf{v}^{\prime}}$ for any $\mathbf{v}, \mathbf{v}^{\prime} \in \mathbf{E}$. This result means that

$$
\begin{equation*}
\alpha_{\mathbf{u}, \mathbf{v}}=: \alpha_{\mathbf{u}} . \tag{31}
\end{equation*}
$$

Moreover, if $\mathbf{u} \in \Gamma$, then one finds

$$
\begin{equation*}
\beta_{\mathbf{u}, \mathbf{v}}=: \beta_{\mathbf{u}}, \gamma_{\mathbf{u}, \mathbf{v}}=: \gamma_{\mathbf{u}} \tag{32}
\end{equation*}
$$

Now, if $\mathbf{u} \in \boldsymbol{\Gamma}_{\mathbf{2}}$, then one finds

$$
\begin{equation*}
s_{\mathbf{u}, \mathbf{v}}=: s_{\mathbf{u}}, \quad t_{\mathbf{u}, \mathbf{v}}=: t_{\mathbf{u}} \tag{33}
\end{equation*}
$$

Taking (31),(32),(33) into (36), we conclude that mapping $D$ can be defined as

$$
D(\mathbf{u})=\left\{\begin{array}{l}
\sum_{k=1}^{n-2} 2^{k-1} \alpha_{\mathbf{u}} u_{k} \mathbf{e}_{k}+ \\
\left(\beta_{\mathbf{u}} u_{1}+\left(K_{n-1} \alpha_{\mathbf{u}}-M_{n-1} s_{\mathbf{u}}\right) u_{n-1}+s_{\mathbf{u}} u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}}+M_{i} s_{\mathbf{u}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}} \\
+\left(\gamma_{\mathbf{u}} u_{1}+\left(L_{n-1} \alpha_{\mathbf{u}}-N_{n-1} t_{\mathbf{u}}\right) u_{n-1}+t_{\mathbf{u}} u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}}+N_{i} t_{\mathbf{u}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}} \\
\text { if } \mathbf{u} \in \Gamma_{1} \cup \Gamma_{2} \\
\sum_{k=2}^{n-2} 2^{k-1} \alpha_{\mathbf{u}} u_{k} \mathbf{e}_{k}+\left(\left(K_{n-1} \alpha_{\mathbf{u}}-M_{n-1} s_{\mathbf{u}}\right) u_{n-1}+\sum_{i=2}^{n-2}\left(K_{i} \alpha_{\mathbf{u}}+M_{i} s_{\mathbf{u}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}  \tag{34}\\
+\left(\left(L_{n-1} \alpha_{\mathbf{u}}-N_{n-1} t_{\mathbf{u}}\right) u_{n-1}+\sum_{i=2}^{n-2}\left(L_{i} \alpha_{\mathbf{u}}+N_{i} t_{\mathbf{u}}\right) u_{i}\right) \mathbf{e}_{\mathbf{n}} \text { if } \mathbf{u} \notin \boldsymbol{\Gamma}_{\mathbf{1}} \cup \boldsymbol{\Gamma}_{\mathbf{2}} .
\end{array}\right.
$$

Then, for any $\mathbf{u}^{\prime}, \mathbf{v}^{\prime} \in \mathbf{E}$, we can find derivation $d$ given by

$$
d_{i j}= \begin{cases}2^{i-1} \alpha, & \text { if } 1 \leq i=j<n-1 \\ \beta, & \text { if } i=1, j=n-1 \\ \gamma, & \text { if } i=1, j=n \\ s, & \text { if } i=n, j=n-1 \\ t, & \text { if } i=n, j=n \\ K_{n-1} \alpha-M_{n-1} s, & \text { if } i=n-1, j=n-1 \\ L_{n-1} \alpha-N_{n-1} t, & \text { if } i=n-1, j=n \\ K_{i} \alpha+N_{i} s, & \text { if } 2 \leq i \leq n-2, j=n-1 \\ L_{i} \alpha+N_{i} t, & \text { if } 2 \leq i \leq n-2, j=n \\ 0, & \text { otherwise }\end{cases}
$$

such that $D\left(\mathbf{u}^{\prime}\right)=d\left(\mathbf{u}^{\prime}\right), D\left(\mathbf{v}^{\prime}\right)=d\left(\mathbf{v}^{\prime}\right)$. Then, from (34) one obtains

$$
\begin{equation*}
\alpha_{\mathbf{u}^{\prime}}=\alpha_{\mathbf{v}^{\prime}}=\alpha \quad \text { for any } \mathbf{u}^{\prime}, \mathbf{v}^{\prime} \in \mathbf{E} . \tag{35}
\end{equation*}
$$

This result means that functional $\alpha_{\mathbf{u}}$ is a constant.
To complete the proof, we show $\beta_{\mathbf{u}}, \gamma_{\mathbf{u}}, s_{\mathbf{u}}$, and $t_{\mathbf{u}}$ are constants for any $\mathbf{u} \in \mathbf{E}$. We consider non-zero points $\mathbf{u}, \mathbf{v} \in \Gamma_{1} \cup \Gamma_{2}$. Using the first equality of (34) and noting (35) by definition of 2-local derivation, we obtains $\beta_{\mathbf{u}}=\beta_{\mathbf{v}}, \gamma_{\mathbf{u}}=\gamma_{\mathbf{v}}, s_{\mathbf{u}}=s_{\mathbf{v}}$, and $t_{\mathbf{u}}=t_{\mathbf{v}}$. This result means that $\beta_{\mathbf{u}}, \gamma_{\mathbf{u}}, s_{\mathbf{u}}$ and $t_{\mathbf{u}}$ do not depend on $\mathbf{u}$, i.e., $\beta_{\mathbf{u}}=\beta, \gamma_{\mathbf{u}}=\gamma, s_{\mathbf{u}}=s$ and $t_{\mathbf{u}}=t$ for any $\mathbf{u} \in \boldsymbol{\Gamma}_{\mathbf{1}} \cup \boldsymbol{\Gamma}_{\mathbf{2}}$. Placing this result and (35) into (34) yields $D$, which has the following form:

