



Numerical Analysis of Deterministic and Stochastic Model of COVID-19 Co-infection with Influenza

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Abstract. The dynamics of co-infection model of SARS-Cov-2 and influenza is presented in this paper. A detailed analysis is conducted on the possible effects of the influenza vaccination alone as well as the combined effect of both vaccinations on the co-infection dynamics. The two diseases' basic reproduction numbers utilizing the next-generation matrix method. Endemic equilibrium point (EEP), and disease free equilibrium points (DFEP) are calculated for deterministic model. The global stability of the model equilibrium is demonstrated using the Lyapunov function function, and the local stability is discussed for deterministic as well as stochastic. There are supplied simulations to highlights the theoretical outcomes of the model. For each infection, we compute the basic reproductive numbers $\mathbb{R}_{01} < 1$, and $\mathbb{R}_{02} < 1$. To determine the realistic values of the model parameters, data regarding COVID-19 instances was obtained from China National Health Commission. Sensitivity study employing the PRCC technique to look into the key variables that affect \mathbb{R}_{01} , or $\mathbb{R}_{02} < 1$ decrease or increase. We show the numerical simulation of the model using non-standard finite difference scheme (NSFD) and stochastic numerical method. On the basis of these mentioned numerical methods, some graphical results for the model with sensitive parameters are provided.

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Key Words and Phrases: Co-infection model, NSFD scheme, Sensitivity analysis, Stochastic model, Stochastic numerical analysis

1. Introduction

In December 2019, a city in China known as Wuhan identified the coronavirus for the first time [1, 2]. As of November 2022, the new infection has caused over six hundred million cases and over seven million fatalities worldwide in a short period of time [3]. Severe Acute Respiratory Syndrome Coronavirus 2 (SARS-CoV-2) is the cause of COVID-19 disease, the common cold, and Middle East Respiratory Syndrome (MERS)

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[4]. However, COVID-19 is more contagious and deadly than the aforementioned illnesses. The World Health Organization (WHO) considered the COVID-19 outbreak to be a pandemic in March 2020 [4, 5]. Direct transmission of the virus can occur from one person to another via breathing in harmful particles generated when an infected individual meets each other, talks, coughs, or sneezes. If a susceptible individual comes into contact with somebody who is infected through touching, holding, kissing, or other behaviors, they could become infected with the virus. The indirect transmission mechanism involves contacting a contaminated surface with the hands to touch the eyes, nose, and mouth [6, 7]. Prior to the introduction of vaccines, government officials and decision-makers advised the public to focus on non-pharmaceutical means. Good personal hygiene, using the right sneezing mode, physical distancing, closing schools, isolations, hospitalization of exposed people and infected individuals, contact tracing, and donning face masks are some of these non-pharmaceutical interventions [8, 9]. To reduce the number of cases, other measures included screening exposed persons, providing rapid immunization, and providing intense medical care [10, 11]. In many countries throughout the world, infection controls and preventive measures were in place, but the disease continued to spread. It started with alpha, went on to beta and delta, and is still running strong with the latest omicron version [12, 13], which significantly raises the number of cases and death rate. Public health professionals have long been concerned about the bacterial influenza disease often known as the flu. Seasonal influenza outbreaks affect millions of people each year, with an estimated 500,000 deaths from the illness [14, 15]. It has been demonstrated that only close interaction with droplets and interaction with an infected individual can carry influenza dynamics, despite mounting evidence suggesting aerosols play a significant role in the spread of the illness [16, 17]. Muscle aches, loss of hunger, temperature, sore head, and sore throats are typical symptoms.

The cyclical nature of outbreaks of influenza and the persistent frequency of COVID-19 may cause influenza and SARS-Cov2 to revolve, greatly increasing the likelihood of co-infection. The research that is currently applicable indicates that co-infection with the SARS-Cov2 increases influenza infectivity in an extensive range of cell types [18] and that people with co-infection seem to have same clinical signs and imaging results compared with individuals infected with SARS-Cov-2 only [19]. However, there is limited information available regarding the biological and medical consequences of co-infection. Seasonal influenza vaccination is considered to play a major impact in influenza prevention as well as offer extra advantages during the difficult COVID-19 pandemic period. The influenza vaccine considerably reduces the risk of respiratory infectious disorders such as COVID-19, which also relieves pressure on medical facilities and save materials for treating more serious infection [20]. Furthermore, it is believed that vaccination against influenza enhances COVID-19 surveillance's specificity and accuracy [21]. The co-infection of COVID-19 and influenza virus was investigated by [22] using two mathematical models of COVID-19 and the co-infection idea (COVID-19 and influenza virus). A unique characteristic of epidemic models, incidence rates explain how a disease spreads within a population or among a host. There are many types of interaction rates of infectious disease in mathematical models, including concave, bilinear, square root, monotonic, saturated and linear models,

the following is used in our work, which is called convex incidence rate. Follow as,

$$f(\mathcal{S}, \mathcal{I}) = K\mathcal{S}(\beta\mathcal{S} + 1).$$

Here, $\beta > 0$ and $K > 0$ are belong to positive real constant. \mathcal{S} stand for susceptible population and infection is $\mathcal{I} = \mathcal{I}_f + \mathcal{I}_c$. Hence \mathcal{I}_f is represent the influenza infection rate and \mathcal{I}_c for COVID infection rate. Due to the $K\mathcal{S}\mathcal{I}^2$ term, squaring on \mathcal{I} gives a double rate of infection; furthermore, the term $K\mathcal{S}\mathcal{I}$ gives a single infection rate. This type of interaction will be considered in this research work.

For numerical simulation, the non-standard finite difference (NSFD) scheme is used for deterministic model. Numerous nonlinear problems can be effectively and practically solved numerically with this method. For instance, many scholars have used this technique to numerically simulate a variety of effusive systems [23, 24]. However, [25] discussed COVID-19 dynamics using fractional numerical simulation. One of the best methods for estimating solutions to fractional-order models among those discussed is the NSFD method; for further details, see [26, 27].

This study introduces a new vaccination-based deterministic co-infection approach for COVID-19 and influenza. The purpose of this study is to examine the dynamic and stabilization characteristics of the model equations as well as the connection between influenza prevalence and the COVID-19 vaccine. To discuss the dynamics of co-infection under convex incidence rate, we examine a mathematical $\mathcal{SEI}_c\mathcal{I}_f\mathcal{V}\mathcal{R}\mathcal{C}$ model. \mathcal{S} stands for susceptible, \mathcal{E} for exposed, \mathcal{I}_f for influenza infected, \mathcal{I}_c for covid infected, \mathcal{V} for vaccinated, and \mathcal{R} for recovered, and \mathcal{C} for combined infection compartment individual. These seven equations comprised the model. To determine the most vulnerable variables that raise or lower the fundamental reproduction number R_0 , sensitivity analysis is performed. The organization of the work is as follows: model formulation is discussed in Section 2. Mathematical results, local and global stability are discussed in Section 3. Numerical simulation through the NSFD scheme and the stochastic model are in Section 4, and the last section is a summarization of the results.

2. Model Formulation

In this section, we present the dynamic of the co-infection of influenza and COVID-19 in the following model form. Basically the infection is divided into two way influenza \mathcal{I}_f and COVID \mathcal{I}_c , the whole population is represent by \mathcal{M} which is equal to the sum of all compartments, $\mathcal{M} = \mathcal{S} + \mathcal{E} + \mathcal{I}_f + \mathcal{I}_c + \mathcal{C} + \mathcal{V} + \mathcal{R}$. We formulate the model using the

following equations:

$$\begin{aligned}
 \frac{dS}{dt} &= b - KSI(\beta I + 1) - d_0S + rR, \\
 \frac{dE}{dt} &= KSI(\beta I + 1) - (d_0 + \eta + \phi)E, \\
 \frac{dI_f}{dt} &= \phi E - (\gamma_1 + v_f + d_0 + c_1)I_f, \\
 \frac{dI_c}{dt} &= \eta E - (\gamma_2 + v_c + d_0 + c_2)I_c, \\
 \frac{dC}{dt} &= c_1I_f + c_2I_c - (d_0 + v_3)C, \\
 \frac{dV}{dt} &= v_fI_f + v_cI_c + v_3C - (\gamma_3 + d_0)V, \\
 \frac{dR}{dt} &= \gamma_1I_f + \gamma_2I_c + \gamma_3V - (r + d_0)R.
 \end{aligned}
 \tag{1}$$

Here is the model flow chart which shows the dynamics of the flow with respect to time of different classes of the co-infection.

