EUROPEAN JOURNAL OF PURE AND APPLIED MATHEMATICS
Vol. 16, No. 3, 2023, 1552-1567
ISSN 1307-5543 - ejpam.com
Published by New York Business Global


# The Homotopy Perturbation Method for Solving Nonlocal Initial-Boundary Value Problems for Parabolic and Hyperbolic Partial Differential Equations 

Waleed Al-Hayani ${ }^{1, *}$, Mahasin Thabet Younis ${ }^{1}$<br>${ }^{1}$ Department of Mathematics, College of Computer Science and Mathematics, University of Mosul, Iraq


#### Abstract

To obtain approximate-exact solutions to nonlocal initial-boundary value problems (IBVPs) of linear and nonlinear parabolic and hyperbolic partial differential equations (PDEs) subject to initial and nonlocal boundary conditions of integral type, the homotopy perturbation method (HPM) is utilized in this study. The HPM is used to solve the specified nonlocal IBVPs, which are then transformed into local Dirichlet IBVPs. Some examples demonstrate how accurate and efficient the HPM.


2020 Mathematics Subject Classifications: 35-XX, 35K20, 35L04, 35L20
Key Words and Phrases: Nonlocal IBVPs, Parabolic PDEs, Hyperbolic PDEs, HPM, He's polynomials

## 1. Introduction

The transport equation, often known as the one-way wave equation, is an illustration of a first-order linear partial differential equation with constant coefficient:

$$
v_{\tau}-k v_{\xi}=0, \quad c \leq \xi \leq d, \quad \tau \geq 0
$$

in which $k$ is a fixed number that specifies constant-speed motion. We establish $v(\tau, \xi)$ at time $\tau$, which we set to 0 , i.e. $v(0, \xi)$ is equal to a specific function $v_{0}(\xi)$ on $c \leq \xi \leq d$, and the boundary conditions (BCs) known as the nonlocal BCs of integral type which connect the solution of the differential equation to data of the integral type $\int_{c}^{d} v(\tau, \xi) d \xi=\gamma(\tau)$, in which $v(\tau, \xi)$ indicates the pollutants concentration in $\mathrm{gr} / \mathrm{cm}$ (ratio of mass to length) at time $\tau_{0}$ and $\int_{c}^{d} v(\tau, \xi) d \xi$ indicates the pollutants amount in the interval $[c, d]$ at time $\tau$.

[^0]Email addresses: waleedalhayani@uomosul.edu.iq, waleedalhayani@yahoo.es (W. Al-Hayani), mahasin_thabet@uomosul.edu.iq (M. Th. Younis)

In the case of beginning data and nonlocal BCs, a nonlocal IBVP is the problem of finding a solution to a PDE. The nonlocal IBVPs with integral BCs can be used to describe a wide range of problems in conduction of heat [14], engineering with chemicals [20], thermo-elasticity [17], and physics of plasma [3]. The parabolic PDE with nonlocal BCs has been studied in $[4,16,21,22,26]$ and for hyperbolic PDEs [4, 23]. These topics were looked into, and proper existence and uniqueness theorems were established.

In the last three decades, semi-analytical approximation methods have emerged, such as HPM, homotopy analysis method (HAM), Adomian decomposition method (ADM), and variational iteration method (VIM), etc. to solve linear and nonlinear (algebraic, differential, partial differential, integral, etc.) equations. It has been shown that these methods yield a rapid convergence of the solutions series.

Ji-Huan He proposed the HPM in 1998. Many authors have relied on him to solve linear/non-linear ordinary differential equations (ODEs) and PDEs of integer and fractional order $[7,8,11-13,18,19]$. If the exact answer exists, the approach converges to it through repeated approximations.

Recently, Al-Hayani and Younis [2] have applied the HPM with green's function to solve the fuzzy system of boundary value problems. Ahmed et al. [1] have solved the nonlinear system of Volterra integral equations and applied the genetic algorithm to enhance the solutions by the HAM. Hamoud and Ghadle have used HAM for solving the first order fuzzy Volterra-Fredholm integro-differential equations [9] and fractional Volterra-Fredholm integro-differential equation of the second kind [10]. Fiza et al. [6] have applied the multistep optimal homotopy asymptotic method to some nonlinear KdV-equations. Younis and Al-Hayani [25] utilized the ADM to solve a fuzzy system of volterra integro-differential equations. Turkyilmazoglu [24] has proven the accelerating the convergence of ADM. Finally, Dawood et al. [5] have exercised VIM and MHPM to solve higher-order integro differential equations.

The principal goal of this study is to use the HPM to find approximate-exact solutions to solve nonlocal IBVPs for linear/non-linear parabolic and hyperbolic PDEs with initial and nonlocal BCs of integral type.

## 2. Applications of the HPM

The HPM will be used to solve nonlocal IBVPs for linear/non-linear variablecoefficient parabolic and hyperbolic PDEs in this section. There will be five instances shown.

### 2.1. Nonlocal IBVP for the linear/non-linear parabolic PDE

Let us consider the inhomogeneous linear/non-linear parabolic PDE

$$
\begin{equation*}
v_{\tau}-m(\tau, \xi) v_{\xi \xi}+n(\tau, \xi) v=h(\tau, \xi)+F(v), \quad c \leq \xi \leq d, \quad \tau \geq 0, \tag{1}
\end{equation*}
$$

subjecting to the IC

$$
\begin{equation*}
v(0, \xi)=\alpha(\xi), \tag{2}
\end{equation*}
$$

and the inhomogeneous nonlocal integral type BCs

$$
\begin{equation*}
\int_{c}^{d} \psi_{1}(\xi) v(\tau, \xi) d \xi=\gamma_{1}(\tau) \quad \text { and } \quad \int_{c}^{d} \psi_{2}(\xi) v(\tau, \xi) d \xi=\gamma_{2}(\tau), \tag{3}
\end{equation*}
$$

in which $\psi_{i}(\xi), \gamma_{i}(\tau), i=1,2$ and $\alpha(\xi)$ are specified as continuous functions.
Converting Equations (1)-(3) into local IBVP by using the method of introducing a function $w(\tau, \xi)$ so that

$$
\begin{equation*}
w(\tau, \xi)=\int_{c}^{\xi} \psi(\xi) v(\tau, \xi) d \xi \tag{4}
\end{equation*}
$$