$$
\begin{align*}
& D(\mathbf{u})=\sum_{\mathbf{k}=\mathbf{1}}^{\mathbf{n}-\mathbf{2}} \mathbf{2}^{\mathbf{k}-\mathbf{1}} \alpha \mathbf{u}_{\mathbf{k}} \mathbf{e}_{\mathbf{k}}+ \\
& \left(\beta u_{1}+\left(K_{n-1} \alpha-M_{n-1} s\right) u_{n-1}+s u_{n}+\sum_{i=2}^{n-2}\left(K_{i} \alpha+M_{i} s\right) u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}  \tag{36}\\
& +\left(\gamma u_{1}+\left(L_{n-1} \alpha-N_{n-1} t\right) u_{n-1}+t u_{n}+\sum_{i=2}^{n-2}\left(L_{i} \alpha+N_{i} t\right) u_{i}\right) \mathbf{e}_{\mathbf{n}} .
\end{align*}
$$

Due to Theorem $3(i i), D$ is a derivation.
Case $I_{A} \neq \emptyset$. By definition, there exist functionals $\beta_{\mathbf{u}, \mathbf{v}}, \gamma_{\mathbf{u}, \mathbf{v}}, s_{\mathbf{u}, \mathbf{v}}$ and $t_{\mathbf{u}, \mathbf{v}}$ such that

$$
\begin{align*}
& D(\mathbf{u})=\left(\beta_{\mathbf{u}, \mathbf{v}} u_{1}+s_{\mathbf{u}, \mathbf{v}} u_{n}+s_{\mathbf{u}, \mathbf{v}} \sum_{i=2}^{n-2} d_{i} u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}+\left(\gamma_{\mathbf{u}, \mathbf{v}} u_{1}+t_{\mathbf{u}, \mathbf{v}} u_{n}+t_{\mathbf{u}, \mathbf{v}} \sum_{i=2}^{n-2} d_{i} u_{i}\right) \mathbf{e}_{\mathbf{n}} \\
& D(\mathbf{v})=\left(\beta_{\mathbf{u}, \mathbf{v}} v_{1}+s_{\mathbf{u}, \mathbf{v}} v_{n}+s_{\mathbf{u}, \mathbf{v}} \sum_{i=2}^{n-2} d_{i} v_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}+\left(\gamma_{\mathbf{u}, \mathbf{v}} v_{1}+t_{\mathbf{u}, \mathbf{v}} v_{n}+t_{\mathbf{u}, \mathbf{v}} \sum_{i=2}^{n-2} d_{i} v_{i}\right) \mathbf{e}_{\mathbf{n}} \tag{37}
\end{align*}
$$

where $\mathbf{u}=\sum_{k=1}^{n} u_{k} \mathbf{e}_{k}$ and $\mathbf{v}=\sum_{k=1}^{n} v_{k} \mathbf{e}_{k}$.
Take arbitrary $\mathbf{u} \in \Gamma_{1} \cup \Gamma_{2}$. Then from the first equation of (37) we obtain $\beta_{\mathbf{u}, \mathbf{v}}=$ $\beta_{\mathbf{u}, \mathbf{v}^{\prime}}, s_{\mathbf{u}, \mathbf{v}}=s_{\mathbf{u}, \mathbf{v}^{\prime}}, t_{\mathbf{u}, \mathbf{v}}=t_{\mathbf{u}, \mathbf{v}^{\prime}}$ for any $\mathbf{v}, \mathbf{v}^{\prime} \in \mathbf{E}$. This result means that $\beta_{\mathbf{u}, \mathbf{v}}, t_{\mathbf{u}, \mathbf{v}}$, and $t_{\mathbf{u}, \mathbf{v}}$ do not depend on $\mathbf{v}$, i.e., $\beta_{\mathbf{u}, \mathbf{v}}=\beta_{\mathbf{u}}, s_{\mathbf{u}, \mathbf{v}}=s_{\mathbf{u}}, t_{\mathbf{u}, \mathbf{v}}=t_{\mathbf{u}}, \forall \mathbf{u} \in \Gamma_{1} \cup \Gamma_{2}$. On the other hand, from the second equation of (37) we obtains $\beta_{\mathbf{u}, \mathbf{v}}=\beta_{\mathbf{v}}, s_{\mathbf{u}, \mathbf{v}}=s_{\mathbf{v}}$ and $t_{\mathbf{u}, \mathbf{v}}=t_{\mathbf{v}}$ for any $\mathbf{v} \in \Gamma_{1} \cup \Gamma_{2}$. These facts yield that $\beta_{\mathbf{u}}=: \beta, s_{\mathbf{u}}=: s$ and $t_{\mathbf{u}}=: t$ for any $\mathbf{u}, \mathbf{v} \in \mathbf{E}$. Consequently, we have

$$
D(\mathbf{u})=\left(\beta u_{1}+s u_{n}+s \sum_{i=2}^{n-2} d_{i} u_{i}\right) \mathbf{e}_{\mathbf{n}-\mathbf{1}}+\left(\gamma u_{1}+t u_{n}+t \sum_{i=2}^{n-2} d_{i} u_{i}\right) \mathbf{e}_{\mathbf{n}} .
$$

Due to Theorem 3 ( $i$ ), we obtain $D \in \operatorname{Der}(\mathbf{E})$.