The variables used in the system (1) with their physical meaning are, new recruitment

1. Flow chart

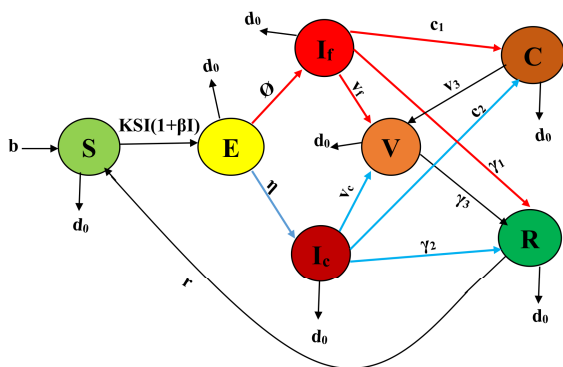


Figure 1: Flow chart of parameters of the model (1).

represent by b , death rate is represented by d_0 , the co-infection rate from influenza is c_1 and COVID is c_2 . v_f is vaccination rate of influenza, and v_c is vaccination rate of covid-19. The recovery rate from influenza is represented by γ_1 , the recovery rate from COVID is by γ_2 and recovery from vaccination is represented by γ_3 . K stands for infection constant, the influenza infection rate is represented by ϕ , the COVID infection rate by η , and the co-infection rate by β . The model recovered individuals lose immunity is represent by r .

3. Mathematical Analysis of Deterministic model (1)

In this part of our work, we present the well posedness of the model, and feasible region where solution exist. Furthermore, the uniqueness and existence are discussed. The equilibrium points are calculated for the model, disease free as well as endemic equilibrium points of the deterministic model (1).

Lemma 1. *The deterministic model (1) have invariant manifold of plane $\mathcal{S} + \mathcal{E} + \mathcal{I}_f + \mathcal{I}_c + \mathcal{C} + \mathcal{V} + \mathcal{R} = \frac{b}{d_0}$, which exist in first quadrant.*

Proof. Sum all equation of the system (1), and let suppose \mathcal{M} represent the whole population of the community, then we have $\mathcal{M} = \mathcal{S} + \mathcal{E} + \mathcal{I}_f + \mathcal{I}_c + \mathcal{V} + \mathcal{R} + \mathcal{C}$, which can be calculated as,

$$\begin{aligned} \frac{dM}{dt} &= b - d_0\mathcal{S} - d_0\mathcal{E} - d_0\mathcal{I}_f - d_0\mathcal{I}_c - d_0\mathcal{C} - d_0\mathcal{V} - d_0\mathcal{R} \\ &= b - d_0(\mathcal{S} + \mathcal{E} + \mathcal{I}_f + \mathcal{I}_c + \mathcal{C} + \mathcal{V} + \mathcal{R}). \end{aligned}$$

By simple calculation, we get

$$\frac{dM}{dt} = b - d_0M \quad (2)$$

Hence, the solution $\mathcal{M} = \frac{b}{d_0}$, is obtained from (2)
Also, the general solution for $M(t_0) \geq 0$ of (2) is

$$\mathcal{M} = \frac{1}{d_0} [b - (b - d_0M(t_0))e^{-d_0(t-t_0)}].$$

Thus

$$\lim_{t \rightarrow \infty} \mathcal{M} = \frac{b}{d_0}.$$

Hence, the proof is complete.

This above result shows that the system (1) is mathematically well-posed. The possible region where solution lies is the following,

$$\Phi = (\mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C}) : 0 \leq \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C}, \mathcal{S} + \mathcal{E} + \mathcal{I}_f + \mathcal{I}_c + \mathcal{V} + \mathcal{R} + \mathcal{C} \leq \frac{b}{d_0}.$$

3.1. Existence and Uniqueness of Deterministic model (1)

We search for the existence and uniqueness of the system (1). To do this, we supply the model (1) in the way that is dictated by

$$\begin{aligned}
 \mathcal{S}' &= f_1(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},), \\
 \mathcal{E}' &= f_2(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},), \\
 \mathcal{I}_f' &= f_3(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},), \\
 \mathcal{I}_c' &= f_4(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},), \\
 \mathcal{V}' &= f_5(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},), \\
 \mathcal{R}' &= f_6(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},), \\
 \mathcal{C}' &= f_7(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{C}, \mathcal{V}, \mathcal{R},).
 \end{aligned} \tag{3}$$

Norm is define as

$$\|\chi\|_\infty = \sup_{t \in x} \tag{4}$$

Let for some positive constant $h_1, h_2, h_3, h_4, h_5, h_6$ and h_7 , where $t \in [0, \mathcal{T}]$, we assume that the each compartment of deterministic model (1) is bounded in $[0, \mathcal{T}]$

$$\|\mathcal{S}\|_\infty < h_1,$$

$$\|\mathcal{E}\|_\infty < h_2,$$

$$\|\mathcal{I}_f\|_\infty < h_3,$$

$$\|\mathcal{I}_c\|_\infty < h_4,$$

$$\|\mathcal{V}\|_\infty < h_5,$$

$$\|\mathcal{R}\|_\infty < h_6,$$

$$\|\mathcal{C}\|_\infty < h_7,$$

and

$$k = h_1 + h_2.$$

To investigated the bondness of model 1, we have

$$\begin{aligned}
 |g_1(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |b - K\mathcal{S}\mathcal{I}(\beta\mathcal{I} + 1) - d_0\mathcal{S} + r\mathcal{R}|, \\
 &\leq b + |\mathcal{S}K\mathcal{I}|(\beta|\mathcal{I}| + 1) + d_0|\mathcal{S}| + r|\mathcal{R}|, \\
 &\leq b + \sup_X |\mathcal{S}K \sup_X |\mathcal{I}|(\beta \sup_X |\mathcal{I}| + 1) + d_0 \sup_X |\mathcal{S}| + r \sup_X |\mathcal{R}|, \tag{5} \\
 &\leq b + \|\mathcal{S}\|_\infty K \|\mathcal{I}\|_\infty (\beta \|\mathcal{I}\|_\infty + 1) + d_0 \|\mathcal{S}\|_\infty + r \|\mathcal{R}\|_\infty, \\
 &\leq b + h_1 K k (\beta k + 1) + d_0 h_1 + r h_6 < \infty.
 \end{aligned}$$

Where M is equal to t , and belong to $[0, \mathcal{T}]$. Using the same procedure, we have

$$\begin{aligned}
 |g_2(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |K\mathcal{S}\mathcal{I}(\beta\mathcal{I} + 1) - (d_0 + \eta + \phi)\mathcal{E}|, \\
 &\leq Kh_1k(\beta k + 1) + (d_0 + \eta + \phi)h_2 < \infty.
 \end{aligned}
 \tag{6}$$

$$\begin{aligned}
 |g_3(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |\phi\mathcal{E} - (\gamma_1 + v_f + d_0 + c_1)\mathcal{I}_f|, \\
 &\leq \phi h_2 + (\gamma_1 + v_f + d_0 + c_1)h_3 < \infty.
 \end{aligned}
 \tag{7}$$

$$\begin{aligned}
 |g_4(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |\eta\mathcal{E} - (\gamma_2 + v_c + d_0 + c_2)\mathcal{I}_c|, \\
 &\leq \eta h_2 + (\gamma_2 + v_c + d_0 + c_2)h_4 < \infty.
 \end{aligned}
 \tag{8}$$

$$\begin{aligned}
 |g_5(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |v_f\mathcal{I}_f + v_c\mathcal{I}_c - \gamma_3\mathcal{V}|, \\
 &\leq v_f h_3 + v_c h_4 + \gamma_3 h_5 < \infty.
 \end{aligned}
 \tag{9}$$

$$\begin{aligned}
 |g_6(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |\gamma_1\mathcal{I}_f + \gamma_2\mathcal{I}_c + \gamma_3\mathcal{V} - (r + d_0)\mathcal{R}|, \\
 &\leq \gamma_1 h_3 + \gamma_2 h_4 + \gamma_3 h_5 + (r + d_0)h_6 < \infty.
 \end{aligned}
 \tag{10}$$

$$\begin{aligned}
 |g_7(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &= |c_1\mathcal{I}_f + c_2\mathcal{I}_c|, \\
 &\leq c_1 h_3 + c_2 h_4 < \infty.
 \end{aligned}
 \tag{11}$$

Thus $\mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}$ and \mathcal{C} all are bounded in the given region, and there exist h_1, h_2, h_3, h_4, h_5 and h_6 such that

$$\begin{aligned}
 \sup_X |g_1(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_1, \\
 \sup_X |g_2(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_2, \\
 \sup_X |g_3(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_3, \\
 \sup_X |g_4(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_4, \\
 \sup_X |g_5(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_5, \\
 \sup_X |g_6(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_6, \\
 \sup_X |g_7(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< h_7.
 \end{aligned}$$