in which $\psi(\xi)=\psi_{1}(\xi)+\psi_{2}(\xi)$. Thus, we have

$$
\begin{align*}
v(\tau, \xi)= & \frac{1}{\psi(\xi)} w_{\xi}(\tau, \xi), \quad \psi(\xi) \neq 0  \tag{5}\\
v_{\tau}(\tau, \xi)= & \frac{1}{\psi(\xi)} w_{\tau \xi}(\tau, \xi), \quad v_{\tau \tau}(\tau, \xi)=\frac{1}{\psi(\xi)} w_{\tau \tau \xi}(\tau, \xi)  \tag{6}\\
v_{\xi}(\tau, \xi)= & \frac{1}{\psi(\xi)} w_{\xi \xi}(\tau, \xi)+\left(\frac{1}{\psi(\xi)}\right)^{\prime} w_{\xi}(\tau, \xi)  \tag{7}\\
v_{\xi \xi}(\tau, \xi)= & \frac{1}{\psi(\xi)} w_{\xi \xi \xi}(\tau, \xi)+2\left(\frac{1}{\psi(\xi)}\right)^{\prime} w_{\xi \xi}(\tau, \xi) \\
& +\left(\frac{1}{\psi(\xi)}\right)^{\prime \prime} w_{\xi}(\tau, \xi) \tag{8}
\end{align*}
$$

Replacing Equations (5)-(8) into Equation (1) we conclude
Lemma 1. The nonlocal IBVP (1)-(3) may be reduced to a local IBVP of the form

$$
\left\{\begin{array}{l}
w_{\tau \xi}+r(\tau, \xi) w_{\xi}+s(\tau, \xi) w_{\xi \xi}-m(\tau, \xi) w_{\xi \xi \xi}=g(\tau, \xi)+N(w),  \tag{9}\\
w_{\xi}(0, \xi)=h_{1}(\xi), \quad w(\tau, c)=0, \quad w(\tau, d)=\gamma(\tau),
\end{array}\right.
$$

in which

$$
\begin{align*}
r(\tau, \xi) & =-m(\tau, \xi) \psi(\xi)\left(\frac{1}{\psi(\xi)}\right)^{\prime \prime}+n(\tau, \xi),  \tag{10}\\
s(\tau, \xi) & =-2 m(\tau, \xi) \psi(\xi)\left(\frac{1}{\psi(\xi)}\right)^{\prime}  \tag{11}\\
g(\tau, \xi) & =\psi(\xi) h(\tau, \xi)  \tag{12}\\
h_{1}(\xi) & =\psi(\xi) \alpha(\xi)  \tag{13}\\
\gamma(\tau) & =\gamma_{1}(\tau)+\gamma_{2}(\tau) . \tag{14}
\end{align*}
$$ and the non-linear term $N(w)=\psi(\xi) F\left(\frac{w_{\xi}}{\psi(\xi)}\right)$ is assumed to be an analytic function. This problem's solution will lead to the original problem's solution, in which $v(\tau, \xi)$ is provided by Eq (5). By the HPM [7, 8, 11-13, 18, 19], we write

$$
\begin{gather*}
w_{\tau \xi}-\left(v_{0}\right)_{\tau \xi}+p\left[\left(v_{0}\right)_{\tau \xi}+r(\tau, \xi) w_{\xi}+s(\tau, \xi) w_{\xi \xi}\right.  \tag{15}\\
\left.-m(\tau, \xi) w_{\xi \xi \xi}-g(\tau, \xi)-N(w)\right]=0,
\end{gather*}
$$

Define the solution $w(\tau, \xi)$ by an infinite series in the form

$$
\begin{equation*}
w(\tau, \xi)=\sum_{j=0}^{\infty} p^{j} w_{j}, \tag{16}
\end{equation*}
$$

and the non-linear term $N(w)$ can be decomposed as

$$
\begin{equation*}
N(w(\tau, \xi))=\sum_{j=0}^{\infty} p^{j} H_{j}(w), \tag{17}
\end{equation*}
$$

in which the $H_{j}$ are He's polynomials of $w_{0}, w_{1}, \ldots, w_{j}$ and are calculated by the definitional formula [8, 15]

$$
\begin{equation*}
H_{j}\left(w_{0}, w_{1}, \ldots, w_{j}\right)=\frac{1}{j!} \frac{\partial^{j}}{\partial p^{j}}\left[N\left(\sum_{i=0}^{\infty} p^{i} w_{i}\right)\right]_{p=0}, \quad j=0,1, \ldots . \tag{18}
\end{equation*}
$$

in which $p \in[0,1]$ is an embedding parameter. Replacing (16) and (17) into Equation (15), we get

$$
\begin{gather*}
\sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\tau \xi}-\left(v_{0}\right)_{\tau \xi}+p\left[\left(v_{0}\right)_{\tau \xi}+r(\tau, \xi) \sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\xi}+s(\tau, \xi) \sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\xi \xi}\right. \\
\left.-m(\tau, \xi) \sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\xi \xi \xi}-g(\tau, \xi)-\sum_{j=0}^{\infty} p^{j} H_{j}(w)\right]=0, \tag{19}
\end{gather*}
$$

and when we combine the terms in the same power of $p$, we get

$$
\begin{align*}
& p^{0}:\left\{\begin{array}{l}
\left(w_{0}\right)_{\tau \xi}-\left(v_{0}\right)_{\tau \xi}=0, \\
\left(w_{0}\right)_{\xi}(0, \xi)=h_{1}(\xi), \\
p^{2}(\tau, c)=0, \\
p_{0}(\tau, d)=\gamma(\tau),
\end{array}\right. \\
&:\left\{\begin{array}{l}
\left(w_{1}\right)_{\tau \xi}+\left(v_{0}\right)_{\tau \xi}+r(\tau, \xi)\left(w_{0}\right)_{\xi}+s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi} \\
-g(\tau, \xi)-H_{0}(w)=0, \\
\left(w_{1}\right)_{\xi}(0, \xi)=0, w_{1}(\tau, c)=0, \quad w_{1}(\tau, d)=0,
\end{array}\right.  \tag{20}\\
& p^{j}:\left\{\begin{array}{l}
\left(w_{j}\right)_{\tau \xi}+r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}-m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-H_{j-1}(w)=0, \\
\left(w_{j}\right)_{\xi}(0, \xi)=0, w_{j}(\tau, c)=0, \quad w_{j}(\tau, d)=0, \quad j \geq 2
\end{array}\right.
\end{align*}
$$