## 5. Automorphisms and local automorphisms

Recall that by an automorphism of an evolution algebra $\mathbf{E}$, we mean an isomorphism of $\mathbf{E}$ into itself. The set of all automorphisms is denoted by $\operatorname{Aut}(\mathbf{E})$. It is known that $\operatorname{Aut}(\mathbf{E})$ is a group. In this section, to describe $\operatorname{Aut}(\mathbf{E})$ of nilpotent evolution algebras with maximal index of nilpotency.

If $I_{A} \neq \emptyset$, then by $\eta$ we denote the largest common divisor of all numbers $2^{j-1}-2^{i}$ where $(i, j) \in I_{A}$, i.e.,

$$
\begin{equation*}
\eta=L C D_{(i, j) \in I_{A}}\left(2^{j-1}-2^{i}\right) . \tag{38}
\end{equation*}
$$

Theorem 6. Let $\mathbf{E}$ be an n-dimensional nilpotent evolution algebra with $2^{n-2}+1$ index of nilpotency and $A=\left(a_{i j}\right)_{i, j=1}^{n}$ be its structural matrix in a natural basis $\left\{\mathbf{e}_{i}\right\}_{i=1}^{n}$. Then, the following statements hold:
(i) if $I_{A} \neq \emptyset$ then

$$
\operatorname{Aut}(\mathbf{E})=\left\{\left(\begin{array}{llllll}
\alpha & 0 & \ldots & 0 & \beta & \gamma \\
0 & \alpha^{2} & \ldots & 0 & \varphi_{2, n-1} & \varphi_{2, n} \\
\vdots & \vdots & \ddots & \vdots & \vdots & \\
0 & 0 & \ldots & \alpha^{2^{n-2}} & \varphi_{n-2, n-1} & \varphi_{n-2, n} \\
0 & 0 & \ldots & 0 & \varphi_{n-1, n-1} & \varphi_{n-1, n} \\
0 & 0 & \ldots & 0 & s & t
\end{array}\right): \alpha, \beta, \gamma, s, t \in \mathbb{K}, \alpha^{\eta}=1\right\}
$$

where $\eta$ is defined as (38), and $\varphi_{i n-1}, \varphi_{i n}$ is given by the following recurrence formula.

$$
\begin{aligned}
& \varphi_{n-1, n-1}=\alpha^{2^{n-2}}-a_{n-2, n} s, \\
& \varphi_{n-1, n}=a_{n-2, n}\left(\alpha^{2^{n-2}}-t\right) \text {, } \\
& \varphi_{i, n-1}=a_{i-1, n-1} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n-1}, \quad 1<i<n-1, \\
& \varphi_{i, n}=a_{i-1, n} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n}, \quad 1<i<n-1 .
\end{aligned}
$$

(ii) if $I_{A}=\emptyset$ then

$$
\operatorname{Aut}(\mathbf{E})=\left\{\left(\begin{array}{llllll}
\alpha & 0 & \ldots & 0 & \beta & \gamma \\
0 & \alpha^{2} & \ldots & 0 & \varphi_{2, n-1} & \varphi_{2, n} \\
\vdots & \vdots & \ddots & \vdots & \vdots & \\
0 & 0 & \ldots & \alpha^{2^{n-2}} & \varphi_{n-2, n-1} & \varphi_{n-2, n} \\
0 & 0 & \ldots & 0 & \varphi_{n-1, n-1} & \varphi_{n-1, n} \\
0 & 0 & \ldots & 0 & s & t
\end{array}\right): \alpha, \beta, \gamma, s, t \in \mathbb{K}, \alpha \neq 0\right\}
$$

where $\varphi_{i n-1}, \varphi_{\text {in }}$ is given by the following recurrence formula:

$$
\begin{aligned}
& \varphi_{n-1, n-1}=\alpha^{2^{n-2}}-a_{n-2, n} s \\
& \varphi_{n-1, n}=a_{n-2, n}\left(\alpha^{2^{n-2}}-t\right) \\
& \varphi_{i, n-1}=a_{i-1, n-1}\left(\alpha^{2^{i-1}}-\varphi_{n-1, n-1}\right)-a_{i-1, n} s, \\
& \varphi_{i, n}=a_{i-1, n}\left(\alpha^{2^{i-1}}-t\right)-a_{i-1, n-1} \varphi_{n-1, n},
\end{aligned} 1<i<n-1, ~ 1<n-1 .
$$

Proof. Let $\varphi$ be a linear mapping on E. Now, we represent $\varphi$ on the basis elements as follows:

$$
\varphi\left(\mathbf{e}_{i}\right)=\sum_{j=1}^{n} \varphi_{i j} \mathbf{e}_{j}, \quad 1 \leq i \leq n
$$