Now, we are going to prove that,

$$\begin{aligned}
 &|g_1(t, \mathcal{S}_2, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C}) - g_1(t, \mathcal{S}_1, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| = \\
 &|b - K\mathcal{S}_2\mathcal{I}(\beta\mathcal{I} + 1) - d_0\mathcal{S}_2 + r\mathcal{R} - (b - K\mathcal{S}_1\mathcal{I}(\beta\mathcal{I} + 1) - d_0\mathcal{S}_1 + r\mathcal{R})| \\
 &< (K\mathcal{I}(\beta\mathcal{I} + 1) + d_0)|\mathcal{S}_2 - \mathcal{S}_1| \\
 &< p_1|\mathcal{S}_2 - \mathcal{S}_1|.
 \end{aligned}
 \tag{12}$$

Where $p_1 = (K\mathcal{I}(\beta\mathcal{I} + 1) + d_0)$. Follow the similar method, we get

$$\begin{aligned} |g_2(t, \mathcal{S}, \mathcal{E}_2, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C}) - g_2(t, \mathcal{S}, \mathcal{E}_1, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< p_2|\mathcal{E}_2 - \mathcal{E}_1|, \\ |g_3(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_{g_2}, \mathcal{I}_1, \mathcal{V}, \mathcal{R}, \mathcal{C}) - f_3(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_{g_1}, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< p_3|\mathcal{I}_{g_2} - \mathcal{I}_{g_1}|, \\ |g_4(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_{c_2}, \mathcal{V}, \mathcal{R}, \mathcal{C}) - f_4(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_{c_1}, \mathcal{V}, \mathcal{R}, \mathcal{C})| &< p_4|\mathcal{I}_{c_2} - \mathcal{I}_{c_1}|, \\ |g_5(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C}_2) - f_5(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}, \mathcal{C}_1)| &< p_5|\mathcal{C}_2 - \mathcal{C}_1|, \\ |g_6(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}_2, \mathcal{R}, \mathcal{C}) - f_6(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}_2, \mathcal{R}, \mathcal{C})| &< p_6|\mathcal{V}_2 - \mathcal{V}_1|, \\ |g_7(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}_2, \mathcal{C}) - f_7(t, \mathcal{S}, \mathcal{E}, \mathcal{I}_f, \mathcal{I}_c, \mathcal{V}, \mathcal{R}_1, \mathcal{C})| &< p_7|\mathcal{R}_2 - \mathcal{R}_1|. \end{aligned}$$

Where

$$\begin{aligned} p_2 &= d_0 + \phi + \eta, \\ p_3 &= \gamma_1 + v_f + d_0 + c_1, \\ p_4 &= \gamma_2 + v_c + d_0 + c_2, \\ p_5 &= d_0 + v_3 \\ p_6 &= \gamma_3 + d_0, \\ p_7 &= r + d_0. \end{aligned}$$

This uniqueness and existence show that the system (1) has a unique set of solutions.

3.2. Disease Free Equilibrium Points DFEP:

\mathcal{P}^0 represent the DFEP of model (1), which is equal to $(\mathcal{S}^0, 0, 0, 0, 0, 0, 0)$. May be write in the following form,

$$\mathcal{P}^0 = \left(\frac{b}{d_0}, 0, 0, 0, 0, 0, 0 \right).$$

3.3. Endemic Equilibrium points EEP

We obtained EEP for our model (1) as

$$\begin{aligned}
 \mathcal{S}^* &= \frac{b(r + d_0) + r [(\gamma_1 + v_f)\mathcal{I}_f^* + (\gamma_2 + v_c)\mathcal{I}_c^*]}{(r + d_0)(K\mathcal{I}^*(\beta\mathcal{I}^* + 1) + d_0)}, \\
 \mathcal{E}^* &= \frac{K\mathcal{I}^*(\beta\mathcal{I}^* + 1)(b(r + d_0) + r[(\gamma_1 + v_f)\mathcal{I}_f^* + (\gamma_2 + v_c)\mathcal{I}_c^*])}{(r + d_0)(d_0 + \phi + \eta)}, \\
 \mathcal{I}_f^* &= \frac{\phi K\mathcal{I}^*(\beta\mathcal{I}^* + 1)(b(r + d_0) + r[(\gamma_1 + v_f)\mathcal{I}_f^* + (\gamma_2 + v_c)\mathcal{I}_c^*])}{(r + d_0)(d_0 + \phi + \eta)(\gamma_1 + v_f + d_0 + c_1)}, \\
 \mathcal{I}_c^* &= \frac{\eta K\mathcal{I}^*(\beta\mathcal{I}^* + 1)(b(r + d_0) + r[(\gamma_1 + v_f)\mathcal{I}_f^* + (\gamma_2 + v_c)\mathcal{I}_c^*])}{(r + d_0)(d_0 + \phi + \eta)(\gamma_2 + v_c + d_0 + c_2)}, \\
 \mathcal{V}^* &= \frac{v_f\mathcal{I}_f^* + v_c\mathcal{I}_c^*}{\gamma_3}, \\
 \mathcal{R}^* &= \frac{(\gamma_1 + v_f)\mathcal{I}_f^* + (\gamma_2 + v_c)\mathcal{I}_c^*}{r + d_0}.
 \end{aligned} \tag{13}$$

3.4. Basic Reproduction number \mathbb{R}_0

In epidemiology, the term \mathbb{R}_0 , or basic reproduction number, refers to the way in which infections are controlled and propagated. Information regarding the disease’s prevalence in the community and the best ways to protect the local people from the deadly virus are provided by \mathbb{R}_0 . We utilize the next generation matrix notion to determine \mathbb{R}_0 .

Let $\Phi = (\mathcal{E}, \mathcal{I}_f, \mathcal{I}_c)$, then from system (1), we have

$$\frac{d\Phi}{dt} = \mathcal{X} - \mathcal{Y},$$

such that,

$$\mathcal{X} = \begin{pmatrix} K\mathcal{S}\mathcal{I}(\beta\mathcal{I} + 1) \\ 0 \\ 0 \end{pmatrix}$$

and

$$\mathcal{Y} = \begin{pmatrix} (d_0 + \eta + \phi)\mathcal{E} \\ -\phi\mathcal{E} + (\gamma_1 + v_f + d_0 + c_1)\mathcal{I}_f \\ -\eta\mathcal{E} + (\gamma_2 + v_c + d_0 + c_2)\mathcal{I}_c \end{pmatrix}.$$

At DFEP the Jacobian of \mathcal{X} is, we have

$$\mathcal{X} = \begin{pmatrix} 0 & k\mathcal{S}^0 & k\mathcal{S}^0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

where at DFEP the Jacobian of \mathcal{X} is, we have

$$\mathcal{Y} = \begin{pmatrix} (d_0 + \eta + \phi) & 0 & 0 \\ -\phi & \gamma_1 + v_f + d_0 + c_1 & 0 \\ -\eta & 0 & \gamma_2 + v_c + d_0 + c_2 \end{pmatrix}.$$

$$\mathcal{X}\mathcal{Y}^{-1} = \frac{\begin{pmatrix} 0 & K\mathcal{S}^0 & K\mathcal{S}^0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} q(\gamma_1 + v_f + d_0 + c_1) & 0 & 0 \\ \phi(\gamma_2 + v_c + d_0 + c_2) & q(\gamma_2 + v_c + d_0 + c_2) & 0 \\ \eta(\gamma_1 + v_f + d_0 + c_1) & 0 & q(\gamma_1 + v_f + d_0 + c_1) \end{pmatrix}}{(q(\gamma_1 + v_f + d_0 + c_1)(\gamma_2 + v_c + d_0 + c_2))}.$$

Assume that $q = d_0 + \eta + \phi$, where $\mathcal{X}\mathcal{Y}^{-1}$ have the following positive radius, which is known as reproduction rate of influenza and covid respectively,

$$\mathbb{R}_{01} = \frac{Kb}{d_0(d_0 + \phi + \eta)(\gamma_1 + v_f + d_0 + c_1)}$$

$$\mathbb{R}_{02} = \frac{Kb\phi}{d_0(d_0 + \phi + \eta)(\gamma_2 + v_c + d_0 + c_2)}.$$

May some one consider as,

$$\mathbb{R}_0 = \max [\mathbb{R}_{01}, \mathbb{R}_{02}]. \tag{14}$$

4. Stability Analysis

In this part of the manuscript consist of stability analysis of the deterministic model (1). Actually, we check here local and global stability of the system at disease free and endemic equilibrium points.

4.1. Local Stability

Local stability analysis is investigate though applying the Jacobian matrix of the deterministic model (1. As in the next theorem, we get condition under which the system is locally asymptotically stable.