Solving the Equations (20) with choosing the initial approximation $v_{0}=\alpha(\xi)$. Applying the inverse linear operators $L_{c, \tau \xi}^{-1}(\cdot)=\int_{c}^{\xi} \int_{0}^{\tau}(\cdot) d \tau d \xi$ to both sides of Equations (20), we obtain

$$
\begin{align*}
w_{0}(\tau, \xi)= & \int_{c}^{\xi} h_{1}(\xi) d \xi+L_{c, \tau \xi}^{-1}\left(v_{0}\right)_{\tau \xi}, \\
w_{1}(\tau, \xi)= & L_{c, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}\right. \\
& \left.+g(\tau, \xi)+H_{0}(w)\right], \\
w_{j}(\tau, \xi)= & L_{c, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}\right. \\
& \left.-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right], \\
j \geq & 2 \tag{21}
\end{align*}
$$

Applying the inverse linear operator $L_{d, \tau \xi}^{-1}(\cdot)=\int_{\xi}^{d} \int_{0}^{\tau}(\cdot) d \tau d \xi$ to both sides of Equations (20), as previously, we get

$$
\begin{align*}
w_{0}(\tau, \xi)= & \gamma(\tau)-\int_{\xi}^{d} h_{1}(\xi) d \xi+L_{d, \tau \xi}^{-1}\left(v_{0}\right)_{\tau \xi}, \\
w_{1}(\tau, \xi)= & -L_{d, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}\right. \\
& \left.+g(\tau, \xi)+H_{0}(w)\right], \\
w_{j}(\tau, \xi)= & -L_{d, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}\right. \\
& \left.-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right], \\
j \geq & 2 \tag{22}
\end{align*}
$$

By combining the relationships in (21) and (22) and dividing by 2 , we arrive at the equalweight average as the solution

$$
\begin{aligned}
w_{0}(\tau, \xi)= & \frac{1}{2}\left[\int_{c}^{\xi} h_{1}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{d} h_{1}(\xi) d \xi\right]+\frac{1}{2}\left[L_{c, \tau \xi}^{-1}\left(v_{0}\right)_{\tau \xi}+L_{d, \tau \xi}^{-1}\left(v_{0}\right)_{\tau \xi}\right], \\
w_{1}(\tau, \xi)= & \frac{1}{2} L_{c, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}+g(\tau, \xi)+H_{0}(w)\right] \\
& -\frac{1}{2} L_{d, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}+g(\tau, \xi)+H_{0}(w)\right], \\
w_{j}(\tau, \xi)= & \frac{1}{2} L_{c, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right]
\end{aligned}
$$

$$
\begin{align*}
& -\frac{1}{2} L_{d, \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right] \\
j \geq & 2 \tag{23}
\end{align*}
$$

The best approximation for the solution is

$$
w(\tau, \xi)=\lim _{p \rightarrow 1} \sum_{j=0}^{\infty} p^{j} w_{j}=w_{0}+w_{1}+w_{2}+w_{3}+\cdots
$$

we may use Equation (5) to return to the original dependent variable $v(\tau, \xi)$ once the function $w(\tau, \xi)$ has been determined.

### 2.2. Nonlocal IBVP for the linear/non-linear hyperbolic PDE

We consider the inhomogeneous linear/non-linear hyperbolic PDE

$$
\begin{equation*}
v_{\tau \tau}-m(\tau, \xi) v_{\xi \xi}+n(\tau, \xi) v=h(\tau, \xi)+F(v), \quad c \leq \xi \leq d, \quad \tau \geq 0 \tag{24}
\end{equation*}
$$

subjecting to the ICs

$$
\begin{equation*}
v(0, \xi)=\alpha_{1}(\xi), \quad v_{\tau}(0, \xi)=\alpha_{2}(\xi) \tag{25}
\end{equation*}
$$

with the BCs (3). Replacing Equations (5)-(8) into Equation (24) we conclude
Lemma 2. The nonlocal IBVP (24) subjecting to (25) and (3) may be reduced to a local IBVP of the form

$$
\left\{\begin{array}{l}
w_{\tau \tau \xi}+r(\tau, \xi) w_{\xi}+s(\tau, \xi) w_{\xi \xi}-m(\tau, \xi) w_{\xi \xi \xi}=g(\tau, \xi)+N(w)  \tag{26}\\
w_{\xi}(0, \xi)=h_{2}(\xi), w_{\tau \xi}(0, \xi)=h_{3}(\xi), w(\tau, c)=0, w(\tau, d)=\gamma(\tau)
\end{array}\right.
$$

in which $h_{i}(\xi)=\psi(\xi) \alpha_{i}(\xi), i=2,3$.
This problem's solution will lead to the original problem's solution, in which $v(\tau, \xi)$ is provided by Eq (5). By the HPM, we write

$$
\begin{align*}
w_{\tau \tau \xi}-\left(v_{0}\right)_{\tau \tau \xi} & +p\left[\left(v_{0}\right)_{\tau \tau \xi}+r(\tau, \xi) w_{\xi}+s(\tau, \xi) w_{\xi \xi}\right.  \tag{27}\\
& \left.-m(\tau, \xi) w_{\xi \xi \xi}-g(\tau, \xi)-N(w)\right]=0
\end{align*}
$$

Replacing (16) and (17) into Equation (27), we get

$$
\begin{gather*}
\sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\tau \tau \xi}-\left(v_{0}\right)_{\tau \tau \xi}+p\left[\left(v_{0}\right)_{\tau \tau \xi}+r(\tau, \xi) \sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\xi}+s(\tau, \xi) \sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\xi \xi}\right.  \tag{28}\\
\left.-m(\tau, \xi) \sum_{j=0}^{\infty} p^{j}\left(w_{j}\right)_{\xi \xi \xi}-g(\tau, \xi)-\sum_{j=0}^{\infty} p^{j} H_{j}(w)\right]=0,
\end{gather*}
$$

and when we combine the terms in the same power of $p$, we get

$$
\begin{align*}
& p^{0}:\left\{\begin{array}{l}
\left(w_{0}\right)_{\tau \tau \xi}-\left(v_{0}\right)_{\tau \tau \xi}=0, \\
\left(w_{0}\right)_{\xi}(0, \xi)=h_{2}(\xi),\left(w_{0}\right)_{\tau \xi}(0, \xi)=h_{3}(\xi), w_{0}(\tau, c)=0, w_{0}(\tau, d)=\gamma(\tau),
\end{array}\right. \\
& p^{1}:\left\{\begin{array}{c}
\left(w_{1}\right)_{\tau \tau \xi}+\left(v_{0}\right)_{\xi \tau}+r(\tau, \xi)\left(w_{0}\right)_{\xi}+s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi} \\
-g(\tau, \xi)-H_{0}(w)=0, \\
\left(w_{1}\right)_{\xi}(0, \xi)=0,\left(w_{1}\right)_{\tau \xi}(0, \xi)=0, w_{1}(\tau, c)=0, w_{1}(\tau, d)=0,
\end{array}\right.  \tag{29}\\
& p^{j}:\left\{\begin{array}{l}
\left(w_{j}\right)_{\tau \tau \xi}+r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}-m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-H_{j-1}(w)=0, \\
\left(w_{j}\right)_{\xi}(0, \xi)=0,\left(w_{j}\right)_{\tau \xi}(0, \xi)=0, w_{j}(\tau, c)=0, w_{j}(\tau, d)=0, \quad j \geq 2
\end{array}\right.
\end{align*}
$$