We want to describe matrix $\left(\varphi_{i j}\right)_{i, j=1}^{n}$ when $\varphi$ is an automorphism of $\mathbf{E}$. Suppose that $\varphi$ is an automorphism. Then, we have

$$
\begin{aligned}
& \varphi\left(\mathbf{e}_{i}\right) \varphi\left(\mathbf{e}_{j}\right)=\mathbf{0}, \quad i \neq j \\
& \varphi\left(\mathbf{e}_{i}^{2}\right)=\left[\varphi\left(\mathbf{e}_{i}\right)\right]^{2}, \quad 1 \leq i \leq n
\end{aligned}
$$

which is equivalent to the followings:

$$
\begin{array}{r}
\sum_{k=1}^{n-1} \varphi_{i k} \varphi_{j k} \mathbf{e}_{k}^{2}=\mathbf{0}, \quad i \neq j \\
\sum_{j=i+1}^{n} a_{i j} \sum_{k=1}^{n} \varphi_{j k} \mathbf{e}_{k}=\sum_{k=1}^{n-1} \varphi_{i k}^{2} \mathbf{e}_{k}^{2}, \quad i \leq n-2 \\
a_{n-1, n}\left(\sum_{k=1}^{n} \varphi_{n k} \mathbf{e}_{k}\right)=\sum_{k=1}^{n-1} \varphi_{n-1, k}^{2} \mathbf{e}_{k}^{2}, \\
\sum_{k=1}^{n-1} \varphi_{n k}^{2} \mathbf{e}_{k}^{2}=0 . \tag{42}
\end{array}
$$

The linear independence of $\left\{\mathbf{e}_{1}^{2}, \mathbf{e}_{2}^{2}, \cdots, \mathbf{e}_{n-2}^{2}\right\}$ together with (39),(42) implies

$$
\begin{array}{rc}
\varphi_{i k} \varphi_{j k}=0, \quad i \neq j, k \leq n-2 \\
\varphi_{n-1, k}=\varphi_{n k}=0, \quad k \leq n-2 . \tag{44}
\end{array}
$$

We find that $\varphi_{n-2, n-2} \neq 0$. Plugging (44) into (41), we find

$$
\begin{array}{ll}
\varphi_{n-2, n-2}=\varphi_{n-3, n-3}^{2} &  \tag{45}\\
\varphi_{n-3, k}=0, & k \leq n-3
\end{array}
$$

Inserting $\mathbf{e}_{l}^{2}=\sum_{j=l+1}^{n} a_{l j} \mathbf{e}_{j}, l \leq n-2$ into (40), we obtain

$$
\begin{gather*}
\sum_{j=i+1}^{n} a_{i j} \varphi_{j l}=\sum_{j=1}^{l-1} a_{j l} \varphi_{i j}^{2}, \quad i \leq n-2, l \geq 2  \tag{46}\\
\sum_{j=i+1}^{n} a_{i j} \varphi_{j 1}=0, \quad i \leq n-2 \tag{47}
\end{gather*}
$$

We claim:

$$
\begin{array}{ll}
\varphi_{i l}=0, & l+1 \leq i \\
\varphi_{j+1, j+1}=\varphi_{j j}^{2}, & j \leq n-2 . \tag{48}
\end{array}
$$

Let us prove the last relations by induction. Due to (44),(45), the first step is satisfied. We take an arbitrary $i_{0}>1$, and assume that for any $i>i_{0}$, assertion (48) holds.

We must prove that $\varphi_{i_{0} l}=0$ for any $l \leq i_{0}-1$ and $\varphi_{i_{0} i_{0}}=\varphi_{i_{0}-1, i_{0}-1}^{2}$. Rewriting (46) for $i=i_{0}>1$, we find

$$
\begin{equation*}
\sum_{j=i_{0}+1}^{n} a_{i_{0} j} \varphi_{j l}=\sum_{j=1}^{l-1} a_{j l} \varphi_{i_{0} j}^{2}, \quad l \geq 2 \tag{49}
\end{equation*}
$$

If $j>i_{0}$, then due to the assumption, we have $\varphi_{j l}=0$ for any $l \leq i_{0}$. As, for any $l \leq i_{0}$ the left side of (49) is equals to zero. Thus,

$$
\begin{equation*}
\sum_{j=1}^{l-1} \varphi_{i_{0} j}^{2} a_{j l}=0, \quad 2 \leq l \leq i_{0} \tag{50}
\end{equation*}
$$

If $l=2$ then from (50) we obtain $\varphi_{i_{0} 1}=0$. Suppose that $\varphi_{i_{0}, l}=0$ for every $l<l_{0} \leq i_{0}$. Then this fact together with (50) for $l=l_{0}$ implies $\varphi_{i_{0}, l_{0}}=0$. Thus, we have shown that $\varphi_{i_{0}, l}=0$ for every $l \leq i_{0}$. From the arbitrary-ness of $i_{0}>1$, we conclude that

$$
\begin{equation*}
\varphi_{i l}=0, \quad l+1<i . \tag{51}
\end{equation*}
$$

On the other hand, rewriting (46) for $l=i+1$ and keeping in mind (51), we obtain

$$
\varphi_{i+1, i+1}=\varphi_{i i}^{2}, \quad i \leq n-2
$$

The last equality yields $\varphi_{i+1, i+1}=\varphi_{i i}^{2}$ for every $i \leq n-2$. This together with (45) implies

$$
\begin{equation*}
\varphi_{i i}=\varphi_{11}^{2^{i-1}} \neq 0, \quad i \leq n-2 . \tag{52}
\end{equation*}
$$

Thus, from (51) and (52), it follows (48).
Plugging (51) into (43), we obtain

$$
\begin{equation*}
\varphi_{i j}=0, \quad i<j<n-1 . \tag{53}
\end{equation*}
$$

Let us consider (46) for $l>i+1$. Then, for every $i \leq n-2$, we obtain

$$
\begin{gather*}
a_{i l} \varphi_{l l}=a_{i l} \varphi_{i i}^{2}, \quad i+1<l<n-1  \tag{54}\\
\sum_{j=i+1}^{n} a_{i j} \varphi_{j, n-1}=a_{i, n-1} \varphi_{i i}^{2}, \quad l=n-1 .  \tag{55}\\
\sum_{j=i+1}^{n} a_{i j} \varphi_{j n}=a_{i n} \varphi_{i i}^{2}, \quad l=n . \tag{56}
\end{gather*}
$$