Theorem 1. *When effective basic reproduction number $\mathbb{R}_{01} < 1$ or $\mathbb{R}_{02} < 1$, the DFEP “ \mathcal{P} ” is stable locally asymptotically. ”*

Proof. At disease free equilibrium state $\mathcal{P}^0 = \left(\frac{b}{d_0}, 0, 0, 0, 0, 0\right)$ the Jacobian matrix of deterministic model (1 as,

$$\mathcal{T}^0 = \begin{bmatrix} -d_0 & 0 & 0 & 0 & 0 & 0 & 0 & r \\ 0 & -(d_0 + \phi + \eta) & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \phi & -(\gamma_1 + v_f + d_0 + c_1) & 0 & 0 & 0 & 0 & 0 \\ 0 & \eta & 0 & -(\gamma_2 + v_c + d_0 + c_2) & 0 & 0 & 0 & 0 \\ 0 & 0 & c_1 & c_2 & 0 & 0 & 0 & 0 \\ 0 & 0 & v_f & v_c & -\gamma_3 & 0 & 0 & 0 \\ 0 & 0 & \gamma_1 & \gamma_2 & \gamma_3 & -(r - d_0) & 0 & 0 \end{bmatrix}$$

and

$$|\chi - \mathcal{T}^0(\mathcal{P})| = 0.$$

Hence

$$\begin{aligned}\chi_1 &= -d_0, \\ \chi_2 &= -(d_0 + \phi + \eta), \\ \chi_3 &= -(\gamma_2 + v_c + d_0 + c_2), \\ \chi_4 &= -(\gamma_1 + v_f + d_0 + c_1), \\ \chi_5 &= -(r + d_0), \\ \chi_6 &= (\gamma_2 + v_c + d_0 + c_2)(\mathbb{R}_{01} - 1), \\ \chi_7 &= (\gamma_1 + v_f + d_0 + c_1)(\mathbb{R}_{02} - 1).\end{aligned}$$

From last two equation, we see that χ_6 is negative whenever $\mathbb{R}_{01} < 1$, χ_7 has condition $\mathbb{R}_{02} < 1$, and the rest are also strictly negative which follow the conclusion.

4.2. Global Stability

Global stability of the deterministic model is highlight through a function “ \mathcal{F} ”, known is Laypaunov function. By using [25] at disease free equilibrium sate “ \mathcal{P} ”, we investigate the stability analysis in next theorem.

Theorem 2. *When effective basic reproduction number $\mathbb{R}_{01} < 1$ or $\mathbb{R}_{02} < 1$, the DFEP “ \mathcal{P} ” is globally asymptotically stable.”*

Proof. Let define the Laypaunov function \mathcal{F} as,

$$\mathcal{F} = h_1 \mathcal{I}_f + h_2 \mathcal{I}_c, \quad (15)$$

where h_1 and h_2 are some positive constants. Since $\mathcal{I}_f, \mathcal{I}_c > 0$, then \mathcal{F} . Also whenever $\mathcal{I}_f = \mathcal{I}_c = 0$ then $\mathcal{F} = 0$. We need to show that $\dot{\mathcal{F}} < 0$, for this follow Now, our goal is $\dot{\mathcal{F}} < 0$.

$$\frac{d\mathcal{F}}{dt} = h_1 \frac{d\mathcal{I}_f}{dt} + h_2 \frac{d\mathcal{I}_c}{dt}. \quad (16)$$

Putting values of \mathcal{I}_f and \mathcal{I}_c from (1) in (16), we get

$$\frac{d\mathcal{F}}{dt} = h_1 (\phi \mathcal{E} - (\gamma_1 + v_f + d_0 + c_1) \mathcal{I}_f) + h_2 (\eta \mathcal{E} - (\gamma_2 + v_c + d_0 + c_2) \mathcal{I}_c). \quad (17)$$

Where

$$h_1 = \frac{kb}{d_0(d_0 + \phi + \eta)}$$

also same as

$$h_2 = \frac{kb}{d_0(d_0 + \phi + \eta)}$$

. From (17), we have

$$\frac{d\mathcal{F}}{dt} = (\mathbb{R}_{01} - 1)(\gamma_1 + d_0 + v_f + c_1)\mathcal{I}_f + (\mathbb{R}_{02} - 1)(\gamma_2 + d_0 + v_c + c_2)\mathcal{I}_c. \quad (18)$$

From the principle of “LaSalle’s invariant”, $\frac{d\mathcal{F}}{dt}$ is equal to zero whenever $\mathcal{I}_f = \mathcal{I}_c = 0$. Also, we see that if $\mathbb{R}_{01} < 1$ and $\mathbb{R}_{02} < 1$, then $\frac{d\mathcal{F}}{dt}$ must be less than zero, which follows the conclusion.

5. Sensitivity Analysis of the Deterministic Model (1)

In order to account for the factors that significantly affect the basic reproduction number \mathbb{R}_0 , we present the sensitivity analysis in this section. To figure out the significance of the many factors influencing the incidence and spread of disease, sensitivity analysis is advised. Controlling the system (1) variables is essential to achieving $\mathbb{R}_{01} < 1$ or $\mathbb{R}_{02} < 1$, in addition to to prevent the spread of illnesses. The formula can be used to determine the sensitivity index, which represents the proportion of changes in a variable to a parameter’s change. In the following 1, we present the sensitivity index of each parameters, involve in the basic reproduction numbers $\mathbb{R}_{01} < 1$. The formula used for determining the the sensitivity index is

$$h[y] = \frac{X}{\mathbb{R}_0} \frac{\partial \mathbb{R}_0}{\partial X}$$

, where X mean parameter of \mathbb{R}_0 .

Parameters	Sensitivity Index
$h(b)$	1
$h(K)$	1
$h(d_0)$	-0.81
$h(\phi)$	0.69
$h(\eta)$	-0.21
$h(\gamma_1)$	-0.78
$h(\gamma_2)$	-0.50
$h(c_1)$	-0.78
$h(c_2)$	-0.13
$h(v_f)$	-0.78
$h(v_c)$	-0.67

Table 1: \mathbb{R}_{01} and \mathbb{R}_{02} sensitivity index relative to system (1) variables.)

It is clear from Table (1) and Fig. (2) that the variables of birth rate b, constant of infection and influenza infection rate are positive so there increase while effect increasing in the value of \mathbb{R}_{01} and \mathbb{R}_{02} . On the other hand, the values of d_0 , η , ϕ , γ_1 , γ_2 , c_1 , c_2 , v_f , and v_c are negative so their increased which follow decrease in \mathbb{R}_{01} and \mathbb{R}_{02} .

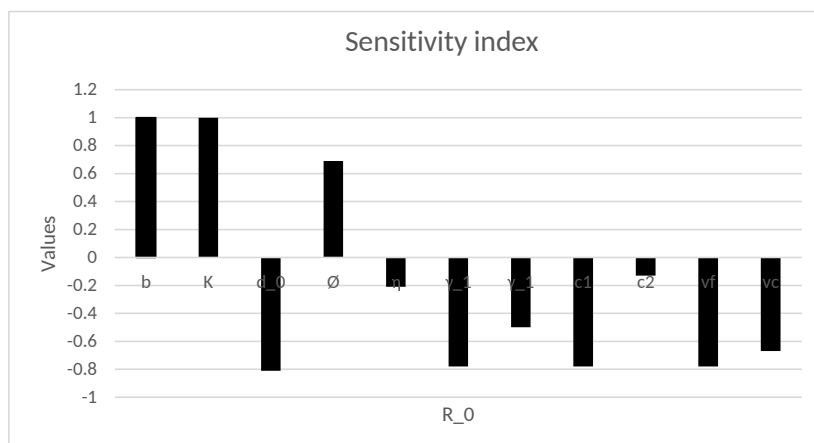


Figure 2: \mathbb{R}_{01} and \mathbb{R}_{02} sensitivity index relative to system (1) variables.

6. Numerical simulation through NSFD of deterministic model

By using non-standard finite difference scheme (NSFD) [28, 29], we plot the numerical simulation of the deterministic model (1) in this section. First, the model equations are written in the following way, as consider the first equation of model (1),

$$\frac{dS}{dt} = b - KSI(\beta I + 1) - d_0S + rR. \tag{19}$$

From the non-standard finite difference method, we decomposed as

$$\frac{S_{j+1} - S_j}{h} = b - KS_jI_j(\beta I_j + 1) - d_0S_j + rR_j. \tag{20}$$

Like (20), we decomposed other equations of model (1) by using none-standard finite difference method

$$\begin{aligned} \mathcal{E}_{j+1} &= \mathcal{E}_j + h \left(KS_jI_j(\beta I_j + 1) - (d_0 + \eta + \phi)\mathcal{E}_j \right), \\ \mathcal{I}_{f(j+1)} &= \mathcal{I}_{1(j)} + h \left(\phi\mathcal{E}_j - (\gamma_1 + d_0 + v_f + c_1)\mathcal{I}_{1j} \right), \\ \mathcal{I}_{c(j+1)} &= \mathcal{I}_{2(j)} + h \left(\eta\mathcal{E}_j - (\gamma_2 + v_c + d_0 + c_2)\mathcal{I}_{2j} \right), \\ \mathcal{V}_{j+1} &= \mathcal{V}_j + h \left(v_f\mathcal{I}_{1j} + v_c\mathcal{I}_{2j} + v_3\mathcal{C}_j - \gamma_3\mathcal{V}_j \right), \\ \mathcal{R}_{j+1} &= \mathcal{R}_j + h \left(\gamma_1\mathcal{I}_{1j} + \gamma_2\mathcal{I}_{2j} + \gamma_3\mathcal{V}_j - (r + d_0)\mathcal{R}_j \right), \\ \mathcal{C}_{j+1} &= \mathcal{C}_j + h \left(c_1\mathcal{I}_{1j} + c_2\mathcal{I}_{2j} - (v_3 + d_0)\mathcal{C}_j \right). \end{aligned}$$

Variable	numerical values	Variable	numerical
\mathcal{S}	0.4540197 Million	ϕ	0.12
\mathcal{E}	0.0030000 Million	γ_1	0.015
\mathcal{I}_f	0.0001455 Million	γ_2	0.0667
\mathcal{I}_c	0.1428015 Million	c_1	0.1
\mathcal{V}	0.0141480 Million	c_2	0.005
\mathcal{R}	0.2700000 Million	η	0.3425
\mathcal{C}	0.0170000 Million	b	0.002500
d_0	0.01	β	0.12
K	0.1175	r	0.000167
v_f	0.003	v_c	0.0015
γ_3	0.036		

Table 2: The parameters of the system are described and specified, with approximate real values (1).