Solving the Equations (29) with choosing the initial approximation $v_{0}=\alpha_{1}(\xi)+\tau \alpha_{2}(\xi)$. Applying the inverse linear operators $L_{c, \tau \tau \xi}^{-1}(\cdot)=\int_{c}^{\xi} \int_{0}^{\tau} \int_{0}^{\tau}(\cdot) d \tau d \xi$ to both sides of Equations (29), we obtain

$$
\begin{align*}
w_{0}(\tau, \xi)= & \int_{c}^{\xi} h_{2}(\xi) d \xi+\tau \int_{c}^{\xi} h_{3}(\xi) d \xi+L_{c, \tau \tau \xi}^{-1}\left(v_{0}\right)_{\tau \tau \xi}, \\
w_{1}(\tau, \xi)= & L_{c, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}\right] \\
& \left.+g(\tau, \xi)+H_{0}(w)\right], \\
w_{j}(\tau, \xi)= & L_{c, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}\right] \\
& \left.-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right], \\
j \geq & 2 \tag{30}
\end{align*}
$$

Applying the inverse linear operator $L_{d, \tau \tau \xi}^{-1}(\cdot)=\int_{\xi}^{d} \int_{0}^{\tau} \int_{0}^{\tau}(\cdot) d \tau d \xi$ to both sides of Equations (29), as previously, we get

$$
\begin{aligned}
w_{0}(\tau, \xi)= & \gamma(\tau)-\int_{\xi}^{d} h_{2}(\xi) d \xi-\tau \int_{\xi}^{d} h_{3}(\xi) d \xi+L_{d, \tau \tau \xi}^{-1}\left(v_{0}\right)_{\tau \tau \xi}, \\
w_{1}(\tau, \xi)= & -L_{d, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}\right. \\
& \left.+g(\tau, \xi)+H_{0}(w)\right], \\
w_{j}(\tau, \xi)= & -L_{d, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}\right. \\
& \left.-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right],
\end{aligned}
$$

$$
\begin{equation*}
j \geq 2 \tag{31}
\end{equation*}
$$

By combining the relationships in (30) and (31) and dividing by 2 , we arrive at the equalweight average as the solution

$$
\begin{align*}
w_{0}(\tau, \xi)= & \frac{1}{2}\left[\int_{c}^{\xi} h_{2}(\xi) d \xi+\tau \int_{c}^{\xi} h_{3}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{d} h_{2}(\xi) d \xi-\tau \int_{\xi}^{d} h_{3}(\xi) d \xi\right] \\
& +\frac{1}{2}\left[L_{c, \tau \tau \xi}^{-1}\left(v_{0}\right)_{\tau \tau \xi}+L_{d, \tau \tau \xi}^{-1}\left(v_{0}\right)_{\tau \tau \xi}\right], \\
w_{1}(\tau, \xi)= & \frac{1}{2} L_{c, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}+g(\tau, \xi)+H_{0}(w)\right] \\
& -\frac{1}{2} L_{d, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{0}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{0}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{0}\right)_{\xi}+g(\tau, \xi)+H_{0}(w)\right], \\
w_{j}(\tau, \xi)= & \frac{1}{2} L_{c, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right] \\
& -\frac{1}{2} L_{d, \tau \tau \xi}^{-1}\left[m(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi \xi}-s(\tau, \xi)\left(w_{j-1}\right)_{\xi \xi}-r(\tau, \xi)\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right], \\
j \geq & 2 \tag{32}
\end{align*}
$$

Similarly, once the function $w(\tau, \xi)$ has been established, we may utilize Equation (5) to go back to the initial dependant variable $v(\tau, \xi)$.

## 3. Problems

Problem 1. We first consider the linear nonlocal inhomogeneous IBVP [4]

$$
\left\{\begin{array}{l}
v_{\tau}-v_{\xi \xi}+v=0, \quad 0 \leq \xi \leq \pi, \quad \tau \geq 0  \tag{33}\\
v(0, \xi)=\sin (\xi) \\
\int_{0}^{\pi} \xi v(\tau, \xi) d \xi=\pi e^{-2 \tau} \\
\int_{0}^{\pi}(1-\xi) v(\tau, \xi) d \xi=(2-\pi) e^{-2 \tau}
\end{array}\right.
$$

in which $c=0, d=\pi, m(\tau, \xi)=1, n(\tau, \xi)=1, h(\tau, \xi)=0, \alpha(\xi)=\sin (\xi), \gamma(\tau)=$ $2 e^{-2 \tau}$ and $\psi(\xi)=1$. Replacing Equations (5)-(8) into Equation (33), we get a local inhomogeneous IBVP of the form

$$
w_{\tau \xi}+w_{\xi}-w_{\xi \xi \xi}=0, \quad w_{\xi}(0, \xi)=\sin (\xi), \quad w(\tau, 0)=0, \quad w(\tau, \pi)=2 e^{-2 \tau}
$$

in which $r(\tau, \xi)=1, s(\tau, \xi)=0, m(\tau, \xi)=1, g(\tau, \xi)=0$ and $h_{1}(\xi)=\sin (\xi)$. Following the algorithm (23), the iterations are
$w_{0}(\tau, \xi)=\frac{1}{2}\left[\int_{0}^{\xi} h_{1}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{\pi} h_{1}(\xi) d \xi\right]=-\cos (\xi)+e^{-2 \tau}$,

$$
\begin{aligned}
w_{1}(\tau, \xi) & =\frac{1}{2} L_{0, \tau \xi}^{-1}\left[\left(w_{0}\right)_{\xi \xi \xi}-\left(w_{0}\right)_{\xi}+g(\tau, \xi)\right]-\frac{1}{2} L_{\pi, \tau \xi}^{-1}\left[\left(w_{0}\right)_{\xi \xi \xi}-\left(w_{0}\right)_{\xi}+g(\tau, \xi)\right]=2 \tau \cos (\xi), \\
w_{j}(\tau, \xi) & =\frac{1}{2} L_{0, \tau \xi}^{-1}\left[\left(w_{j-1}\right)_{\xi \xi \xi}-\left(w_{j-1}\right)_{\xi}\right]-\frac{1}{2} L_{\pi, \tau \xi}^{-1}\left[\left(w_{j-1}\right)_{\xi \xi \xi}-\left(w_{j-1}\right)_{\xi}\right] \\
& =\frac{(-1)^{j-1}}{j!}(2 \tau)^{j} \cos (\xi), \quad j \geq 2 .
\end{aligned}
$$