From (56) with (52) we obtain a recurrence formula for $\varphi_{i n-1}, \varphi_{\text {in }}$ as follows:

$$
\begin{array}{ll}
\varphi_{n-1, n-1}=\alpha^{2^{n-2}}-a_{n-2, n} s, \\
\varphi_{n-1, n}=a_{n-2, n}\left(\alpha^{2^{n-2}}-t\right), \\
\varphi_{i, n-1}=a_{i-1, n-1} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n-1}, & 1<i<n-1,  \tag{57}\\
\varphi_{i, n}=a_{i-1, n} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n}, & 1<i<n-1 .
\end{array}
$$

Hence, we infer that $\varphi$ is an automorphism of evolution algebra (2) if and only if the followings holds:

$$
\begin{array}{ll}
\varphi_{i j}=0, & i \neq j, j<n-1 \\
\varphi_{i i}=\varphi_{11}^{2^{i-1}}, & i \leq n-2 \\
a_{i l} \varphi_{l l}=a_{i l} \varphi_{i i}^{2}, & i+1<l<n-1 \\
\varphi_{n-1, n-1}=\alpha^{2^{n-2}}-a_{n-2, n} s, & \\
\varphi_{n-1, n}=a_{n-2, n}\left(\alpha^{2^{n-2}}-t\right), & 1<i<n-1, \\
\varphi_{i, n-1}=a_{i-1, n-1} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n-1}, & 1<i<n-1 . \\
\varphi_{i, n}=a_{i-1, n} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n}, & 1<i=1 \tag{58}
\end{array}
$$

Now let us consider two cases w.r.t. $I_{A}$.
Case $I_{A} \neq \emptyset$. For the sake of convenience, we denote $\varphi_{11}=\alpha \neq 0$. Then, from (58) one obtains

$$
\begin{array}{ll}
\varphi_{i j}=\varphi_{j i}=0, & i \neq j, j<n-1 \\
\varphi_{i i}=\alpha^{2^{i-1}}, & i \leq n-2 \\
\alpha^{2^{l-1}-2^{i}}=1, & (i, l) \in I_{A} \\
\varphi_{1, n-1}=\gamma, \varphi_{1 n}=\beta, \varphi_{n, n-1}=s, \varphi_{n, n}=t & \\
\varphi_{n-1, n-1}=\alpha^{2^{n-2}}-a_{n-2, n} s, & \\
\varphi_{n-1, n}=a_{n-2, n}\left(\alpha^{2^{n-2}}-t\right), & 1<i<n-1 \\
\varphi_{i, n-1}=a_{i-1, n-1} \alpha^{2^{i-1}}-\sum_{j=i+1}^{n-i} a_{i-1, j} \varphi_{j, n-1}, & 1<i<n-1
\end{array}
$$

where $\alpha, \beta, \gamma, s, t \in \mathbb{K}$, and $\alpha^{\eta}=1$, which implies the assertion.
Case $I_{A}=\emptyset$. For the automorphism $\varphi$, we have

$$
\begin{array}{ll}
\varphi_{i j}=\varphi_{j i}=0, & i \neq j, j<n-1 \\
\varphi_{i i}=\alpha^{2^{i-1}}, & 1 \leq i \leq n-2 \\
\varphi_{1, n-1}=\gamma, \varphi_{1 n}=\beta, \varphi_{n, n-1}=s, \varphi_{n, n}=t & \\
\varphi_{n-1, n-1}=\alpha^{2^{n-2}}-a_{n-2, n} s, & \\
\varphi_{n-1, n}=a_{n-2, n}\left(\alpha^{\left.2^{n-2}-t\right),}\right. & \\
\varphi_{i, n-1}=a_{i-1, n-1}\left(\alpha^{2^{i-1}}-\varphi_{n-1, n-1}\right)-a_{i-1, n} s, \quad 1<i<n-1, \\
\varphi_{i, n}=a_{i-1, n}\left(\alpha^{2^{i-1}}-t\right)-a_{i-1, n-1} \varphi_{n-1, n}, & 1<i<n-1 .
\end{array}
$$

where $\alpha, \beta, \gamma, s, t \in \mathbb{K}$, which implies the assertion.
The proof is complete.

### 5.1. Local automorphisms of evolution algebras

In the previous section, we have been able to find the set of all automorphisms of evolution algebra (2). Now, we show that every local automorphism is an automorphism if evolution algebra is defined by (2) with $n>3$. Recall that a linear mapping $\psi$ from $\mathbf{E}$ to $\mathbf{E}$ is called local automorphism if for every $\mathbf{u} \in \mathbf{E}$ there exists an automorphism $\varphi_{\mathbf{u}} \in \operatorname{Aut}(\mathbf{E})$ such that $\psi(\mathbf{u})=\varphi_{\mathbf{u}}(\mathbf{u})$.

Theorem 7. Let $\mathbf{E}$ be an n-dimensional nilpotent evolution algebra with $2^{n-2}+1$ index of nilpotency. Then, the following statements hold:
(i) If $n=3$, then the set of all local automorphisms has the following form:

$$
\left\{\left(\begin{array}{ccc}
\alpha & \beta & \gamma  \tag{59}\\
0 & l^{2} & 0 \\
0 & s & T
\end{array}\right): \alpha, \beta, \gamma, l, s, t \in \mathbb{K}, \alpha l \neq 0\right\}
$$

(ii) If $n>3$, then every local automorphism of $\mathbf{E}$ is an automorphism.