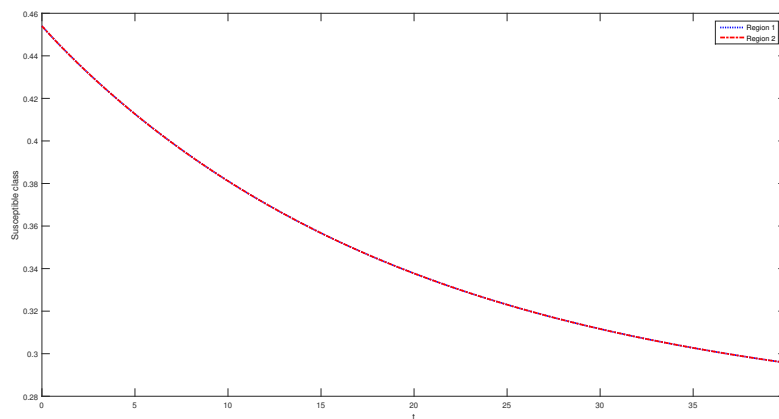


Figure 3: Graph of numerical solutions using the NSFD technique for the deterministic model (1) susceptible compartment.

By using NSFD scheme, we simulate the system (1) utilizing the numerical values listed in the 2 taking the values from [4].

It is apparent in Fig.3 to Fig.9, the findings that the recovered populations grow slowly and eventually stable at the top, while the susceptible and exposed populations progressively decline toward zero throughout the first 50 days, by using a Table.2 and graph the numerical data using the NSFD method. As predicted, the covid-19 infected and influenza infected populations steadily declines after one week. Initially co-infected populations increased significantly in first two week, but after two week it start decline and become stable in 50 days. Also, when infection decreased the vaccinated individuals and recovered become stabilize. These findings support Theorem 3.1, which states that the disease dies out whenever the basic reproduction number less then 1. Additionally, it indicates that the SARS-Cov-2 virus will be eliminate from the population in 50 days.

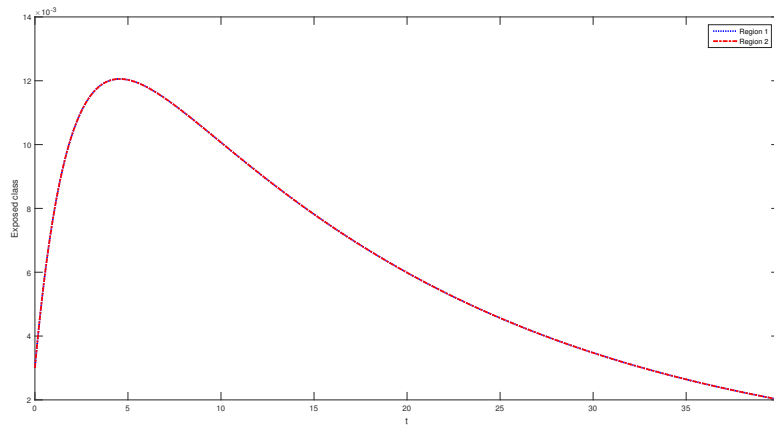


Figure 4: Graph of numerical solutions using the NSFD technique for the deterministic model (1) exposed compartment.

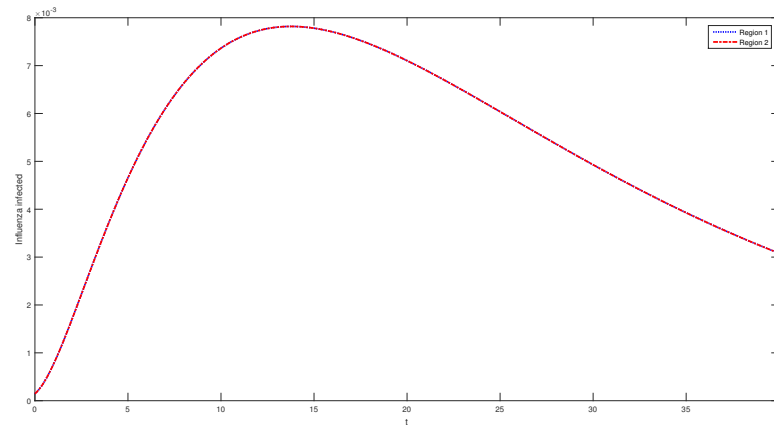


Figure 5: Graph of numerical solutions using the NSFD technique for the deterministic model (1) influenza infected compartment.

7. Stochastic model

Here, we introduce the influence of environmental white noise to transform the previously proposed deterministic system (1) into a stochastic model. We accomplish this by introducing nonlinear perturbations into each of the system’s equations, in this case merely the rate of each class, as illustrated for each class below.

$$\begin{aligned}
 \mathcal{S}(t) : -\beta &\longrightarrow -\beta + (\chi_{11}S + \chi_{12})d\mathbb{A}_1(t), \\
 \mathcal{E}(t) : -\phi &\longrightarrow -\phi + (\Pi_{21}S + \chi_{22})d\mathbb{A}_2(t), \\
 \mathcal{I}_f(t) : -c_1 &\longrightarrow -c_1 + (\chi_{31}S + \chi_{32})d\mathbb{A}_3(t),
 \end{aligned}$$

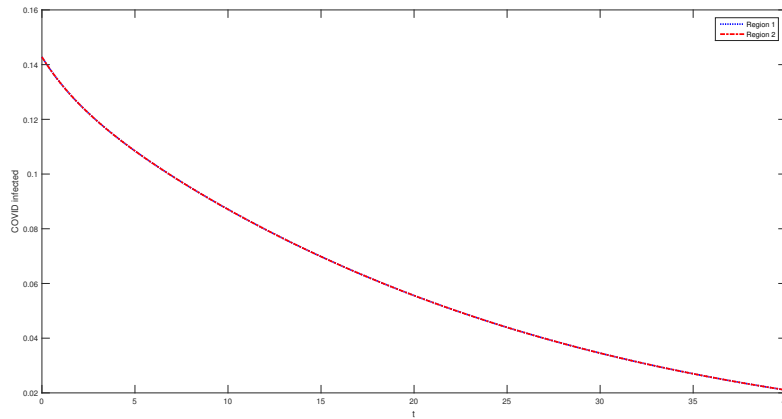


Figure 6: Graph of numerical solutions using the NSFD technique for the deterministic model COVID (1) infected compartment.