Thus, the series form's approximate solution is

$$
w(\tau, \xi)=-\left(1-2 \tau+2 \tau^{2}-\frac{4}{3} \tau^{3}+\frac{2}{3} \tau^{4}-\frac{4}{15} \tau^{5}+\cdots\right) \cos (\xi)+e^{-2 \tau} .
$$

This series has been written in closed-form.

$$
w(\tau, \xi)=-e^{-2 \tau} \cos (\xi)+e^{-2 \tau}
$$

Using Equation (5) to return to the original dependent variable, we get

$$
v(\tau, \xi)=\frac{w_{\xi}(\tau, \xi)}{\psi(\xi)}=e^{-2 \tau} \sin (\xi)
$$

is the exact solution of the nonlocal IBVP (33) compatible with ADM.
Problem 2. Let us consider the linear nonlocal inhomogeneous IBVP [4]

$$
\left\{\begin{array}{l}
v_{\tau}-v_{\xi \xi}=\sin (\xi), \quad 0 \leq \xi \leq \pi, \quad \tau \geq 0  \tag{34}\\
v(0, \xi)=\cos (\xi) \\
\int_{0}^{\pi} \xi v(\tau, \xi) d \xi=-(2+\pi) e^{-\tau}+\pi \\
\int_{0}^{\pi}(k-\xi) v(\tau, \xi) d \xi=(2+\pi-2 k) e^{-\tau}+2 k-\pi
\end{array}\right.
$$

in which $c=0, d=\pi, m(\tau, \xi)=1, n(\tau, \xi)=0, h(\tau, \xi)=\sin (\xi), \alpha(\xi)=\cos (\xi)$, $\gamma(\tau)=2 k\left(1-e^{-\tau}\right)$ and $\psi(\xi)=k, k$ constant. Replacing Equations (5)-(8) into Equation (34), we get a local inhomogeneous IBVP of the form

$$
w_{\tau \xi}-w_{\xi \xi \xi}=k \sin (\xi), \quad w_{\xi}(0, \xi)=k \cos (\xi), \quad w(\tau, 0)=0, \quad w(\tau, \pi)=2 k\left(1-e^{-\tau}\right)
$$

in which $r(\tau, \xi)=0, s(\tau, \xi)=0, m(\tau, \xi)=1, g(\tau, \xi)=k \sin (\xi)$ and $h_{1}(\xi)=k \cos (\xi)$. Utilizing the algorithm (23), the iterations are

$$
w_{0}(\tau, \xi)=\frac{1}{2}\left[\int_{0}^{\xi} h_{1}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{\pi} h_{1}(\xi) d \xi\right]=k \sin (\xi)+k\left(1-e^{-\tau}\right)
$$

$$
w_{1}(\tau, \xi)=\frac{1}{2} L_{0, \tau \xi}^{-1}\left[\left(w_{0}\right)_{\xi \xi \xi}+g(\tau, \xi)\right]-\frac{1}{2} L_{\pi, \tau \xi}^{-1}\left[\left(w_{0}\right)_{\xi \xi \xi}+g(\tau, \xi)\right]=-k \tau(\sin (\xi)+\cos (\xi))
$$

$w_{j}(\tau, \xi)=\frac{1}{2} L_{0, \tau \xi}^{-1}\left[\left(w_{j-1}\right)_{\xi \xi \xi}\right]-\frac{1}{2} L_{\pi, \tau \xi}^{-1}\left[\left(w_{j-1}\right)_{\xi \xi \xi}\right]=\frac{(-1)^{j}}{j!} k \tau^{j}(\sin (\xi)+\cos (\xi)), \quad j \geq 2$.
Thus, the series form's approximate solution is

$$
w(\tau, \xi)=k\left(1-\tau+\frac{\tau^{2}}{2!}-\frac{\tau^{3}}{3!}+\cdots\right) \sin (\xi)-k\left(\tau-\frac{\tau^{2}}{2!}+\frac{\tau^{3}}{3!}+\cdots\right) \cos (\xi)+k\left(1-e^{-\tau}\right) .
$$

This series has been written in closed-form

$$
w(\tau, \xi)=k e^{-\tau} \sin (\xi)-k\left(1-e^{-\tau}\right) \cos (\xi)+k\left(1-e^{-\tau}\right) .
$$

Using Equation (5) to return to the original dependent variable, we get

$$
v(\tau, \xi)=\frac{w_{\xi}(\tau, \xi)}{\psi(\xi)}=e^{-\tau} \cos (\xi)+\left(1-e^{-\tau}\right) \sin (\xi)
$$

is the exact solution of the nonlocal IBVP (34) compatible with ADM.
Problem 3. We consider the linear nonlocal inhomogeneous IBVP [4]

$$
\left\{\begin{array}{l}
v_{\tau \tau}-v_{\xi \xi}=0, \quad 0 \leq \xi \leq 1, \quad \tau \geq 0  \tag{35}\\
v(0, \xi)=\xi^{2}, \quad v_{\tau}(0, \xi)=0 \\
\int_{0}^{1} v(\tau, \xi) d \xi=\frac{1}{3}+\tau^{2} \\
\int_{0}^{1} \xi v(\tau, \xi) d \xi=\frac{1}{4}+\frac{1}{2} \tau^{2}
\end{array}\right.
$$

in which $c=0, d=1, m(\tau, \xi)=1, n(\tau, \xi)=0, h(\tau, \xi)=0, \alpha_{1}(\xi)=\xi^{2}, \alpha_{2}(\xi)=0$, $\gamma(\tau)=\frac{7}{12}+\frac{3}{2} \tau^{2}$ and $\psi(\xi)=\xi+1$. Replacing Equations (5)-(8) into Equation (35), we get a local inhomogeneous IBVP of the form

$$
\left\{\begin{array}{l}
w_{\tau \tau \xi}-\frac{2}{(\xi+1)^{2}} w_{\xi}+\frac{2}{\xi+1} w_{\xi \xi}-w_{\xi \xi \xi}=0 \\
w_{\xi}(0, \xi)=\xi^{3}+\xi^{2}, \quad w_{\tau \xi}(0, \xi)=0 \\
w(\tau, 0)=0, \quad w(\tau, 1)=\frac{7}{12}+\frac{3}{2} \tau^{2},
\end{array}\right.
$$