Proof. (i) Let $n=3$. Due to Lemma 2, we may assume that an evolution algebra $\mathbf{E}$ is given by $\mathbf{e}_{1}^{2}=\mathbf{e}_{2}$ and $\mathbf{e}_{2}^{2}=\mathbf{e}_{3}^{2}=\mathbf{0}$. Take an arbitrary linear map $\psi$ on $\mathbf{E}$, i.e.,

$$
\begin{aligned}
\psi(\mathbf{u})= & \left(\psi_{11} u_{1}+\psi_{21} u_{2}+\psi_{31} u_{3}\right) \mathbf{e}_{1}+\left(\psi_{12} u_{1}+\psi_{22} u_{2}+\psi_{32} u_{3}\right) \mathbf{e}_{2}+\left(\psi_{13} u_{1}+\psi_{23} u_{2}+\psi_{33} u_{3}\right) \mathbf{e}_{3} \\
& \forall \mathbf{u}=u_{1} \mathbf{e}_{1}+u_{2} \mathbf{e}_{2}+u_{3} \mathbf{e}_{3} .
\end{aligned}
$$

If $\psi$ is a local automorphism, then for any $\mathbf{u}$, there exist $\alpha_{\mathbf{u}}, \beta_{\mathbf{u}}, \gamma_{\mathbf{u}}, s_{\mathbf{u}}$ and $t_{\mathbf{u}}$, such that

$$
\begin{aligned}
& \psi_{11} u_{1}+\psi_{21} u_{2}+\psi_{31} u_{3}=\alpha_{\mathbf{u}} u_{1} \\
& \psi_{12} u_{1}+\psi_{22} u_{2}+\psi_{32} u_{3}=\beta_{\mathbf{u}} u_{1}+\alpha_{\mathbf{u}}^{2} u_{2}+s_{\mathbf{u}} u_{3} \\
& \psi_{13} u_{1}+\psi_{23} u_{2}+\psi_{33} u_{3}=\gamma_{\mathbf{u}} u_{1}+t_{\mathbf{u}} u_{3} .
\end{aligned}
$$

From the first equation, we obtain $\psi_{21}=\psi_{31}=0$, and from the third equation, we have $\psi_{23}=0$. If we take $\mathbf{u}$ such that $u_{1}=u_{3}=0$, then from the second equation, we immediately find $\psi_{22}=\alpha_{\mathbf{u}}^{2}$. It yields that if $\psi$ is a local automorphism, it has the following form:

$$
\left\{\left(\begin{array}{ccc}
\alpha & \beta & \gamma  \tag{60}\\
0 & l^{2} & 0 \\
0 & s & T
\end{array}\right): \alpha, \beta, \gamma, l, s, t \in \mathbb{K}, \alpha l \neq 0\right\}
$$

We show that (60) is indeed a local automorphism of (2). In fact, for any $\mathbf{u} \in \mathbf{E}$, we may take an automorphism $\varphi_{\mathbf{u}}$ of (2) as follows:

$$
\varphi_{\mathbf{u}}= \begin{cases}\left(\begin{array}{lll}
\alpha & \beta+\frac{\left(l^{2}-\alpha^{2}\right) u_{2}}{u_{1}} & \gamma \\
0 & \alpha^{2} & 0 \\
0 & s & t
\end{array}\right), & \text { if } u_{1} u_{3} \neq 0 \\
\left(\begin{array}{lll}
l & 0 & 0 \\
0 & l^{2} & 0 \\
0 & 0 & 0
\end{array}\right), & \text { if } u_{1}=u_{3}=0\end{cases}
$$

From this, one can check that $\psi(\mathbf{u})=\varphi_{\mathbf{u}}(\mathbf{u})$.
(ii) Let $n>3$. Let $\psi$ be a local automorphism for (2). By definition of local automorphism, for every $\mathbf{u} \in \mathbf{E}$ we have $\psi(\mathbf{u})=\varphi_{\mathbf{u}}(\mathbf{u})$, where $\varphi_{\mathbf{u}}$ is an automorphism. Then, theorem 6 implies $\psi_{i j}=0$ for every $i \neq j, j<n-1$. On the other hand, taking $\mathbf{u}=\mathbf{e}_{i}$, $i \leq n$, we conclude that the local automorphism $\psi$ has the following form:

$$
\psi=\left(\begin{array}{lllllll}
\alpha_{\mathbf{e}_{1}} & 0 & 0 & \vdots & 0 & \beta_{\mathbf{e}_{1}} & \gamma \mathbf{e}_{1} \\
0 & \alpha_{\mathbf{e}_{2}}^{2} & 0 & \vdots & 0 & \varphi_{2, n-1}^{\left(\mathbf{e}_{2}\right)} & \varphi_{2 n}^{\left(\mathbf{e}_{2}\right)} \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \\
0 & 0 & 0 & \vdots & \alpha_{\mathbf{e}_{n-2}}^{2^{n-2}} & \varphi_{n-2, n-1}^{\left(\mathbf{e}_{n-2}\right)} & \varphi_{n-2, n}^{\left(\mathbf{e}_{n-2}\right)} \\
0 & 0 & 0 & \vdots & 0 & \varphi_{n-1, n-1}^{\left(\mathbf{e}_{n-1}\right)} & \varphi_{n-1, n}^{\left(\mathbf{e}_{n-1}\right)} \\
0 & 0 & 0 & \vdots & 0 & s_{\mathbf{e}_{n}} & t_{\mathbf{e}_{n}}
\end{array}\right)
$$