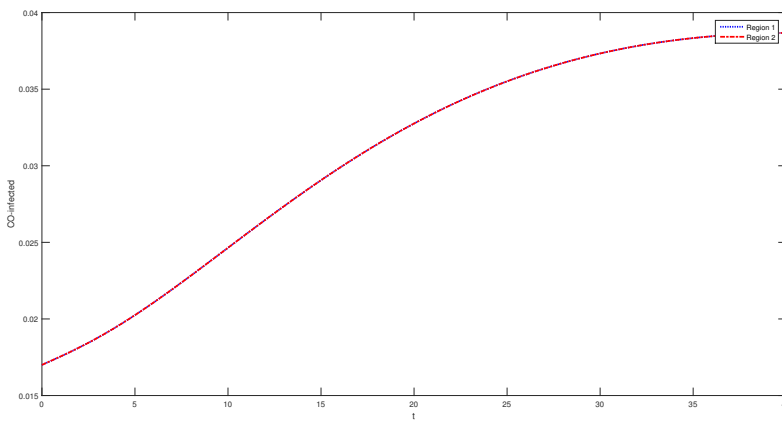


Figure 7: Graph of numerical solutions using the NSFD technique for the deterministic model (1) co-infection compartment.

$$\begin{aligned}
 \mathcal{I}_c(t) &: -c_2 \longrightarrow -c_2 + (\chi_{41}S + \chi_{42})d\mathbb{A}_4(t), \\
 \mathcal{C}(t) &: -v_3 \longrightarrow -v_3 + (\chi_{51}S + \chi_{52})d\mathbb{A}_5(t), \\
 \mathcal{V}(t) &: \gamma_3 \longrightarrow -\gamma_3 + (\chi_{61}S + \chi_{62})d\mathbb{A}_6(t), \\
 R(t) &: -d_0 \longrightarrow -d_0 + (\chi_{71}S + \chi_{72})d\mathbb{A}_7(t).
 \end{aligned}$$

The modified stochastic model (1) is thus represented by the system of equations that follows:

$$\begin{aligned}
 dS &= [b - KSI(\beta I + 1) - d_0S + r\mathcal{R}]dt + (\chi_{11}S + \chi_{12})\mathbb{A}_1(t), \\
 d\mathcal{E} &= [KSI(\beta I + 1) - (d_0 + \eta + \phi)\mathcal{E}]dt + (\chi_{21}S + \chi_{22})\mathbb{A}_2(t),
 \end{aligned}$$

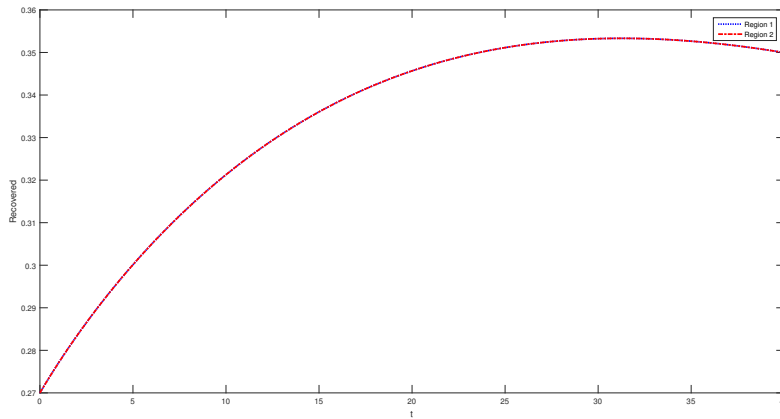


Figure 8: Graph of numerical solutions using the NSFD technique for the deterministic model (1). recovered compartment

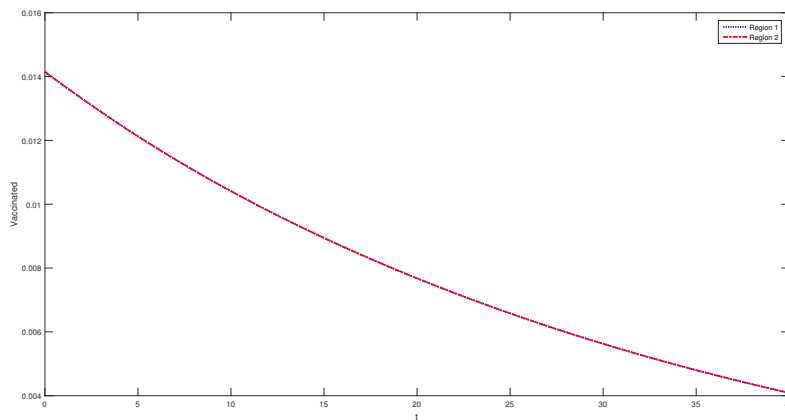


Figure 9: Graph of numerical solutions using the NSFD technique for the deterministic model (1) vaccinated compartment.

$$\begin{aligned}
 d\mathcal{I}_f &= [\phi\mathcal{E} - (\gamma_1 + v_f + d_0 + c_1)\mathcal{I}_f]dt + (\chi_{31}S + \chi_{32})\mathbb{A}_3(t), \\
 d\mathcal{I}_c &= [\eta\mathcal{E} - (\gamma_2 + v_c + d_0 + c_2)\mathcal{I}_c]dt + (\chi_{41}S + \chi_{42})\mathbb{A}_4(t), \\
 d\mathcal{C} &= [c_1\mathcal{I}_f + c_2\mathcal{I}_c - (d_0 + v_3)\mathcal{C}]dt + (\chi_{51}S + \chi_{52})\mathbb{A}_5(t), \\
 d\mathcal{V} &= [v_f\mathcal{I}_f + v_c\mathcal{I}_c + v_3\mathcal{C} - (\gamma_3 + d_0)\mathcal{V}]dt + (\chi_{61}S + \chi_{62})\mathbb{A}_6(t), \\
 d\mathcal{R} &= [\gamma_1\mathcal{I}_f + \gamma_2\mathcal{I}_c + \gamma_3\mathcal{V} - (r + d_0)\mathcal{R}]dt + (\chi_{71}S + \chi_{72})\mathbb{A}_7(t).
 \end{aligned}$$

8. Numerical simulation of stochastic model

The following equation is used to determine the trajectories or estimated solutions of a stochastic model equations using the Euler-Maruyama method:

$$\chi_{t_{i+1}} = \chi_{t_i} + \alpha(t_i, \chi_{t_i}) + \beta(t_i, \chi_{t_i})\Delta A_i. \tag{21}$$

Where $i = 0, 1, \dots, n - 1$. It is required to understand how to compute ΔA_i in order to implement the procedure computationally. The distribution of the differences ΔA_i , $i = 0, 1, \dots, n - 1$ has the same value, $\Delta A_i \sim M(0, \Delta t)$, because the partition is composed of equal intervals. Consider a random variable η which has a normal $\eta \sim M(0, 1)$. Then $\sqrt{\Delta t}\eta_1$ has zero mean and variance Δt , indicating a normal distribution; that is $\sqrt{\Delta t}\eta_1 \sim M(0, \Delta t)$. For our proposed model, to implement the Euler-Maruyama method algorithm similarly (21), we must perform the appropriate separating of the system of stochastic differential equations (21), which is given by

$$\begin{aligned} S_{t_{i+1}} &= S_{t_i} + [b - KSI(\beta I + 1) - d_0 S + rR] \Delta t + \sqrt{\Delta t}\eta_1, \\ E_{t_{i+1}} &= E_{t_i} + [KSI(\beta I + 1) - (d_0 + \eta + \phi)E] \Delta t + \sqrt{\Delta t}\eta_2, \\ I_{ft_{i+1}} &= I_{ft_i} + [\phi E - (\gamma_1 + v_f + d_0 + c_1)I_f] \Delta t + \sqrt{\Delta t}\eta_3, \\ I_{ct_{i+1}} &= I_{ct_i} + [\eta E - (\gamma_2 + v_c + d_0 + c_2)I_c] \Delta t + \sqrt{\Delta t}\eta_4, \\ C_{t_{i+1}} &= C_{t_i} + [c_1 I_f + c_2 I_c - (d_0 + v_3)C] \Delta t + \sqrt{\Delta t}\eta_5, \\ V_{t_{i+1}} &= V_{t_i} + [v_f I_f + v_c I_c + v_3 C - (\gamma_3 + d_0)V] \Delta t + \sqrt{\Delta t}\eta_6, \\ R_{t_{i+1}} &= R_{t_i} + [\gamma_1 I_f + \gamma_2 I_c + \gamma_3 V - (r + d_0)R] \Delta t + \sqrt{\Delta t}\eta_7. \end{aligned} \tag{22}$$

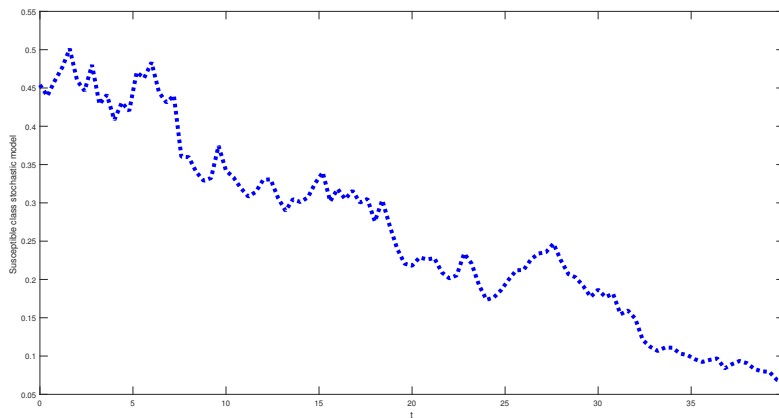


Figure 10: Graph of numerical solutions for the stochastic model (21) susceptible compartment by using Euler-Maruyama.