in which $r(\tau, \xi)=\frac{-2}{(\xi+1)^{2}}, s(\tau, \xi)=\frac{2}{\xi+1}, m(\tau, \xi)=1, g(\tau, \xi)=0, h_{2}(\xi)=\xi^{3}+\xi^{2}$ and $h_{3}(\xi)=0$. Using the algorithm (32), the iterations are

$$
w_{0}(\tau, \xi)=\frac{1}{2}\left[\int_{0}^{\xi} h_{2}(\xi) d \xi+\tau \int_{0}^{\xi} h_{3}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{1} h_{2}(\xi) d \xi-\tau \int_{\xi}^{1} h_{3}(\xi) d \xi\right]
$$

$$
\begin{aligned}
= & \frac{1}{4} \xi^{4}+\frac{1}{3} \xi^{3}+\frac{3}{4} \tau^{2}, \\
w_{1}(\tau, \xi)= & \frac{1}{2} L_{0, \tau \tau \xi}^{-1}\left[\left(w_{0}\right)_{\xi \xi \xi}-\frac{2}{\xi+1}\left(w_{0}\right)_{\xi \xi}+\frac{2}{(\xi+1)^{2}}\left(w_{0}\right)_{\xi}+g(\tau, \xi)\right] \\
& -\frac{1}{2} L_{1, \tau \tau \xi}^{-1}\left[\left(w_{0}\right)_{\xi \xi \xi}-\frac{2}{\xi+1}\left(w_{0}\right)_{\xi \xi}+\frac{2}{(\xi+1)^{2}}\left(w_{0}\right)_{\xi}+g(\tau, \xi)\right] \\
= & \frac{1}{2} \tau^{2} \xi^{2}+\tau^{2} \xi-\frac{3}{4} \tau^{2}, \\
w_{j}(\tau, \xi)= & \frac{1}{2} L_{0, \tau \tau \xi}^{-1}\left[\left(w_{j-1}\right)_{\xi \xi \xi}-\frac{2}{\xi+1}\left(w_{j-1}\right)_{\xi \xi}+\frac{2}{(\xi+1)^{2}}\left(w_{j-1}\right)_{\xi}\right] \\
& -\frac{1}{2} L_{1, \tau \tau \xi}^{-1}\left[\left(w_{j-1}\right)_{\xi \xi \xi}-\frac{2}{\xi+1}\left(w_{j-1}\right)_{\xi \xi}+\frac{2}{(\xi+1)^{2}}\left(w_{j-1}\right)_{\xi}\right]=0, \quad j \geq 2
\end{aligned}
$$

Thus, the series form's approximate solution is

$$
w(\tau, \xi)=\frac{1}{4} \xi^{4}+\frac{1}{3} \xi^{3}+\frac{1}{2} \tau^{2} \xi^{2}+\tau^{2} \xi
$$

Using Equation (5) to return to the original dependent variable, we get

$$
v(\tau, \xi)=\frac{w_{\xi}(\tau, \xi)}{\psi(\xi)}=\xi^{2}+\tau^{2}
$$

is the exact solution of the nonlocal IBVP (35) compatible with ADM.

Problem 4. Consider the non-linear nonlocal inhomogeneous IBVP [4]

$$
\left\{\begin{array}{l}
v_{\tau \tau}-\xi v_{\xi \xi}=1-v^{2}, \quad 0 \leq \xi \leq 1, \quad \tau \geq 0  \tag{36}\\
v(0, \xi)=1, \quad v_{\tau}(0, \xi)=0 \\
\int_{0}^{1} v(\tau, \xi) d \xi=1, \quad \int_{0}^{1}(\xi-1) v(\tau, \xi) d \xi=-\frac{1}{2}
\end{array}\right.
$$

in which $c=0, d=1, m(\tau, \xi)=\xi, n(\tau, \xi)=0, h(\tau, \xi)=1, F(v)=-v^{2}, \alpha_{1}(\xi)=1$, $\alpha_{2}(\xi)=0, \gamma(\tau)=\frac{1}{2}$ and $\psi(\xi)=\xi$. Replacing Equations (5)-(8) into Equation (36), we get a local inhomogeneous IBVP of the form

$$
\left\{\begin{array}{l}
w_{\tau \tau \xi}-\frac{2}{\xi} w_{\xi}+2 w_{\xi \xi}-\xi w_{\xi \xi \xi}=\xi-\frac{1}{\xi}\left(w_{\xi}\right)^{2} \\
w_{\xi}(0, \xi)=\xi, \quad w_{\tau \xi}(0, \xi)=0 \\
w(\tau, 0)=0, \quad w(\tau, 1)=\frac{1}{2}
\end{array}\right.
$$

in which $r(\tau, \xi)=\frac{-2}{\xi}, s(\tau, \xi)=2, m(\tau, \xi)=\xi, g(\tau, \xi)=\xi, h_{2}(\xi)=\xi, h_{3}(\xi)=0$ and the non-linear term $N(w)=-\frac{1}{\xi}\left(w_{\xi}\right)^{2}$ is given by Equation (17). The corresponding He's polynomials by the formula Equation (18) are given by

$$
H_{j}(w)=-\frac{1}{\xi} \sum_{i=0}^{j}\left(w_{\xi}\right)_{j-i}\left(w_{\xi}\right)_{i}, \quad j \geq i, \quad j=0,1, \ldots
$$

due to the fact that the nonlinear component $N(w)$ exhibits quadratic nonlinearity in $w_{\xi}$. It should be noted that only the dependent variable $w$ and its derivatives are parametrized in $p$, whereas $\tau$ and $\xi$ are not. Following the algorithm (32), the iterations are