Now, we take arbitrary $\mathbf{v}=\sum_{i=1}^{n} v_{i} \mathbf{e}_{i}$. Then, from $\psi(\mathbf{v})=\varphi_{\mathbf{v}}(\mathbf{v})$, we obtain

$$
\begin{align*}
& \alpha_{\mathbf{e}_{i}}^{2^{i-1}} v_{i}=\alpha_{\mathbf{v}}^{2^{i-1}} v_{i}, \quad i<n-1  \tag{61}\\
& \beta_{\mathbf{e}_{1}} v_{1}+s_{\mathbf{e}_{n}} v_{n}+\sum_{k=2}^{n-1} \varphi_{k, n-1}^{\left(\mathbf{e}_{k}\right)} v_{k}=\beta_{\mathbf{v}} v_{1}+s_{\mathbf{v}} v_{n}+\sum_{k=2}^{n-1} \varphi_{k, n-1}^{(\mathbf{v})} v_{k}  \tag{62}\\
& \gamma_{\mathbf{e}_{1}} v_{1}+t_{\mathbf{e}_{n}} v_{n}+\sum_{k=2}^{n-1} \varphi_{k, n}^{\left(\mathbf{e}_{e}\right)} v_{k}=\beta_{\mathbf{v}} v_{1}+t_{\mathbf{v}} v_{n}+\sum_{k=2}^{n-1} \varphi_{k, n}^{(\mathbf{v})} v_{k} . \tag{63}
\end{align*}
$$

From (61) we find

$$
\begin{equation*}
\alpha_{\mathbf{e}_{i}}^{2^{i-1}}=\alpha_{\mathbf{e}_{1}}^{2^{i-1}}, \quad i<n-1 \tag{64}
\end{equation*}
$$

Consequently, $\varphi_{k, n-1}^{\left(\mathbf{e}_{k}\right)}=\varphi_{k, n-1}^{\left(\mathbf{e}_{1}\right)}$ and $\varphi_{k n}^{\left(\mathbf{e}_{\mathbf{e}}\right)}=\varphi_{k n}^{\left(\mathbf{e}_{\mathbf{e}}\right)}$ for any $k<n$. Based on this fact, the following is obtained from (62) and (63),

$$
\begin{equation*}
\gamma_{\mathbf{e}_{1}} v_{1}+s_{\mathbf{e}_{n}} v_{n}=\gamma_{\mathbf{v}} v_{1}+s_{\mathbf{v}} v_{n}, \quad \beta_{\mathbf{e}_{1}} v_{1}+t_{\mathbf{e}_{n}} v_{n}=\beta_{\mathbf{v}} v_{1}+s_{\mathbf{v}} v_{n} . \tag{65}
\end{equation*}
$$

Finally, taking $\mathbf{v}^{\prime}=\mathbf{e}_{2}+\mathbf{e}_{n}$, we obtain $\gamma_{\mathbf{e}_{1}}=\gamma_{\mathbf{v}}, \beta_{\mathbf{e}_{1}}=\beta_{\mathbf{v}}, s_{\mathbf{e}_{n}}=s_{\mathbf{v}}$, and $t_{\mathbf{e}_{n}}=t_{\mathbf{v}}$, for any $\mathbf{v} \in \mathbf{E}$.

Thus, we conclude that local automorphism $\psi=\left(\varphi_{i j}\right)$ has the following form:

$$
\varphi_{i j}= \begin{cases}\alpha_{\mathbf{e}_{1}}^{2 i-1}, & i=j>n-1 \\ \gamma_{\mathbf{e}_{1}}, & i=1, j=n-1 \\ \beta_{\mathbf{e}_{1}}, & i=1, j=n \\ \varphi_{i, n-1}^{\left(\mathbf{e}_{1}\right)}, & i>1, j=n-1 \\ \varphi_{i n}, & i>1, j=n \\ s_{\mathbf{e}_{1}}, & i=n, j=n-1 \\ t_{\mathbf{e}_{1}}, & i=n, j=n \\ 0, & \text { otherwise }\end{cases}
$$

Thus, theorem 6 implies that the local automorphism $\psi$ is an automorphism. The proof is complete.

Remark 4. In [25], it was proven that if $n>2$ then all local automorphism is automorphism, in the above theorem we find that if $n>3$ then all local automorphism is automorphism.