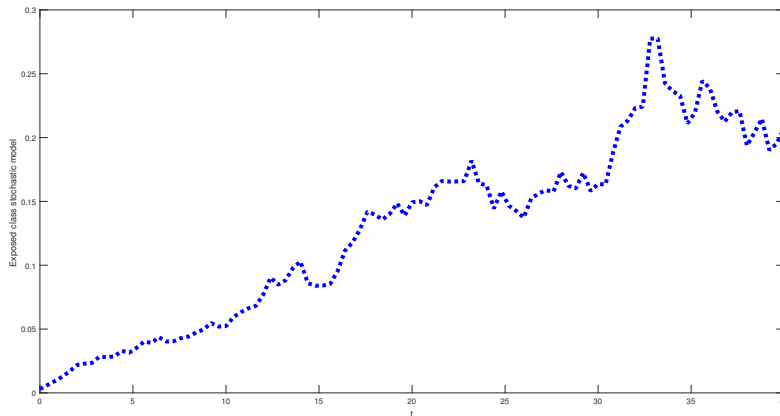


Figure 11: Graph of numerical solutions for the stochastic model (21) exposed compartment by using Euler-Maruyama..

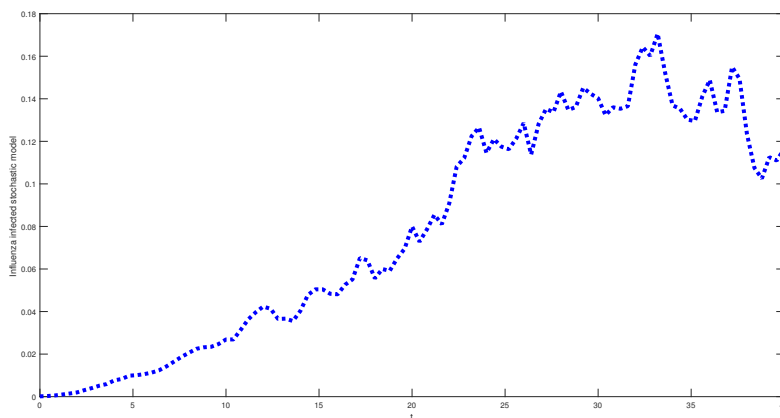


Figure 12: Graph of numerical solutions for the stochastic model (21) influenza compartment by using Euler-Maruyama.

Using the algorithm mentioned above and data from Table.2, we next apply the model and get the results in Fig.(10-16). This confirms the analytical result done in Theorems 5.1 and 5.2, as well as the effect of vaccination and the degree of white noise on the movement of the novel coronavirus disease. Mortality analysis clearly shows that, in the case that $\mathbb{R}_1^S < 1$, there will always be susceptible and recovered people and the infected individual disappears, as above plot illustrates. However, if $\mathbb{R}_1^S > 1$, there will still be sick individuals and the disease will continue, as mention above figures illustrates. Furthermore, Figs (15) illustrate how vaccination and the level of white noise affect the dynamics of the compartmental population. It is evident that immunization and the white noise degree variable are important factors in both situations. We found that the amount

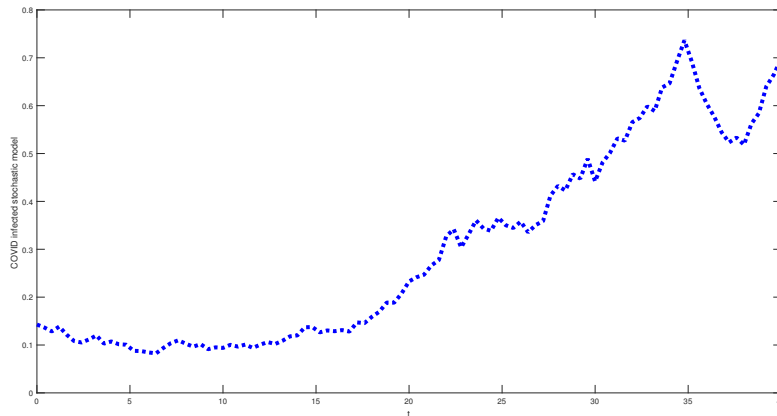


Figure 13: Graph of numerical solutions for the stochastic model (21) covid compartment by using Euler-Maruyama.

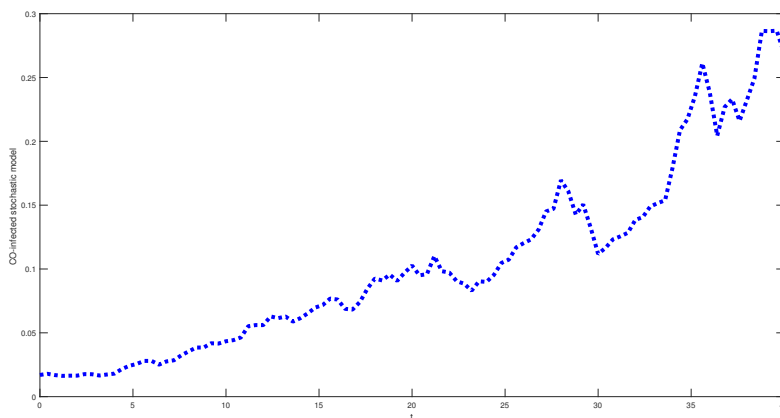


Figure 14: Graph of numerical solutions for the stochastic model (21) co-infected compartment by using Euler-Maruyama.

of white noise and vaccination had a significant impact on the spread of new coronavirus diseases. It should be highlighted that, as Figs. 6 and 7 demonstrate, increasing the values of these two parameters would accelerate the extinction of the disease. Consequently, as the values of v_f and v_c rise, the number of susceptible and infected individuals falls while the numbers of recovered population rises. Similarly, as shown in above figures, in the situation of disease persistence, v_f is directly proportional to the number of recovered individuals while inversely related to the amount of susceptible and infected individuals. However, v_f the parameter is directly related to the number of susceptible and infected persons and inversely proportional to the amount of infected individuals. To see the figures (17-23) the dynamics of the stochastic and deterministic follow real data, which

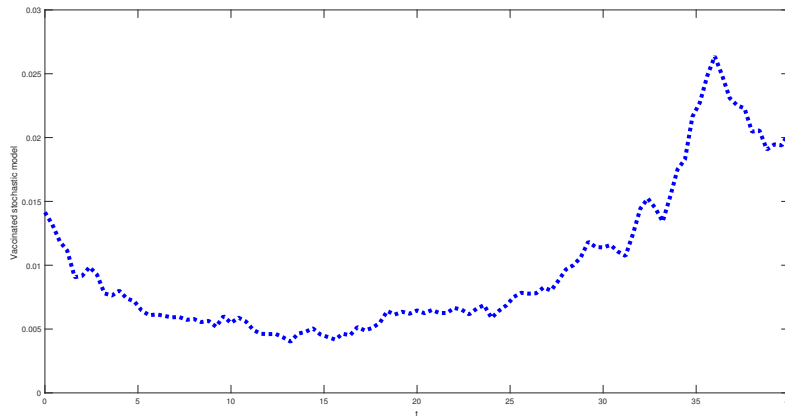


Figure 15: Graph of numerical solutions for the stochastic model (21) vaccination compartment by using Euler-Maruyama.

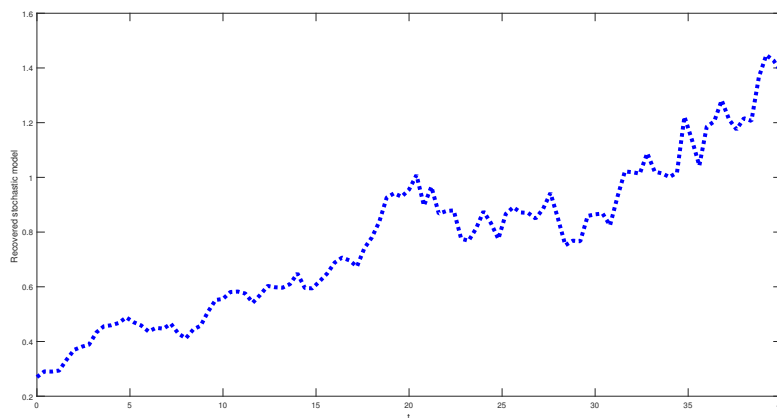


Figure 16: Graph of numerical solutions for the stochastic model (21) recovered compartment by using Euler-Maruyama.

show accuracy of our model.