$$
\begin{aligned}
w_{0}(\tau, \xi)= & \frac{1}{2}\left[\int_{0}^{\xi} h_{2}(\xi) d \xi+\tau \int_{0}^{\xi} h_{3}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{1} h_{2}(\xi) d \xi-\tau \int_{\xi}^{1} h_{3}(\xi) d \xi\right]=\frac{1}{2} \xi^{2}, \\
w_{1}(\tau, \xi)= & \frac{1}{2} L_{0, \tau \tau \xi}^{-1}\left[\xi\left(w_{0}\right)_{\xi \xi \xi}-2\left(w_{0}\right)_{\xi \xi}+\frac{2}{\xi}\left(w_{0}\right)_{\xi}+g(\tau, \xi)-H_{0}(w)\right] \\
& -\frac{1}{2} L_{1, \tau \tau \xi}^{-1}\left[\xi\left(w_{0}\right)_{\xi \xi \xi}-2\left(w_{0}\right)_{\xi \xi}+\frac{2}{\xi}\left(w_{0}\right)_{\xi}+g(\tau, \xi)-H_{0}(w)\right]=0, \\
w_{j}(\tau, \xi)= & \frac{1}{2} L_{0, \tau \tau \xi}^{-1}\left[\xi\left(w_{j-1}\right)_{\xi \xi \xi \xi}-2\left(w_{j-1}\right)_{\xi \xi}+\frac{2}{\xi}\left(w_{j-1}\right)_{\xi}-H_{j-1}(w)\right] \\
& -\frac{1}{2} L_{1, \tau \tau \xi}^{-1}\left[\xi\left(w_{j-1}\right)_{\xi \xi \xi}-2\left(w_{j-1}\right)_{\xi \xi}+\frac{2}{\xi}\left(w_{j-1}\right)_{\xi}-H_{j-1}(w)\right]=0, \quad j \geq 2 .
\end{aligned}
$$

Thus, the series form's approximate solution is

$$
w(\tau, \xi)=\frac{1}{2} \xi^{2},
$$

Using Equation (5) to return to the original dependent variable, we get

$$
v(\tau, \xi)=\frac{w_{\xi}(\tau, \xi)}{\psi(\xi)}=1
$$

is the exact solution of the nonlocal IBVP (36) compatible with ADM.
Problem 5. Finally, we consider the non-linear nonlocal inhomogeneous IBVP [4]

$$
\left\{\begin{array}{l}
v_{\tau}-\xi v_{\xi \xi}=-v v_{\xi}, \quad 0 \leq \xi \leq 1, \quad \tau \geq 0  \tag{37}\\
v(0, \xi)=\xi, \\
\int_{0}^{1} v(\tau, \xi) d \xi=\frac{1}{2(1+\tau)}, \\
\int_{0}^{1}\left(e^{\xi}-1\right) v(\tau, \xi) d \xi=\frac{1}{2(1+\tau)},
\end{array}\right.
$$

in which $c=0, d=\pi, m(\tau, \xi)=\xi, n(\tau, \xi)=0, h(\tau, \xi)=0, F(v)=-v v_{\xi}, \alpha(\xi)=\xi$, $\gamma(\tau)=\frac{1}{1+\tau}$ and $\psi(\xi)=e^{\xi}$. Replacing Equations (5)-(8) into Equation (37), we get a local inhomogeneous IBVP of the form

$$
\left\{\begin{array}{l}
w_{\tau \xi}-\xi w_{\xi}+2 \xi w_{\xi \xi}-\xi w_{\xi \xi \xi}=e^{-\xi}\left[\left(w_{\xi}\right)^{2}-w_{\xi} w_{\xi \xi}\right] \\
w_{\xi}(0, \xi)=\xi e^{\xi}, \quad w(\tau, 0)=0, \quad w(\tau, 1)=\frac{1}{1+\tau}
\end{array}\right.
$$

in which $r(\tau, \xi)=-\xi, s(\tau, \xi)=2 \xi, m(\tau, \xi)=\xi, g(\tau, \xi)=0, h_{1}(\xi)=\xi e^{\xi}$ and the nonlinear term $N(w)=e^{-\xi}\left[\left(w_{\xi}\right)^{2}-w_{\xi} w_{\xi \xi}\right]$ is given by Equation (17). The corresponding He's polynomials by the formula Equation (18) are given by

$$
H_{j}(w)=e^{-\xi}\left[\sum_{i=0}^{j}\left(w_{\xi}\right)_{j-i}\left(w_{\xi}\right)_{i}-\sum_{i=0}^{j}\left(w_{\xi}\right)_{j-i}\left(w_{\xi \xi}\right)_{i}\right], \quad j \geq i, \quad j=0,1, \ldots
$$

because the non-linear term $N(w)$ is the difference between a quadratic nonlinearity in $w_{\xi}$ and a product nonlinearity in $w_{\xi}$ and $w_{\xi \xi}$. Utilizing the algorithm (23), the iterations are

$$
\begin{aligned}
w_{0}(\tau, \xi)= & \frac{1}{2}\left[\int_{0}^{\xi} h_{1}(\xi) d \xi+\gamma(\tau)-\int_{\xi}^{1} h_{1}(\xi) d \xi\right]=\frac{1}{2}+e^{\xi}(\xi-1)+\frac{1}{2(1+\tau)}, \\
w_{1}(\tau, \xi)= & \frac{1}{2} L_{0, \tau \xi}^{-1}\left[\xi\left(w_{0}\right)_{\xi \xi \xi}-2 \xi\left(w_{0}\right)_{\xi \xi}+\xi\left(w_{0}\right)_{\xi}+g(\tau, \xi)+H_{0}(w)\right] \\
& -\frac{1}{2} L_{1, \tau \xi}^{-1}\left[\xi\left(w_{0}\right)_{\xi \xi \xi}-2 \xi\left(w_{0}\right)_{\xi \xi}+\xi\left(w_{0}\right)_{\xi}+g(\tau, \xi)+H_{0}(w)\right] \\
= & -\frac{1}{2} \tau-\tau e^{\xi}(\xi-1), \\
w_{j}(\tau, \xi)= & \frac{1}{2} L_{0, \tau \xi}^{-1}\left[\xi\left(w_{j-1}\right)_{\xi \xi \xi}-2 \xi\left(w_{j-1}\right)_{\xi \xi}+\xi\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right] \\
& -\frac{1}{2} L_{1, \tau \xi}^{-1}\left[\xi\left(w_{j-1}\right)_{\xi \xi \xi}-2 \xi\left(w_{j-1}\right)_{\xi \xi}+\xi\left(w_{j-1}\right)_{\xi}+H_{j-1}(w)\right] \\
= & (-1)^{j}\left[\frac{1}{2} \tau^{j}+\tau^{j} e^{\xi}(\xi-1)\right], \quad j \geq 2 .
\end{aligned}
$$

Thus, the series form's approximate solution is

$$
w(\tau, \xi)=\frac{1}{2}\left(1-\tau+\tau^{2}-\tau^{3}+\cdots\right)+\left(1-\tau+\tau^{2}-\tau^{3}+\cdots\right) e^{\xi}(\xi-1)+\frac{1}{2(1+\tau)} .
$$

This series has been written in closed-form

$$
w(\tau, \xi)=\frac{1}{1+\tau} \xi^{\xi}(\xi-1)+\frac{1}{1+\tau}, \quad|\tau|<1 .
$$

Using Equation (5) to return to the original dependent variable, we get

$$
v(\tau, \xi)=\frac{w_{\xi}(\tau, \xi)}{\psi(\xi)}=\frac{\xi}{1+\tau}, \quad|\tau|<1
$$

is the exact solution of the nonlocal IBVP (37) compatible with ADM.