## References

[1] Ahmad Alarafeen, Izzat Qaralleh, and Azhana Ahmad. Derivation of five-dimensional lotka-voltera algebra. arXiv preprint arXiv:1912.08594, 2019.
[2] Abdelwahab Alsarayreh, Izzat Qaralleh, and Muhammad Zaini Ahmad. Derivation of three-dimensional evolution algebra. JP J. Algebra Number Theory Appl, 39:4, 2017.
[3] Shavkat Ayupov, Abror Khudoyberdiyev, and Bakhtiyor Yusupov. Local and 2local derivations of solvable leibniz algebras. International Journal of Algebra and Computation, 2020.
[4] Shavkat Ayupov, Karimbergen Kudaybergenov, and Antonio M Peralta. A survey on local and 2-local derivations on $c^{*}$-and von neumann algebras. Topics in Functional Analysis and Algebra, Contemporary Mathematics, 672:73-126, 2016.
[5] Julio Becerra, María Beltrán, and M Velasco. Pulse processes in networks and evolution algebras. Mathematics, 8(3):387, 2020.
[6] Paula Cadavid, Mary Luz Rodiño Montoya, and Pablo M Rodriguez. The connection between evolution algebras, random walks and graphs. Journal of Algebra and Its Applications, 19(02):2050023, 2020.
[7] LM Camacho, JR Gómez, BA Omirov, and RM Turdibaev. The derivations of some evolution algebras. Linear and Multilinear Algebra, 61(3):309-322, 2013.
[8] LM Camacho, A Kh Khudoyberdiyev, and BA Omirov. On the property of subalgebras of evolution algebras. Algebras and Representation Theory, 22(2):281-296, 2019.
[9] Luisa María Camacho Santana, José Ramón Gómez Martín, Bakhrom A Omirov, and RM Turdibaev. Some properties of evolution algebras. Bulletin of the Korean Mathematical Society, 50 (5), 1481-1494., 2013.
[10] Yolanda Cabrera Casado, Mercedes Siles Molina, and M Victoria Velasco. Classification of three-dimensional evolution algebras. Linear Algebra and its Applications, 524:68-108, 2017.
[11] JM Casas, M Ladra, BA Omirov, and UA Rozikov. index and dibaricity of evolution algebras. Linear Algebra and its Applications, 439(1):90-105, 2013.
[12] José M Casas, Manuel Ladra, Bakhrom A Omirov, and Utkir A Rozikov. On evolution algebras. In Algebra Colloquium, volume 21, pages 331-342. World Scientific, 2014.
[13] R Costa. On the derivation algebra of zygotic algebras for polyploidy with multiple alleles. Boletim da Sociedade Brasileira de Matemática-Bulletin/Brazilian Mathematical Society, 14(1):63-80, 1983.
[14] Hamza Abd El-Qader, Ahmad Termimi Ab Ghani, and Izzat Qaralleh. On evolution algebras and their derivations. Journal of Mathematics and Computer Scinces, 21(3):213-230, 2020.
[15] Alberto Elduque and Alicia Labra. On nilpotent evolution algebras. Linear Algebra and its Applications, 505:11-31, 2016.
[16] Rasul Ganikhodzhaev, Farrukh Mukhamedov, Abror Pirnapasov, and Izzat Qaralleh. Genetic volterra algebras and their derivations. Communications in Algebra, 46(3):1353-1366, 2018.
[17] Harry Gonshor. Derivations in genetic algebras. Communications in Algebra, 16(8):1525-1542, 1988.
[18] AS Hegazi and Hani Abdelwahab. Five-dimensional nilpotent evolution algebras. arXiv preprint arXiv:1508.07442, 2015.
[19] AS Hegazi and Hani Abdelwahab. Nilpotent evolution algebras over arbitrary fields. Linear Algebra and its Applications, 486:345-360, 2015.
[20] P Holgate. The interpretation of derivations in genetic algebras. Linear Algebra and Its Applications, 85:75-79, 1987.
[21] Nathan Jacobson. A note on automorphisms and derivations of lie algebras. In Nathan Jacobson Collected Mathematical Papers, pages 251-253. Springer, 1989.
[22] Richard V Kadison. Local derivations. Journal of Algebra, 130(2):494-509, 1990.
[23] A Kh Khudoyberdiyev, Bakhrom A Omirov, and Izzat Qaralleh. Few remarks on evolution algebras. Journal of Algebra and Its Applications, 14(04):1550053, 2015.
[24] D. R. Larson and A. R. Sourour. Local derivations and local automorphisms of B(x). In Proc. Sympos. Pure Math. 51, pages 187-194. American Mathematical Society, 1990.
[25] Farrukh Mukhamedov, Otabek Khakimov, Bakhrom Omirov, and Izzat Qaralleh. Derivations and automorphisms of nilpotent evolution algebras with maximal nilindex. Journal of Algebra and Its Applications, 18(12):1950233, 2019.
[26] Farrukh Mukhamedov, Otabek Khakimov, and Izzat Qaralleh. Classification of nilpotent evolution algebras and extensions of their derivations. Communications in Algebra, pages 1-15, 2020.
[27] Farrukh Mukhamedov, Bakhrom Omirov, and Izzat Qaralleh. Description of three dimensional solvable evaluation algebras. In International Conference on Mathematical Sciences and Statistics 2013, pages 165-174. Springer, 2014.
[28] Farrukh Mukhamedov and Izzat Qaralleh. On derivations of genetic algebras. In Journal of Physics: Conference Series, volume 553, 2014.
[29] Farrukh Mukhamedov, Izzat Qaralleh, and Abror Pirnapasov. On genetic and evolution algebras in dimension three. International Journal of Algebra, 10(7):327-334, 2016.
[30] Izzat Qaralleh. A description of derivations of a class of nilpotent evolution algebras. 14(2):295-304, 2020.
[31] Izzat Qaralleh and Farrukh Mukhamedov. Volterra evolution algebras and their graphs. Linear and Multilinear Algebra, pages 1-17, 2019.
[32] Peter Šemrl. Local automorphisms and derivations on $b(h)$. Proceedings of the American Mathematical Society, 125(9):2677-2680, 1997.
[33] Jianjun Paul Tian. Evolution algebras and their applications. Springer, 2007.
[34] Jianjun-Paul Tian and Piotr Vojtĕchovskỳ. Mathematical concepts of evolution algebras in non-mendelian genetics. Quasigroups and Related Systems, 14(1):111-122, 2006.


[^0]:    *Corresponding author.
    DOI: https://doi.org/10.29020/nybg.ejpam.v14i1.3912
    Email addresses: ahmadalarfeen@gmail.com (A. Alarafeen),
    izzat_math@yahoo.com (I. Qaralleh), azhana@usm.my (A. Ahmad)