9. Conclusion

Cases of co-infection with SARS-CoV-2 and influenza have been investigated in recent studies [30–34]. Mathematical models can provide valuable insights into the dynamics of mutual infection within a host. In this work, we developed and analyzed a system of differential equations (DDEs) and stochastic differential equations (SDEs) to characterize the progression of influenza and SARS-CoV-2 co-infection. We established the system’s fundamental properties, including boundedness and non-negativity. Furthermore, we identified

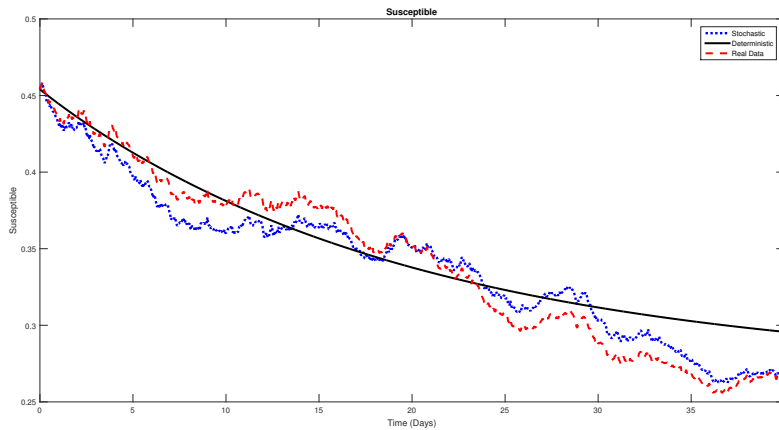


Figure 17: Comparison of susceptible compartment.

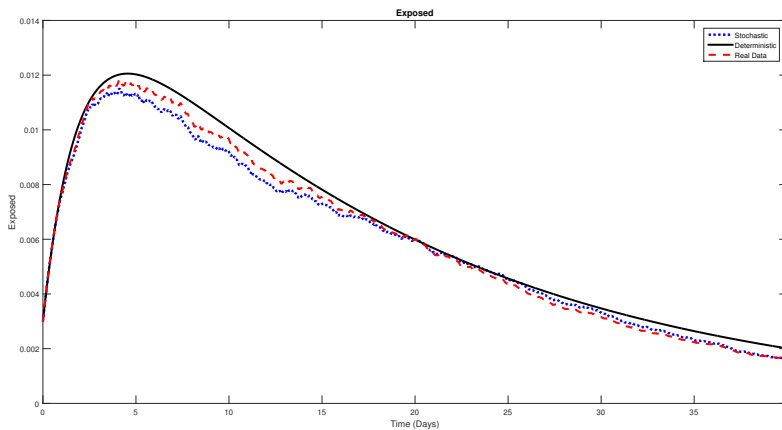


Figure 18: Comparison of exposed compartment.

the system’s equilibria and examined their existence and stability, locally and globally. Our numerical simulations were consistent with the theoretical results, reinforcing the validity of our analysis.

As part of future work, we aim to enhance our model by integrating neural networks and artificial intelligence (AI) techniques [35]. These tools will enable more accurate prediction, parameter estimation, and real-time adaptation of the model, ultimately advancing our understanding of co-infection dynamics and improving decision-making in public health interventions. **Declarations** All authors have read and approved the final manuscript.

Authors contributions

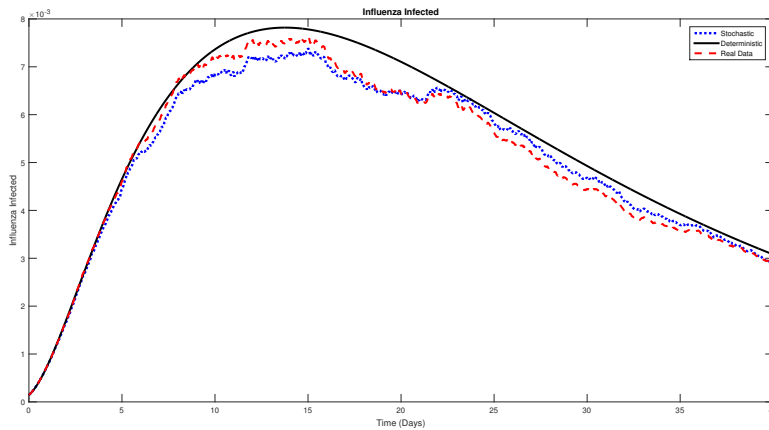


Figure 19: Comparison of influenza infected compartment.

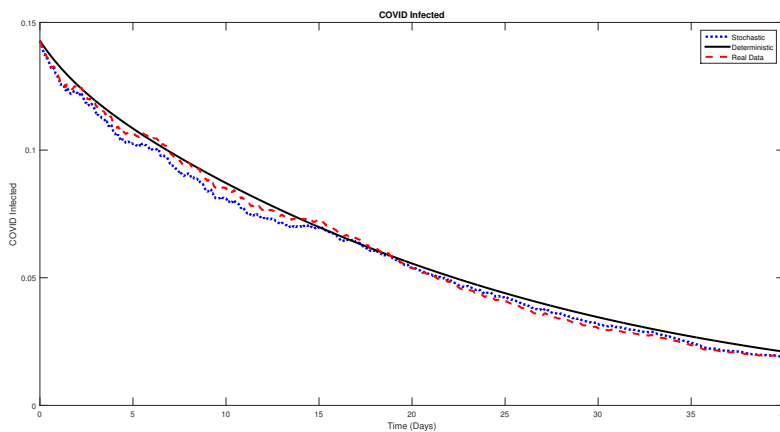


Figure 20: Comparison of COVID infected compartment.

Conceptualization: [Author A, Author B]
 Methodology: [Author A]
 Formal Analysis: [Author A]
 Investigation: [Author A, Author B]
 Data Correction: [Author B]
 Writing Original Draft: [Author A]
 Writing Review & Editing: [Author A, Author B,]
 Visualization: [Author B]
 Supervision: [Author B]
 Project Administration: [Author B]
 Funding Acquisition: [Author B]

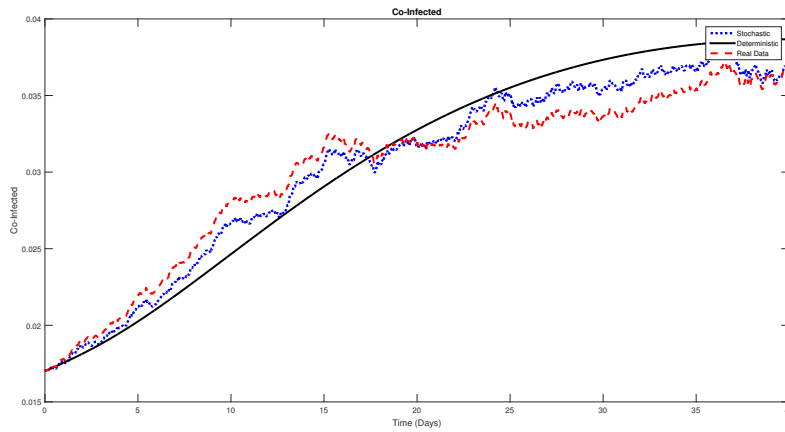


Figure 21: Comparison of co-infection compartment.

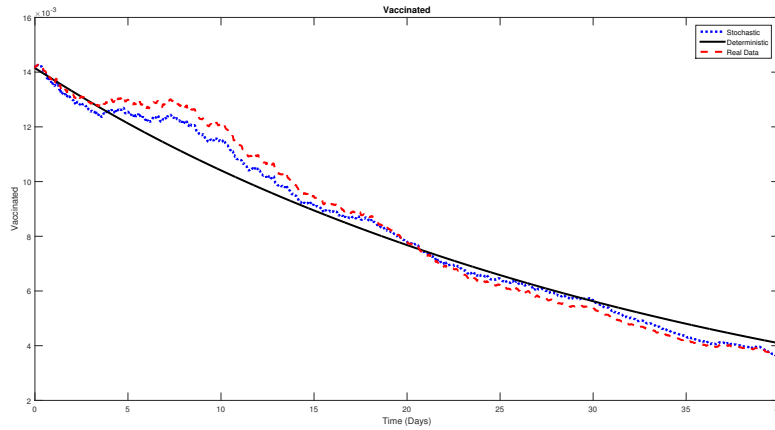


Figure 22: Comparison of vaccination compartment.

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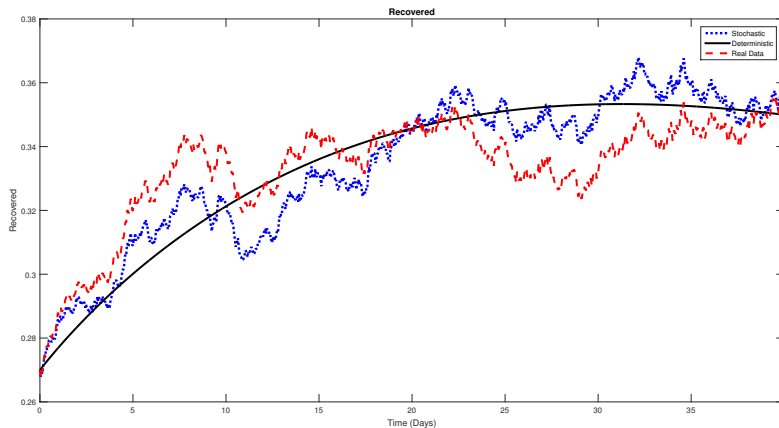


Figure 23: Comparison of recovered compartment.

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