## 4. Conclusion

To obtain approximate-exact solutions, the HPM was effectively employed to resolve nonlocal IBVPs for linear/non-linear parabolic and hyperbolic PDEs subjecting to initial and nonlocal BCs of integral type. The presented nonlocal integral IBVPs for linear/nonlinear parabolic and hyperbolic PDEs have been turned into local Dirichlet IBVPs. The HPM has proven to be useful in dealing with these models, broadening its applicability. The method was put to the test by using it on five different Problems. The results obtained in each Problem show that this strategy is reliable and efficient for handling this type of nonlocal IBVPs.

## References

[1] Rasha F Ahmed, Waleed Mohammed Al-Hayani, and Abbas Y Al-Bayati. The homotopy analysis method to solve the nonlinear system of volterra integral equations and applying the genetic algorithm to enhance the solutions. European Journal of Pure and Applied Mathematics, 16(2):864-892, 2023.
[2] Waleed Mohammed Al-Hayani and Mahasin Thabet Younis. Solving fuzzy system of boundary value problems by homotopy perturbation method with green's function. European Journal of Pure and Applied Mathematics, 16(2):1236-1259, 2023.
[3] Gérard Belmont, Laurence Rezeau, Caterina Riconda, and Arnaud Zaslavsky. Introduction to Plasma Physics. Elsevier, 2019.
[4] Lazhar Bougoffa and Randolph C Rach. Solving nonlocal initial-boundary value problems for linear and nonlinear parabolic and hyperbolic partial differential equations by the adomian decomposition method. Applied Mathematics and Computation, 225:50-61, 2013.
[5] Lafta Dawood, Abdulrahman Sharif, and Ahmed Hamoud. Solving higher-order integro differential equations by vim and mhpm. International Journal of Applied Mathematics, 33(2):253, 2020.
[6] Mehreen Fiza, Hakeem Ullah, Saeed Islam, Qayum Shah, Farkhanda Inayat Chohan, and Mustafa Bin Mamat. Modifications of the multistep optimal homotopy asymptotic method to some nonlinear kdv-equations. European Journal of Pure and Applied Mathematics, 11(2):537-552, 2018.
[7] DD Ganji and A Sadighi. Application of he's homotopy-perturbation method to nonlinear coupled systems of reaction-diffusion equations. International Journal of Nonlinear Sciences and Numerical Simulation, 7(4):411-418, 2006.
[8] Asghar Ghorbani. Beyond adomian polynomials: he polynomials. Chaos, Solitons $\mathcal{B}$ Fractals, 39(3):1486-1492, 2009.
[9] Ahmed A Hamoud and K Ghadle. Homotopy analysis method for the first order fuzzy volterra-fredholm integro-differential equations. Indonesian Journal of Electrical Engineering and Computer Science, 11(3):857-867, 2018.
[10] Ahmen Hamoud and Kirtiwant Ghadle. Usage of the homotopy analysis method for solving fractional volterra-fredholm integro-differential equation of the second kind. Tamkang Journal of Mathematics, 49(4):301-315, 2018.
[11] Ji-Huan He. Homotopy perturbation technique. Computer methods in applied mechanics and engineering, 178(3-4):257-262, 1999.
[12] Ji-Huan He. A coupling method of a homotopy technique and a perturbation technique for non-linear problems. International journal of non-linear mechanics, 35(1):37-43, 2000.
[13] Ji-Huan He. Addendum: New interpretation of homotopy perturbation method. International journal of modern physics B, 20(18):2561-2568, 2006.
[14] Sadık Kakaç, Yaman Yener, and Carolina P Naveira-Cotta. Heat conduction. CRC press, 2018.
[15] S Tauseef Mohyud-Din, Muhammad Aslam Noor, and Khalida Inayat Noor. Traveling wave solutions of seventh-order generalized kdv equations using he's polynomials. International Journal of Nonlinear Sciences and Numerical Simulation, 10(2):227234, 2009.
[16] Lihua Mu and Hong Du. The solution of a parabolic differential equation with nonlocal boundary conditions in the reproducing kernel space. Applied mathematics and computation, 202(2):708-714, 2008.
[17] Witold Nowacki. Thermoelasticity. Elsevier Science, 2013.
[18] Turgut Öziş and Ahmet Yıldırım. Traveling wave solution of korteweg-de vries equation using he's homotopy perturbation method. International Journal of Nonlinear Sciences and Numerical Simulation, 8(2):239-242, 2007.
[19] M Rafei and DD Ganji. Explicit solutions of helmholtz equation and fifth-order kdv equation using homotopy perturbation method. International Journal of Nonlinear Sciences and Numerical Simulation, 7(3):321-328, 2006.
[20] M Tadi and Miloje Radenkovic. A numerical method for 1-d parabolic equation with nonlocal boundary conditions. International Journal of Computational Mathematics, 2014, 2014.
[21] E Tohidi and A Kılıçman. An efficient spectral approximation for solving several types of parabolic pdes with nonlocal boundary conditions. Mathematical Problems in Engineering, 2014, 2014.
[22] M Turkyilmazoglu. Parabolic partial differential equations with nonlocal initial and boundary values. International Journal of Computational Methods, 12(05):1550024, 2015.
[23] Mustafa Turkyilmazoglu. Hyperbolic partial differential equations with nonlocal mixed boundary values and their analytic approximate solutions. International Journal of Computational Methods, 15(02):1850003, 2018.
[24] Mustafa Turkyilmazoglu. Accelerating the convergence of adomian decomposition method (adm). Journal of Computational Science, 31:54-59, 2019.
[25] Mahasin Thabet Younis and Waleed Mohammed Al-Hayani. Solving fuzzy system of volterra integro-differential equations by using adomian decomposition method. European Journal of Pure and Applied Mathematics, 15(1):290-313, 2022.
[26] Reza Zolfaghari and Abdollah Shidfar. Solving a parabolic pde with nonlocal boundary conditions using the sinc method. Numerical Algorithms, 62:411-427, 2013.


[^0]:    *Corresponding author.
    DOI: https://doi.org/10.29020/nybg.ejpam.v16i3.4794

